Differential geometry in mathlib: present and future

Michael B. Rothgang (he/him)

Formalised mathematics group Universität Bonn



Formalised mathematics seminar July 16, 2025

Slides at https://www.math.uni-bonn.de/people/rothgang/

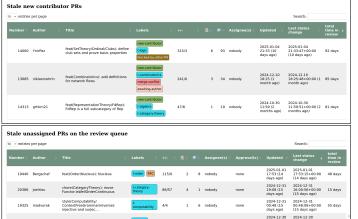


Before we begin...let me introduce myself

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The mathlib queueboard





The queueboard: why?

Mathlib has a review bottleneck; need

- more reviewer bandwith
- discoverability: are there PRs I can review?
- assignment of responsibility one designated reviewer per PR
- triage and tracking: make sure no PR is left behind

Mathlib needs editorial tooling

The queueboard

July 2024: Johan Commelin created a prototype

Spring 2025: 5000 lines of code, $\approx 90\%$ by R.

o v entries per page									Search:		
Number +	Author	Title	Labels	+/-	÷ 🖻 ÷	9 ÷	Assignee(s) +	Updated †	Last status change	total time in + review	
14060	YnirPaz	feat(SetTheory/Ordinal/Clubs): define club sets and prove basic properties	new-contributor t-lagic blocked-by-other-PR	315/3		5 93	nobody	2025-01-04 21:33 (10 days ago)	2025-01-04 21:33:47+00:00 (10 days ago)	92 days	
13685	niklasmohrin	feat(Combinatorics): add definitions for network flows	t-combinatorics merge-conflict awaiting-author	241/0		3 34	nobody	2024-12-10 18:25 (1 month ago)	2024-12-10 18:25:48+00:00 (1 month ago)	85 days	
14313	grhkm21	feat(RepresentationTheory/FdRep): FdRep is a full subcategory of Rep	new-contributor t-algebra t-category-theory	47/8		L 19	nobody	2024-10-30 11:59 (2 months ago)	2024-10-30 11:59:51+00:00 (2 months ago)	81 days	

The queueboard can help you too!

My wish: funding for somebody to extend and maintain it

The moral of the story

- Ask not what mathlib can do for you, ask what you can do for mathlib.
- Open source is great, allows for serendipity
- Maintaining software sustainably needs funding.

Outline of today's talk

- Prologue
- Current state of differential geometry
- Challenges in formalising differential geometry
- Case study: formalising bordism theory
 - What is bordism theory?
 - Motivation
 - Existence of exotic spheres
 - Homology theories
 - Formalisation overview
 - Existing work and new contribution
 - Formalisation design decisions
 - Outlook
 - Formalising smooth embeddings and submanifolds

Overview: differential geometry in mathlib

- general theory of smooth manifolds: allows infinite-dimension, boundaries and corners, different fields (e.g. \mathbb{R} , \mathbb{C} , p-adics)
- smooth maps, (continuous) differentiability
- (manifold) Fréchet derivative, chain rule
- products and disjoint unions of manifolds
- classification of 0-dimensional manifolds
- diffeomorphisms, local diffeomorphisms

Overview of differential geometry (cont.)

- (topological and smooth) vector bundles
- basic constructions: trivial bundle, direct sum, product bundle, hom bundle, (co)tangent bundle
- (continuous) differentiability of sections, smooth bundle maps
- Lie bracket of vector fields; Lie groups and their Lie algebra
- smooth bundle metrics; Riemannian manifolds (very basic)
- examples: \mathbb{R}^n , half-space, quadrants; intervals unit sphere; units in Lie groups
- existence of integral curves and local flows

What's missing?

- special maps: immersions, embeddings, submersions
- smooth submanifolds; sub-bundles
- quotients of manifolds; gluing
- implicit and inverse function theorems
- constant rank theorem; regular value theorem
- existence of a Riemannian metric
- differential topology: Sard's theorem
- classification of 1-manifolds and 2-manifolds
- smooth fibre bundles
- some basic computations, e.g. differential of projection $M \times N \to M$ or inclusion $M \to M \times N$ (not hard, but somebody needs to do it)

Some recent developments

- (Gouëzel) refactoring: unified analytic and C^n manifolds
- (Gouëzel) Lie bracket of vector fields: over any field (given enough smoothness; analytic in general case)
- (Yin) local flow of vector field is Lipschitz in the initial conditions
- (Yin) awaiting review: solutions of Cⁿ vector fields are Cⁿ in time existence of local flows on manifolds existence of global flows on compact manifolds
- (Gouëzel, Macbeth, ...) Riemannian manifolds

This month: Riemannian geometry (Massot–R.)

- lots of additional API lemmas about (continuous) differentiability
- local frames, Gram-Schmidt for vector bundles, orthonormal frames
- covariant derivatives (+local version)
- general tensoriality criterion
- classification of connections on the trivial bundle
- torsion of connections
- Levi-Civita connection: definition; existence and uniqueness
- Ehresmann connections (local story complete), pullback connection
- geodesic flow, exponential map

over 6000 lines of code; much of it awaiting review

In the making/in progress

- smooth immersions and embeddings
- submanifolds
- unoriented bordism groups
- (Hamadani–R.) oriented manifolds
- inverse function theorem help welcome
- (Kudryshov–R.) Moreira's version of Morse–Sard's theorem
- (Eltschig) orbifolds, diffeological spaces reviews welcome
- (Kudryashov–Macbeth–Lindauer) differential forms help wanted
- (Steinitz) principal fibre bundles

Outlook: three geodesics project

Initiated by Pietro Monticone (U Trento)

Goal: Lyusternik-Schnirelman theorem (1929'; Grayson '89)

Let (M,g) be a Riemannian manifold homeomorphic to \mathbb{S}^2 . Then M admits at least 3 simple closed geodesics.

Reference: Guillarmou–Mazzucchelli, *An introduction to Geometric Inverse Problems*

Medium to long-term project; lots of missing prerequisites.

High-level challenges

boilerplate: typeclasses

"let E be a smooth vector bundle over a smooth manifold M"

```
variable (F : Type*) [NormedAddCommGroup F] [NormedSpace k F]

(E : M → Type*) [TopologicalSpace (TotalSpace F E)]

[∀ x, AddCommGroup (E x)] [∀ x, Module k (E x)] [∀ x : M, TopologicalSpace (E x)]

[FiberBundle F E] [VectorBundle k F E] [ContMDiffVectorBundle n F E I]
```

② verbosity: "let $s: M \to E$ be a C^n section at x"

```
variable \{s : (x : M) \rightarrow V x\} \{x : M\}
\{hs : ContMDiffAt I (I.prod <math>\mathcal{J}(k, F)) \ n \ (fun x \mapsto TotalSpace.mk' F x \ (s x)) x\}
```

invisible mathematics (cf. Andrej Bauer) use subtypes, or junk value pattern: lots of trivial proofs "this point lies in this open set"

High-level challenges

- Can we find better abstractions? ContinuousWithinAt, ContMDiffWithinAt are a good abstraction, but very low-level
- Setter abstractions: can we abstract "this is just a local argument"? Make a tactic for this?
- API consistency vs. combinatorial explosion
 - often 4 variants of each lemma ContMDiff{,On,At,WithinAt}
 - mirror for MDifferentiable*, ContDiff*, Differentiable* (and sometimes Continuous*) \Rightarrow 20 versions
 - applied vs non-applied: contMDiffAt_fun_smul vs contMDiffAt_smul ⇒ 40 versions
 - real-life example: one PR (50 lines) became 5 (250 lines)
 - real-life example: 800 lines of our branch is copy-pasting code for ContMDiff to MDifferentiable

What can we do?

typeclasses: wait for Kyle Miller

write custom elaborators to reduce the verbosity

- auto-convert section into dependent function
 T% s means fun x => TotalSpace.mk' F x (s x)
- infer model with corners:
 CMDiffAt n f x means ContMDiffAt I J n f x
- prototypes, but already really useful
- extensible. optional: if they don't work, just write code as before!
- (virtually) syntactic/use the local context, no TC inference, unification or defeq checking

example: "X is a C^n vector field at x" becomes (hX: CMDiffAt (T% X) x)

What can we do (cont.)?

Use tactics to auto-generate and keep APIs in sync

idea: to_mdifferentiable attribute

- replace ContMDiff* (hypotheses and goals) by the analogous MDifferentiable statement
- new name: straightforward replacement
- proofs: just obvious translation; if it fails, indicates missing API
- implementation analogous to to_additive

```
idea: to_applied attribute
given a lemma, automatically generate the applied form (e.g.
contMDiff_smul to contMDiff_fun_smul)
```

help welcome (implementing or mentoring!)



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 - Formalising smooth embeddings and submanifolds



Before we begin: some timeline

- July 2024: PhD thesis submitted, learned about bordism theory
- August 2024: first formalisation attempt, failed badly
- January 2025: better definition, made great progress
- March 2025: mostly done
- March/April: need smooth embeddings to be mathlib-ready
- April 2025: define smooth embeddings and submanifolds (in progress)

Prologue

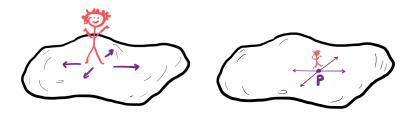
What is bordism theory? A non-answer

The study of smooth manifolds up to bordism

What is a manifold?



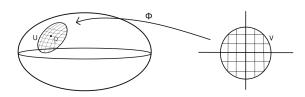
What is a manifold?



surface of a potato is a manifold: locally looks like a disk

Smooth manifolds

- topological **manifold**: second countable Hausdorff topological space M locally homeomorphic to open ball in \mathbb{R}^n
- every $p \in M$ has a coordinate chart: $p \in U \subset M$ open, homeomorphism $\phi \colon V \to U$ for $V \subset \mathbb{R}^n$ open ball
- **smooth manifold**: all coordinate transformations from overlapping charts are smooth



Examples of smooth manifolds

- empty set (of any dimension)
- 0-dimensional: isolated points
- 1-dimensional: \mathbb{R} , \mathbb{S}^1
- *n*-dimensional: open disc $\mathbb{D} \subset \mathbb{R}^n$
- n=2: \mathbb{R}^2 , \mathbb{S}^2 , \mathbb{T}^2 , Σ_g for $g\geq 1$



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- *n*-dimensional: open disc $\mathbb{D} \subset \mathbb{R}^n$
- n=2: \mathbb{R}^2 , \mathbb{S}^2 , \mathbb{T}^2 , Σ_g for $g\geq 1$



- $n \ge 3$: complicated; classification for $n \ge 4$ impossible
- not a manifold: letter "X"

Smooth manifolds with boundary

- interior points locally look like (open ball in) \mathbb{R}^n , boundary points look like (open ball in) upper half of \mathbb{R}^n
- closed manifold: compact and without boundary
- manifold with boundary and corners: details omitted
- examples: \mathbb{S}^2 is closed; $\overline{\mathbb{D}}\subset\mathbb{R}^2$ has boundary; $[0,1]^2\subset\mathbb{R}^2$ has corners

Fact

The boundary ∂M of a smooth n+1-dimensional manifold M is a smooth n-manifold.

Question

Is every closed smooth n-dimensional manifold the boundary of a smooth n + 1-dimensional manifold?



What is bordism theory?

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Is every closed smooth n-dimensional manifold M the boundary of a smooth n + 1-dimensional manifold?

Answer. Yes, for stupid reasons: $M = \partial([0, \infty) \times M)$.

What is bordism theory?

Question

Is every closed smooth n-dimensional manifold M the boundary of a smooth n + 1-dimensional manifold?

Answer. Yes, for stupid reasons: $M = \partial([0, \infty) \times M)$.

Better question

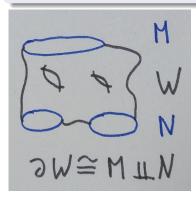
Is every closed smooth n-dimensional manifold M the boundary of a compact smooth n + 1-dimensional manifold?

Answer. No, e.g. $M = \mathbb{CP}^2$ is not (by Poincaré duality).

What is bordism theory?

Definition

A **smooth bordism** between smooth *n*-manifolds M and N is a compact n+1-dimensional manifold W such that $\partial W = M \sqcup N$.



We call *M* and *N* **bordant** if there exists a smooth bordism between them.

Fact

Being bordant is an equivalence relation.

The bordism groups

Definition

The *n*-th unoriented **bordism group** is

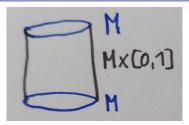
$$\Omega_n^O := \{ \text{closed smooth } n\text{-manifolds} \} / \text{bordism.}$$

 $\Omega^O_*:=\oplus_{n\geq 0}\Omega^O_n$ is called the unoriented **bordism ring**. Binary operations pass to bordism classes: disjoint union resp. product of manifolds.

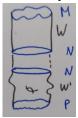
Theorem

Each Ω_n^O is an abelian group; Ω^O is a (graded commutative) ring.

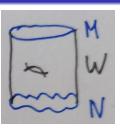
Some proofs by picture



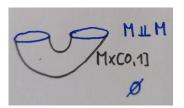
Reflexivity: the trivial bordism



Transitivity: glue bordisms along their common boundary



Symmetry: turn upside down



Every unoriented bordism class has order two.

Why study bordism theory?

- it's beautiful
- great test for differential geometry in mathlib
- exotic spheres and the Hirzebruch signature theorem
- defines an (extraordinary) homology theory

Motivation: existence of exotic spheres

Question

Are there topological manifolds without a smooth structure?

- Low dimensions: no, e.g. by explicit classification
- Dimension 4k: yes!

Theorem (Milnor '56)

There exists a smooth manifold S which is homeomorphic. but not diffeomorphic to \mathbb{S}^7 .

A smooth manifold M has an **intersection form** with **signature** $\sigma(M) \in \mathbb{Z}$.

Theorem (Hirzebruch signature theorem for 8-manifolds)

Each closed oriented smooth 8-manifold M satisfies

$$\sigma(M) = \frac{1}{45} \langle 7p_2(M) - p_1(M) \cup p_1(M), [M] \rangle.$$

Existence of exotic spheres: outline of proof

Theorem (Milnor '56)

There exists a smooth manifold S which is homeomorphic, but not diffeomorphic to \mathbb{S}^7 .

- ① Clever construction ("plumbing of spheres") of a smooth 8-manifold X with simply connected boundary $Y = \partial X$ such that $\sigma(X) = 8$, $p_1(X) = p_2(X) = 0$ and $H_2(Y) = H_3(Y) = 0$
- ② Compute: Y homotopy equivalent to $\mathbb{S}^7 \stackrel{\text{Smale}}{\Rightarrow} Y$ homeomorphic to \mathbb{S}^7
- ③ If Y were diffeomorphic to \mathbb{S}^7 , consider $M := X \cup_{\mathbb{S}^7} \mathbb{D}^8$. Compute $\sigma(M) = 8$ and $p_1(M) = 0$, then Hirzebruch implies

$$45 \,\sigma(M) = 45 \cdot 8 = 7 \langle p_1(M), [M] \rangle \in 7\mathbb{Z},$$

contradiction!



Ingredients for the Hirzebruch signature theorem

- The signature defines a ring homomorphism $\Omega_*^{SO} \to \mathbb{Z}, [M] \mapsto \sigma(M)$.
- $\Omega_*^{SO} \otimes \mathbb{Q}$ is (graded ring) isomorphic to $\mathbb{Q}[x_4, x_8, \dots]$, where each generator x_{4k} is represented by \mathbb{CP}^{2k}
- Computation: $\sigma(\mathbb{CP}^{2n}) = 1$ for all n
- Corollary: any ring homomorphism $\Psi\colon \Omega^{SO}_* \to \mathbb{Q}$ satisfying $\Psi([\mathbb{CP}^{2n}]) = 1$ for all n satisfies $\Psi([M]) = \sigma(M)$ for every closed oriented smooth manifold M
- Algebraic trick ("L-genus") to deduce the theorem

Upshot: the existence of exotic spheres requires bordism theory

Motivation: homology theories

Question

When are two topological spaces "the same" (homeomorphic)? How can we prove two spaces are different?

Algebraic invariants: different values means spaces are non-homeomorphic Common algebraic invariants

- homotopy groups: really hard to compute
- (singular, simplicial, cellular, Morse) homology groups: $(X,A)\mapsto \text{abelian groups }\{H_n(X,A)\}_{n\in\mathbb{N}}$

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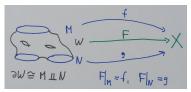
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- homotopy groups: really hard to compute
- (singular, simplicial, cellular, Morse) homology groups: $(X,A) \mapsto \text{abelian groups } \{H_n(X,A)\}_{n \in \mathbb{N}}$
- Eilenberg-Steenrod axioms characterise homology theories
- Singular homology: widely used, but proving the axioms is painful
- Bordism theory: proving the axioms is really easy

Dream goal

Bordism theory as first proven homology theory in mathlib

Bordism theory as a homology theory



Fix a topological space X. A **singular** n-**manifold** on X is a pair

A **singular** *n*-manifold on X is a pair (M, f) of a smooth closed *n*-manifold M and a continuous map $f: M \to X$.

A **bordism** between singular *n*-manifolds (M, f) and (N, g) is a compact n+1-manifold W with a continuous map $F: W \to X$ such that $\partial W \cong M \sqcup N$, $F|_M = f$ and $F|_N = g$.

Definition

The *n*-th unoriented **bordism group** of X is $\Omega_n^O(X) := \{\text{singular } n\text{-manifolds on } X\}/\text{bordism}.$

Example. For $X = \{*\}$, we recover the bordism groups Ω_n^O .



Existing work and new contribution

- Building on mathlib's differential geometry library
- Everything in a branch of mathlib/aiming for mathlib
- Lots of ground-work already existed
 - general theory of smooth manifolds
 - interval [a, b] (for a < b) is a manifold; products of manifolds
 - disjoint unions of top. spaces

New contributions to mathlib: pre-requisites

- discrete spaces are 0-dimensional manifolds (and conversely)
- disjoint union of manifolds
- interior and boundary of a manifold
- boundary of a disjoint union, product; $\partial[a,b] = \{a,b\}$
- disjoint union of two embeddings is an embedding (with Aaron Liu)
- new notion "this manifold has smooth boundary", basic instances

New contributions to mathlib (cont.)

- singular n-manifolds and basic constructions
- unoriented bordisms and bordism classes
- bordism relation is an equivalence relation: done except transitivity
- (absolute) bordism groups; proof of abelian group: virtually done

Missing/next steps

- differential of the inclusion, differential at a product (easy)
- proof of the collar neighbourhood theorem: hard/large
- transitivity of the bordism relation
- remaining group properties

Mathlib's manifold design

- mathlib has a very general definition of manifolds
 - infinite-dimensional case included (e.g. Banach manifolds)
 - over any field: e.g. \mathbb{R} , \mathbb{C} or p-adic numbers
 - allows boundary and corners (and even more)

Mathlib's manifold design

- mathlib has a very general definition of manifolds
 - infinite-dimensional case included (e.g. Banach manifolds)
 - over any field: e.g. \mathbb{R} , \mathbb{C} or p-adic numbers
 - allows boundary and corners (and even more)
- the data of a manifold (example: $\overline{\mathbb{D}}$)
 - M: the manifold (e.g. $\overline{\mathbb{D}}$)
 - H: the local model, a topological space (e.g. \mathbb{H})
 - E: normed space (e.g. \mathbb{R}^2)
 - I: model with corners, continuous map $H \to E$ (e.g. canonical inclusion)
 - charts on M (one preferred chart at each point)
 - compatibility condition: transition maps lie in structure groupoid
- why? abstract to clarify, re-usability

Design decisions: singular manifolds

Abridged code:

```
structure SingularManifold.{u} (X : Type*) [TopologicalSpace X] (k : WithTop N∞)
{E H : Type*) [NormedAddCommGroup E] [NormedSpace R E] [FiniteDimensional R E]
[TopologicalSpace H] (I : ModelWithCorners R E H) where
M : Type u
[CompactSpace M] [BoundarylessManifold I M]
f : M - X
hf : Continuous f
```

- bundled design, to allow using in the definition of bordism groups
- include smoothness exponent explicitly:
 allow smooth manifolds, but also C^k or analytic
- model with corners as a type explicit parameter disjoint union and bordism needs matching model on components
- non-ideal: type parameter in the definition with new universe variable but: X need not be related to M, want to enable functoriality

```
def map.{u} (s : SingularManifold.{u} X k I) {\phi : X - Y} (h\phi : Continuous \phi) : 
 | SingularManifold.{u} Y k I where 
 f := \phi · s.f 
 hf := h\phi.comp s.hf
```

Design decisions: manifolds with smooth boundary

- initial design: consider the set of boundary points, endow with smooth structure
- painful to work with, because of propositional equality of types
 - e.g. if M is closed, $\partial(M \times N) = M \times \partial N$ is not definitionally equal thus cannot re-use a general product construction
 - closed manifolds have empty boundary: only propositionally
- better design: consider boundary as **embedded smooth submanifold**, i.e. choose a smooth manifold M_0 with a smooth embedding $f: M_0 \to M$ s.t. range $f = \partial M$

Design decisions: manifolds with smooth boundary (cont.)

Abridged definition:

```
structure BoundaryManifoldData.{u} (M: Type u) [TopologicalSpace M] [ChartedSpace H M]

(I: ModelWithCorners R E H) (k: WithTop N∞) [IsManifold I k M]

{E<sub>0</sub> H<sub>0</sub>: Type*) [NormedAddCommGroup E<sub>0</sub>] [NormedSpace R E<sub>0</sub>]

[TopologicalSpace H<sub>0</sub>] (I<sub>0</sub>: ModelWithCorners R E<sub>0</sub> H<sub>0</sub>) where

/-- A 'CA's manifold 'M<sub>0</sub>' which describes the boundary of 'M' -/

Mo: Type u

[isManifold : IsManifold I<sub>0</sub> k M<sub>0</sub>]

/-- A 'CA's map from the model manifold into 'M', which is required to be a smooth embedding, i.e. a 'CA's 'immersion which is also a topological embedding -/

f: M<sub>0</sub> - M

isEmbedding: Topology.IsEmbedding f

contMoliff: ContMoliff I<sub>0</sub> I k f

/-- If 'f' is 'C'', it is an immersion: this condition is vacuous for 'C<sup>0</sup>' maps. -/

isImmersion: (1: WithTop N∞) ≤ k - ∀ x, Function.Injective [mfderiv I<sub>0</sub> I f x]]

range_eq_boundary: Set.range f = I.boundary M
```

- type field is needed; choose to align universe to M
- real definition asks for IsSmoothEmbedding I₀ I k f instead in finite dimension, is equivalent the snippet above

Definition of unoriented bordisms

```
structure UnorientedBordism.{u, v} {X E H E' H' : Type*}
    [TopologicalSpace X] [TopologicalSpace H] [TopologicalSpace H']
    [NormedAddCommGroup E] [NormedSpace ℝ E] [NormedAddCommGroup E'] [NormedSpace ℝ E']
    (k : WithTop N∞) {I : ModelWithCorners R E H} [FiniteDimensional R E]
    (s : SingularNManifold.{u} X k I) (t : SingularNManifold.{v} X k I)
    (J : ModelWithCorners R E' H') where
  /-- The underlying compact manifold of this unoriented bordism -/
  W: Type (max u v)
  [compactSpace : CompactSpace W]
  [isManifold: IsManifold J k W]
  /-- The presentation of the boundary 'W' as a smooth manifold -/
  -- Future: we could allow bd.M_0 to be modelled on some other model, not necessarily I:
  -- we only care that this is fixed in the type.
  bd: BoundaryManifoldData W J k I
  /-- A continuous map `W - X` of the bordism into the topological space we work on -/
  F : W → X
  hF : Continuous F
  /-- The boundary of `W` is diffeomorphic to the disjoint union `M ⊔ M'`. -/
  φ : Diffeomorph I I (s.M ⊕ t.M) bd.Mo k
  /-- `F` restricted to `M ↔ ∂W` equals `f`: this is formalised more nicely as
  `f = F \circ \iota \circ \phi^{-1} : M \rightarrow X`, where `\iota : \partial W \rightarrow W` is the inclusion. -/
  hFf : F \circ bd.f \circ \phi \circ Sum.inl = s.f
  /-- `F` restricted to `N ↔ ∂W` equals `q` -/
  hFq : F \circ bd.f \circ \phi \circ Sum.inr = t.f
```

- bundled design, like SingularManifold
- note: no requirement dim $W = \dim M + 1$ yet (just for transitivity)
- model parameters I (for the boundary) and J (for the bordism) later applications take J as the product of I and the model for [0,1]

Outlook: future possibilities

- define the bordism ring with ring operation need to rewrite models with corners, using $\mathbb{R}^n \times \mathbb{R}^m \cong \mathbb{R}^{n+m}$
- prove ring axioms: distributivity requires the inverse function theorem
- relative bordism groups
 - generalise both singular manifolds and bordisms
 - describe the boundary of manifolds with corners
 - define a homology functor (probably easy)
 - show the Eilenberg-Steenrod axioms: mostly easy interesting: boundary is a smooth manifold (false without co-dimension condition)
- oriented bordism groups: mostly straightforward, but requires oriented manifolds and induced boundary orientation (missing)
- for mathlib: need a general definition of smooth immersions and embeddings



Immersions and smooth embeddings

Let M and N be finite-dimensional smooth manifolds.

Definition

A map $f: M \to N$ is an **immersion** iff each differential df_p , $p \in M$ is injective. f is a **smooth embedding** iff it is an immersion and a topological embedding.

Caution about smooth embeddings

- injective immersion does not imply embedding
- smooth map and topological embedding does not imply embedding

Immersions in infinite dimensions

Let $f: M \to N$ be a smooth map between smooth (Banach) manifolds.

Definition

f is an immersion iff each differential df_p for $p \in M$ is injective.

Caution: too weak in infinite dimensions.

Better definition 1

f is an immersion iff each differential df_p for $p \in M$ splits, i.e. is an injective continuous linear map whose range is closed with a closed complement.

Better definition 2

f is an immersion for each $p \in M$, there are charts ϕ and ψ around p and f(p) in which f looks like $u \mapsto (u, 0)$.

Fact

If M and N are finite-dimensional, these definitions are all equivalent.

Immersions in Banach manifolds

Caution

Banach manifolds require additional conditions are boundary points. Currently, smoothness of immersions follows only at interior points.

Comparing these definitions

- Fact. Are equivalent over Banach manifolds.
- Definition 2 is nicer to work with: implies smoothness, similar to constant rank theorem.
- Definition 1 is easier to check (just compute differentials).
 Proving that composition of immersions is an immersion is much easier!

Formalisation status: immersions and smooth embeddings

1000-1500 lines of code already: work in progress

- o find the right definition
- reduce to the standard finite-dimensional definition
- prove: composition of immersions is an immersion
- prove: composition of split linear maps is split
- f immersion implies differential splits
- split differential implies immersion: requires inverse function theorem
- immersion is C^n (need better definition)

Formalisation status: smooth embeddings

- inverse function theorem first version done, "proper version" in progress
- define smooth embeddings
- prove composition of smooth embeddings is a smooth embedding

Formalising embedded submanifolds

Green items mean "sorry-free and mathlib-ready"; depend on smooth embeddings.

- define a suitable class of models with corners
- candidate definition of embedded submanifolds
- construction and properties of slice charts
- $f: M \to N$ smooth embedding implies $M \subset N$ embedded submanifold
- open subset is an embedded submanifold
- \bullet $\overline{\mathbb{D}} \subset \mathbb{R}^2$ is an embedded submanifold
- sanity check: M as submanifold of $M \times N$ (easy)
- future: construct submanifolds via constant rank theorem

Outlook and next steps

- prove smoothness
- prove: split linear maps compose
- ullet polish inverse function theorem; prove "split differential o immersion"
- open a definition of embedded submanifolds for discussion

Summary

Prologue

- Bordism theory is an *extra-ordinary* homology theory.
- Applications: Hirzebruch signature theorem, existence of exotic spheres
- Formalisation is a good test of mathlib's differential geometry section
- Immersions, smooth embeddings and submanifolds are missing, but within reach.
- Be patient and prepared to fill in missing API. Avoid propositional equality of types. Be careful with your universes.

Thanks for listening! Any questions?

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Dream goal

Bordism theory as first proven homology theory in mathlib

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Bordism theory as first proven homology theory in mathlib

Answer: boundary map for homology requires proving " ∂M is a dim M-1-dimensional manifold".

• Uses: interior and boundary are independent of the chosen chart.

Where did I cheat?

Dream goal

Bordism theory as first proven homology theory in mathlib

Answer: boundary map for homology requires proving " ∂M is a dim M-1-dimensional manifold".

- Uses: interior and boundary are independent of the chosen chart.
- Uses: invariance of domain, e.g. via singular homology of spheres

Upshot: this requires singular homology (or similar) first