

Configuration Spaces of Graphs

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Outline

- 1 Introduction
- 2 Describing H_1 and H_2

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2 Describing H_1 and H_2

Definition of Configuration Space $F(\Gamma, n)$

- Let Γ be a graph.
- $F(\Gamma, n)$ is the collection of all n -tuples of distinct points in Γ .

Definition

$$F(\Gamma, n) = \{(x_1, \dots, x_n) \in \Gamma^n \mid x_i \neq x_j \text{ if } i \neq j\}$$

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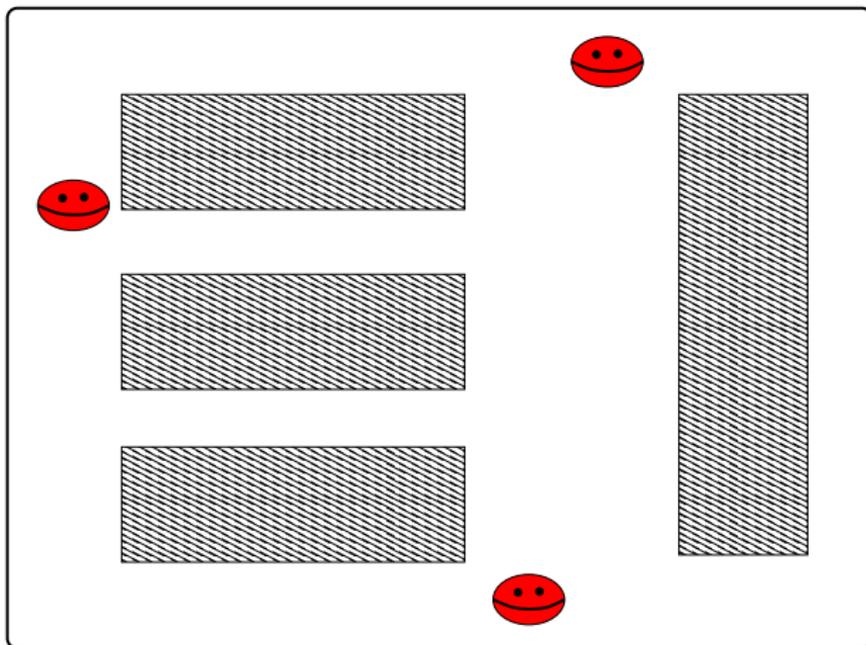
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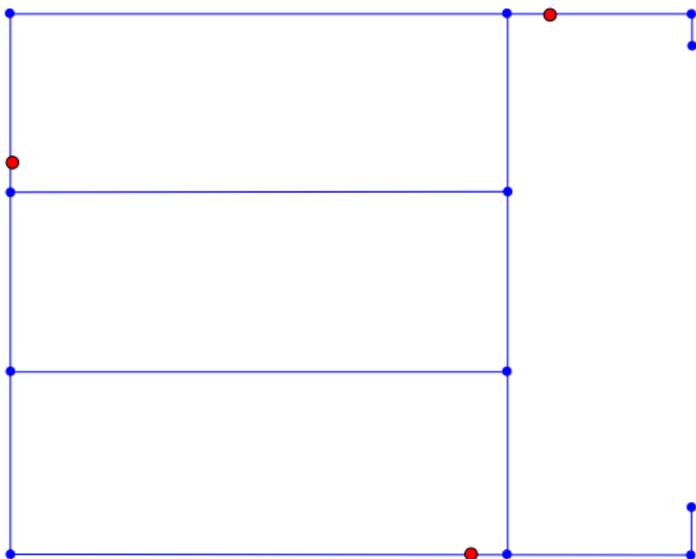
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Configuration Spaces are Important in Robotics

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Examples of $F(\Gamma, 2)$

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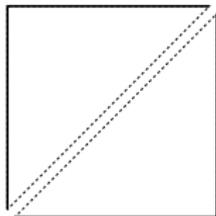
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$$F(K_{3,3}, 2) \simeq \Sigma_4 \text{ (Copeland-Patty)}$$

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Examples of $F(\Gamma, 2)$

$F([0, 1], 2)$:



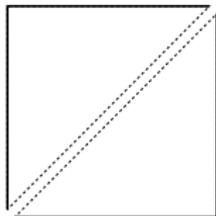
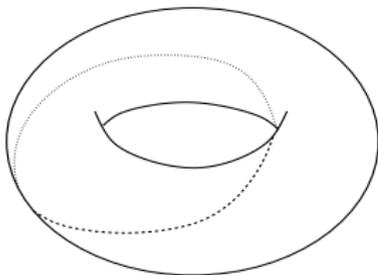
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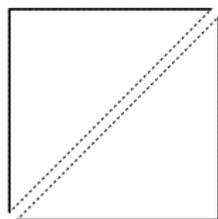
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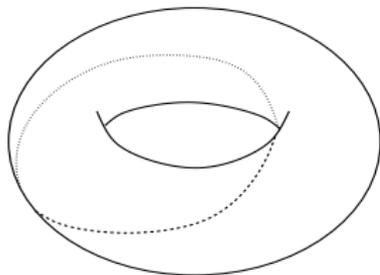
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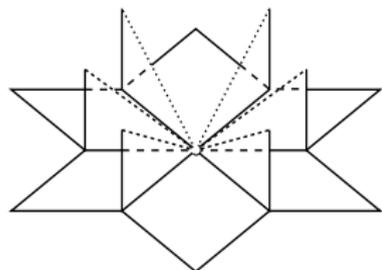
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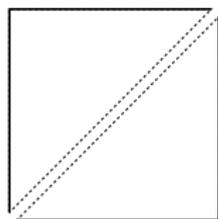
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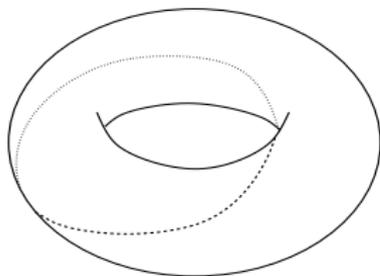
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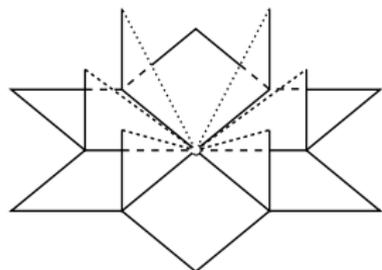
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$F(\Gamma, 2)$ is Usually Path-Connected

- $F([0, 1], 2) \simeq 2$ points.
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- All other graphs Γ contain a vertex of valence ≥ 3 .
- This implies that $F(\Gamma, 2)$ is path-connected.

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$F(\Gamma, 2)$ is path-connected provided $\Gamma \not\cong [0, 1]$.

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The Discrete Configuration Space $D(\Gamma, 2)$

For $x \in \Gamma$, let $\text{supp}(x)$ denote the closure of the simplex containing x .

Definition

$$D(\Gamma, 2) = \{(x, y) \in \Gamma \times \Gamma \mid \text{supp}(x) \cap \text{supp}(y) = \emptyset\}$$

- $D(\Gamma, 2)$ is a deformation retract of $F(\Gamma, 2)$.
- $D(\Gamma, 2)$ is a 2-dimensional cell complex.

$$\chi(D(\Gamma, 2)) = \chi(\Gamma)^2 + \chi(\Gamma) - \sum_{v \in V(\Gamma)} (\mu(v) - 1)(\mu(v) - 2).$$

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Our Aim

In summary:

- $F(\Gamma, 2)$ is path-connected for $\Gamma \neq [0, 1]$.
- $F(\Gamma, 2)$ is homotopy equivalent to a 2-dimensional cell complex $D(\Gamma, 2)$.
- We know $\chi(F(\Gamma, 2))$.

Our Aim:

- Describe $F(\Gamma, 2)$ for a large class of graphs Γ .
- Do this by studying $H_1(F(\Gamma, 2))$ and $H_2(F(\Gamma, 2))$.

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Long Exact Sequence of $(\Gamma \times \Gamma, F(\Gamma, 2))$

From now on, assume $\Gamma \not\cong [0, 1], S^1$.

Lemma (Barnett-Farber)

The map $H_1(F(\Gamma, 2)) \rightarrow H_1(\Gamma \times \Gamma)$ is surjective.

- $H_2(F(\Gamma, 2)) \cong \ker \mathcal{I}$.
- $H_1(F(\Gamma, 2)) \cong H_1(\Gamma) \oplus H_1(\Gamma) \oplus \operatorname{coker} \mathcal{I}$.

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Planar Case

Barnett-Farber

- Find a basis for $\ker \mathcal{I} \cong H_2(F(\Gamma, 2))$.

Theorem (Barnett-Farber)

For planar graphs Γ with 'enough edges'

$$b_2(F(\Gamma, 2)) = b_1(\Gamma)^2 - b_1(\Gamma) + 2 - \sum_{v \in V(\Gamma)} (\mu(v) - 1)(\mu(v) - 2),$$

$$b_1(F(\Gamma, 2)) = 2b_1(\Gamma) + 1.$$

- For these graphs, $\operatorname{coker} \mathcal{I}$ has rank 1.
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Non-planar Case

- For a large class of non-planar graphs, $\text{coker } \mathcal{I} = 0$.
- We call these graphs **mature**.
- For a mature graph Γ we have

$$b_1(F(\Gamma, 2)) = 2b_1(\Gamma),$$

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Key Result

Theorem (H.-Farber)

Let u, v be vertices in Γ that are not joined by an edge. Assume that $\Gamma - \{u, v\}$ is connected. Let Γ' be obtained from Γ by attaching an edge at u and v . If Γ is mature, then so is Γ' .

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Examples

H.-Farber

- The complete graph K_n is mature for all $n \geq 5$.

$$b_1(F(K_n, 2)) = (n-1)(n-2),$$

$$b_2(F(K_n, 2)) = \frac{1}{4}n(n-2)(n-3)(n-5) + 1,$$

- The bipartite graph $K_{p,q}$ is mature for all $p, q \geq 3$.

$$b_1(F(K_{p,q}, 2)) = 2(p-1)(q-1),$$

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$$b_1(F(K_n, 2)) = (n-1)(n-2),$$

$$b_2(F(K_n, 2)) = \frac{1}{4}n(n-2)(n-3)(n-5) + 1,$$

- The bipartite graph $K_{p,q}$ is mature for all $p, q \geq 3$.

$$b_1(F(K_{p,q}, 2)) = 2(p-1)(q-1),$$

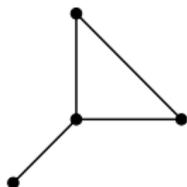
$$b_2(F(K_{p,q}, 2)) = (p^2 - 3p + 1)(q^2 - 3q + 1).$$

Non-Examples I

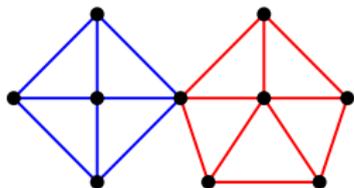
H.-Farber

The following imply that Γ is not mature:

- 1 Γ contains a univalent vertex.



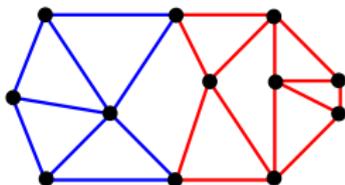
- 2 Γ decomposes as a wedge of two connected graphs Γ_1 and Γ_2 .



Non-Examples II

H.-Farber

- ③ Γ decomposes as a double wedge of two connected graphs Γ_1 and Γ_2 , each different from $[0, 1]$.



Summary

- Configuration spaces of graphs are relevant to motion planning in robotics.
- Barnett-Farber calculated $b_1(F(\Gamma, 2))$ and $b_2(F(\Gamma, 2))$ for a large class of planar graphs Γ .
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Configuration Spaces of Thick Particles

Kenneth Deeley

Let Γ be a metric graph and $r > 0$.

Definition

$$F_r(\Gamma, 2) = \{(x, y) \in \Gamma \times \Gamma \mid d(x, y) \geq 2r\}$$

He shows:

- 1 For $r > \frac{1}{2}\text{diam}(\Gamma)$, $F_r(\Gamma, 2) = \emptyset$.
- 2 For $r < \epsilon_\Gamma$, $F_r(\Gamma, 2) \simeq F(\Gamma, 2)$.
- 3 $F_r(\Gamma, 2)$ assumes only finitely many homotopy types.

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