

# Representation Theories of the Symmetric Group and the Rook Monoid

Tânia Sofia Zaragoza Cotrim Silva



Young Women in Representation Theory  
Mathematical Institute of the University of Bonn

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# The special case of the Symmetric Group

$n.$ ° of isoclasses of Irr. Rep. of  $G = n.$ ° of conjugacy classes in  $G$

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$n.$ ° of isoclasses of Irr. Rep. of  $\mathcal{S}_n = n.$ ° of partitions of  $n$

## Isoclasses of Irreducible Representations of $\mathcal{S}_n$

(1)

$n = 1$

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(1)  $n = 1$

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(3) (2,1) (1,1,1)  $n = 3$

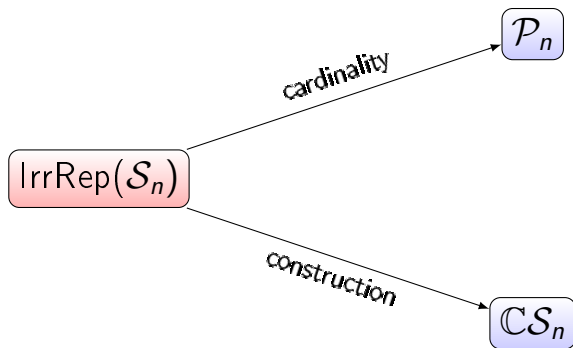
Isoclasses of Irreducible Representations of  $\mathcal{S}_n$ 

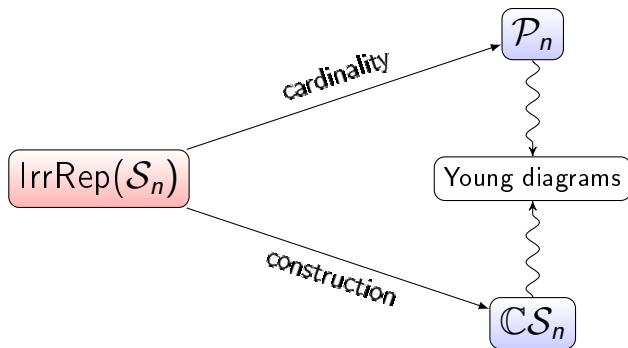
		(1)				$n = 1$
		(2)	(1,1)			$n = 2$
		(3)	(2,1)	(1,1,1)		$n = 3$
(4)	(3,1)	(2,2)	(2,1,1)	(1,1,1,1)		$n = 4$



Isoclasses of Irreducible Representations of  $\mathcal{S}_n$ 

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	(4)	(3,1)	(2,2)	(2,1,1)	(1,1,1,1)			$n = 4$
(5)	(4,1)	(3,2)	(3,1,1)	(2,2,1)	(2,1,1,1)	(1,1,1,1,1)		$n = 5$



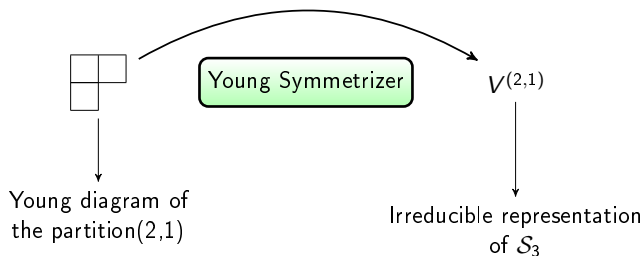


# Classic Approach

$$\left\{ \begin{array}{c} \lambda \\ \text{partition of } n \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{c} S^\lambda \\ \text{Specht module} \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{c} \text{class of irreducible} \\ \mathcal{S}_n\text{-representations} \end{array} \right\}$$

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# Constructing the Specht Modules of $\mathcal{S}_3$

$$\lambda_1 = (3)$$

$$\lambda_2 = (2, 1)$$

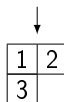
$$\lambda_3 = (1, 1, 1)$$

# Constructing the Specht Modules of $\mathcal{S}_3$

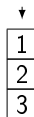
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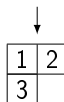
$$\lambda_1 = (3)$$



$$R_{\lambda_1} = \mathcal{S}_3$$

$$C_{\lambda_1} = \{(1)\}$$

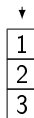
$$\lambda_2 = (2, 1)$$



$$R_{\lambda_2} = \{(1), (1\ 2)\}$$

$$C_{\lambda_2} = \{(1), (1\ 3)\}$$

$$\lambda_3 = (1, 1, 1)$$

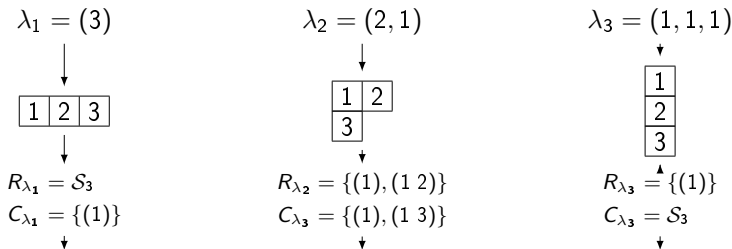


$$R_{\lambda_3} = \{(1)\}$$

$$C_{\lambda_3} = \mathcal{S}_3$$



# Constructing the Specht Modules of $\mathcal{S}_3$



Young symmetrizers

$$s_{\lambda_i} = \left( \sum_{\sigma \in R_{\lambda_i}} \sigma \right) \left( \sum_{\sigma \in C_{\lambda_i}} \text{sign}(\sigma) \sigma \right) \in \mathbb{C}\mathcal{S}_3$$

Constructing the Specht Modules of  $\mathcal{S}_3$ 

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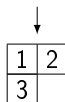


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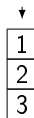


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Young symmetrizers

$$\mathfrak{s}_{\lambda_i} = \left( \sum_{\sigma \in R_{\lambda_i}} \sigma \right) \left( \sum_{\sigma \in C_{\lambda_i}} \text{sign}(\sigma) \sigma \right) \in \mathbb{C}\mathcal{S}_3$$

$$\downarrow$$

$$\mathbb{C}\mathcal{S}_3 \cdot \mathfrak{s}_{\lambda_1}$$

$$\mathbb{C} \sum_{\sigma \in \mathcal{S}_3} \sigma$$

$$\downarrow$$

$$\mathbb{C}\mathcal{S}_3 \cdot \mathfrak{s}_{\lambda_2}$$

$$\mathbb{C}\mathfrak{s}_{\lambda_2} + \mathbb{C}x$$

$$\downarrow$$

$$\mathbb{C}\mathcal{S}_3 \cdot \mathfrak{s}_{\lambda_3}$$

$$\mathbb{C} \sum_{\sigma \in \mathcal{S}_3} \text{sgn}(\sigma) \sigma$$

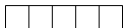
## Theorem

When  $\lambda$  ranges over all distinct partitions of  $n$ ,  $\{\mathbb{C}\mathcal{S}_n \cdot \mathfrak{s}_\lambda\}$  is a full set of non-isomorphic simple  $\mathbb{C}\mathcal{S}_n$ -modules.

# Representation Theories of the Symmetric Group and the Rook Monoid

## └ The Symmetric Group

### └ Classic Approach



# Branching Graph

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Let  $V$  be a simple  $\mathbb{C}S_n$ -module.

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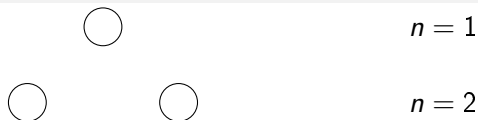
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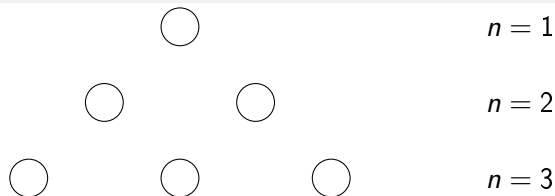


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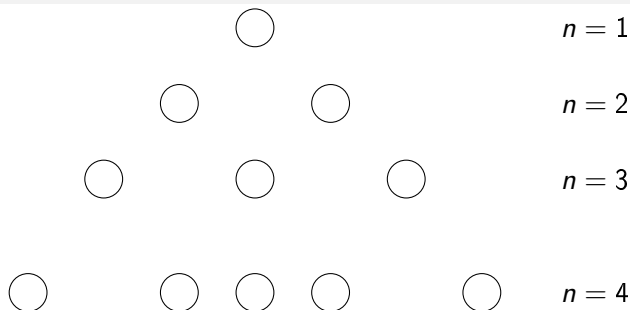


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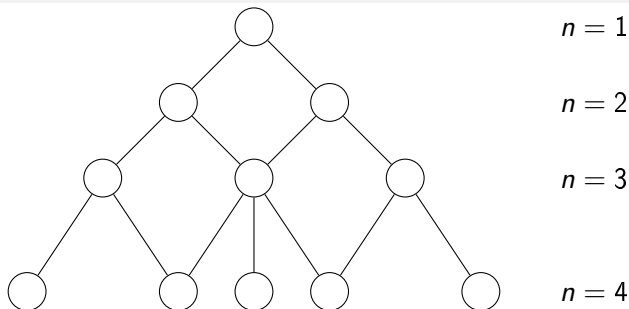


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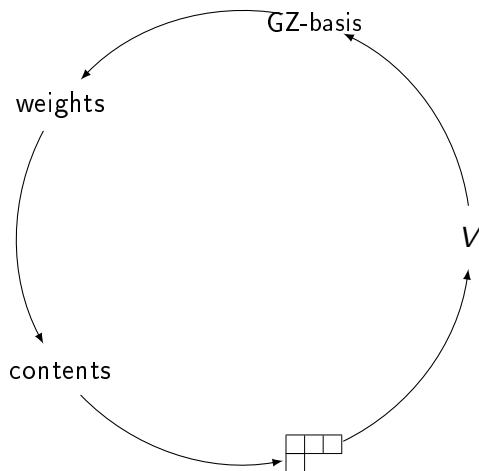
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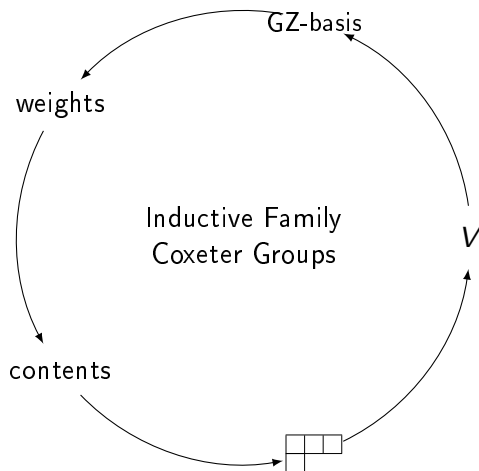
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# Different Approach

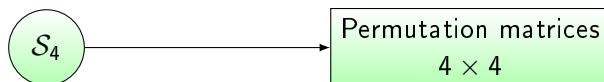


# Different Approach

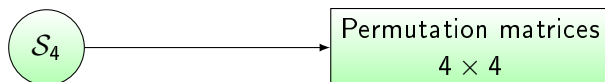


## Example: The standard representation of $\mathcal{S}_4$

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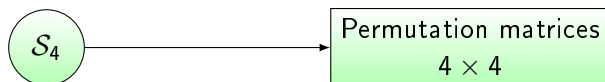


$$\rho : \mathcal{S}_4 \rightarrow GL(V)$$

where for all  $\sigma \in \mathcal{S}_4$

$$\rho(\sigma)(x_1, x_2, x_3, x_4) = (x_{\sigma^{-1}(1)}, x_{\sigma^{-1}(2)}, x_{\sigma^{-1}(3)}, x_{\sigma^{-1}(4)}).$$

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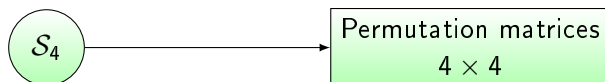
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$$V = \{(x_1, x_2, x_3, x_4) \in \mathbb{C}^4 : x_1 + x_2 + x_3 + x_4 = 0\}$$



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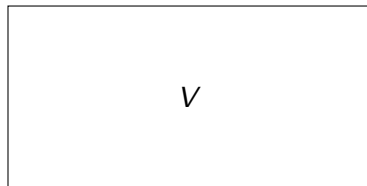
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$\rho$  is an irreducible representation of  $\mathcal{S}_4$

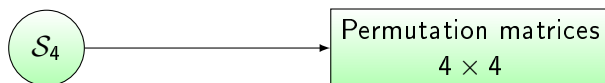
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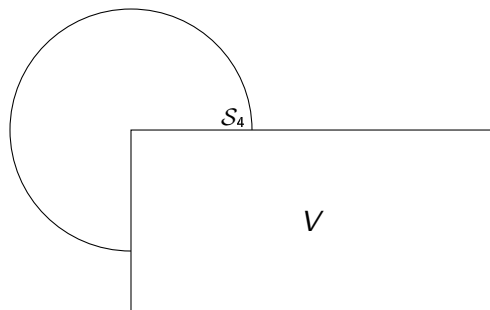
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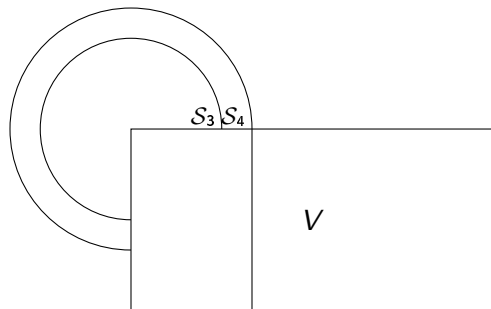
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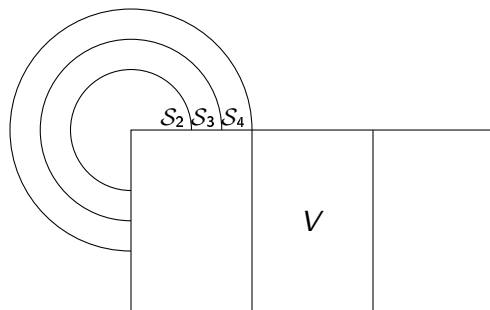
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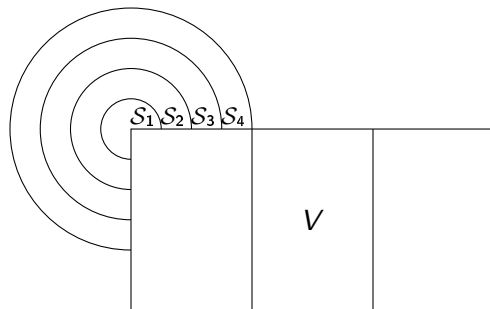
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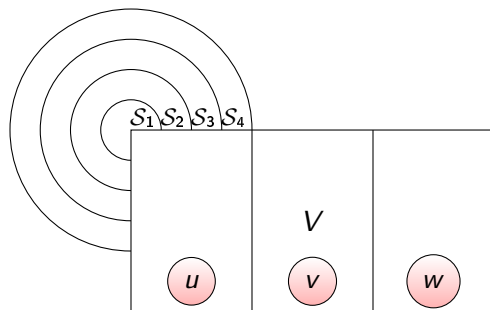
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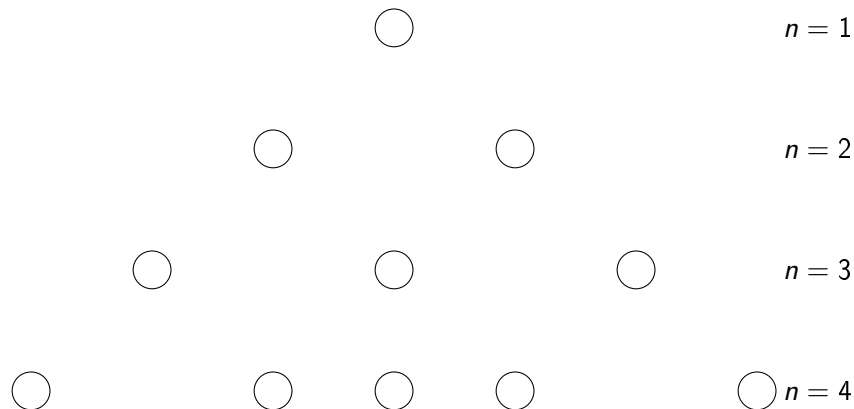
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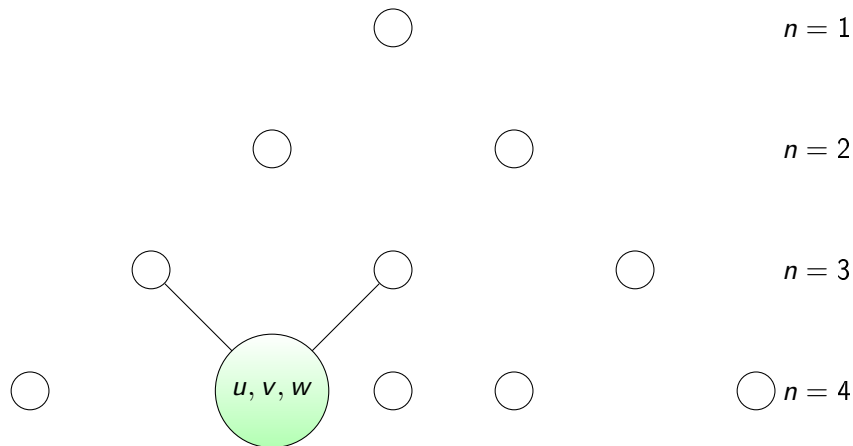


# Branching Graph

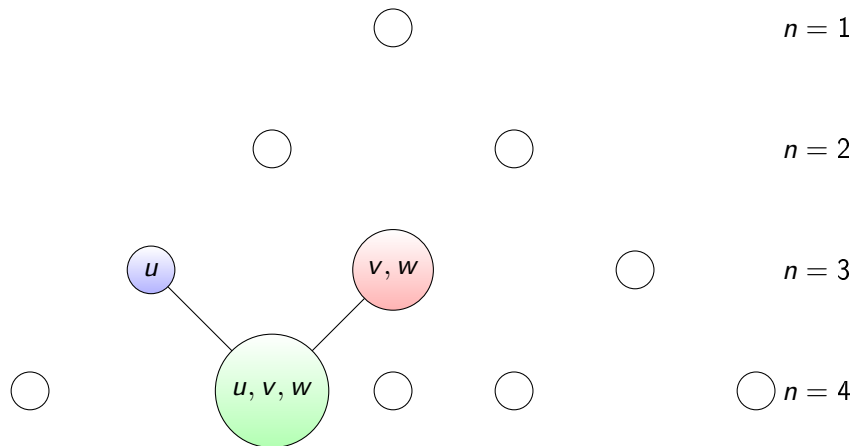




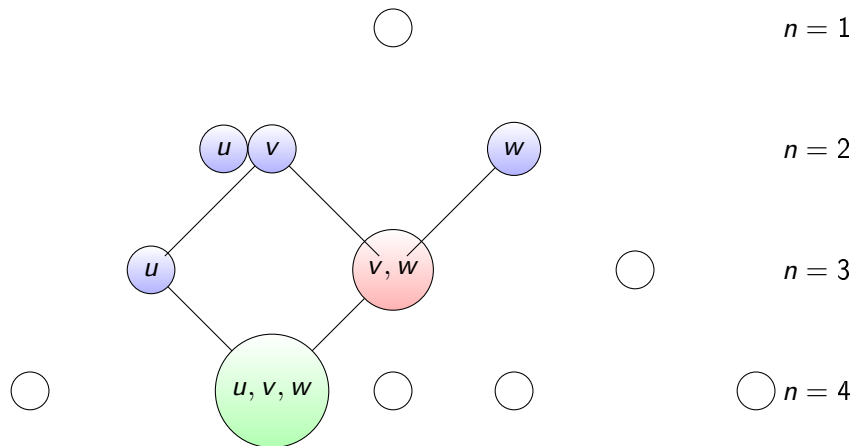
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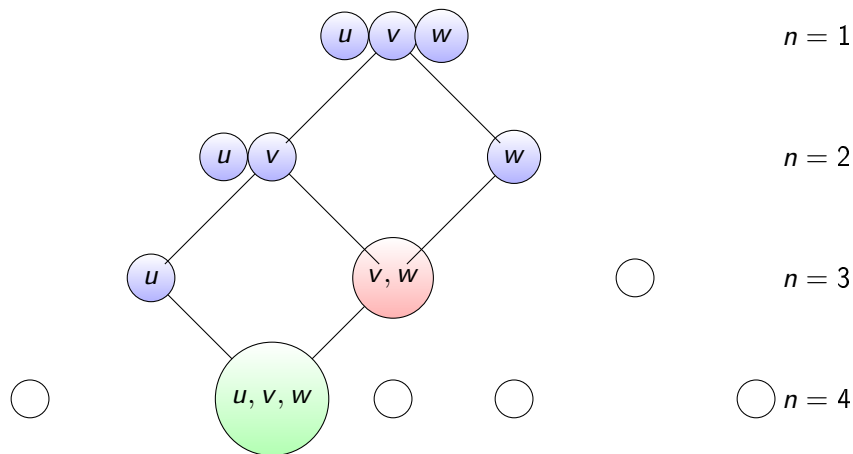
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## Proposition

All simple  $\mathbb{C}S_n$ -module  $V$  has a canonical decomposition

$$V = \bigoplus_T V^T$$

indexed by all possible chains

$$T = \lambda_1 \nearrow \dots \nearrow \lambda_n$$

where  $\lambda_i \in \mathcal{S}_n^\wedge$ ,  $V \in \lambda_n$  and all  $V^T$  are simple  $\mathcal{S}_1$ -modules.

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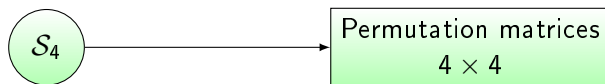
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## Gelfand-Zetlin Basis

For each  $T$  we can choose a vector  $v_T$  from each  $V^T$  obtaining a basis  $\{v_T\}$  of  $V$ , which we call **Gelfand-Zetlin basis**.

## Example: The standard representation of $\mathcal{S}_4$

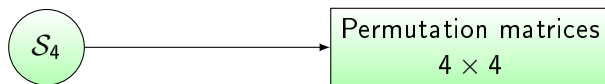


$$V = \{(x_1, x_2, x_3, x_4) \in \mathbb{C}^4 : x_1 + x_2 + x_3 + x_4 = 0\}$$

$$V = \langle (1, 1, 1, -3) \rangle \oplus \langle (1, 1, -2, 0) \rangle \oplus \langle (1, -1, 0, 0) \rangle.$$

Let  $u = (1, 1, 1, -3)$ ,  $v = (1, 1, -2, 0)$ ,  $w = (1, -1, 0, 0)$  and fix the basis  $\text{GZ} = \{u, v, w\}$  for  $V$ .

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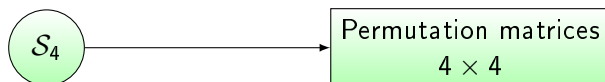
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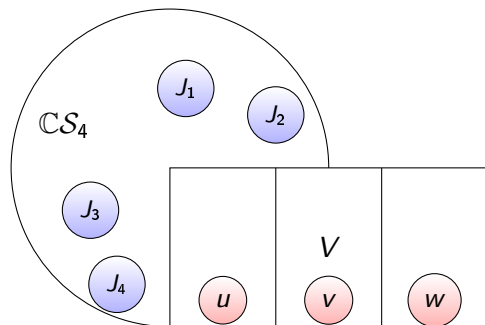
(1)	(1 2)	(2 3)	(3 4)
$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} \\ 0 & \frac{3}{2} & \frac{1}{2} \end{bmatrix}$	$\begin{bmatrix} -\frac{1}{3} & \frac{2}{3} & 0 \\ \frac{4}{3} & 0 & 0 \\ 0 & \frac{1}{3} & 1 \end{bmatrix}$ .



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$$J_1 = 0$$

$$J_2 = (1\ 2)$$

$$J_3 = (1\ 3) + (2\ 3)$$

$$J_4 = (1\ 4) + (2\ 4) + (3\ 4)$$

Jucys-Murphy elements

## Example: The standard representation of $\mathcal{S}_4$

0	(1 2)	(1 3) + (2 3)	(1 4) + (2 4) + (3 4)
$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$	$\begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ .

$$\gamma(u) = (0, 1, 2, -1)$$

$$\gamma(v) = (0, 1, -1, 2)$$

$$\gamma(w) = (0, -1, 1, 2)$$

## Example: The standard representation of $\mathcal{S}_4$

$$\begin{array}{c}
 \hline
 \begin{array}{cccc}
 0 & (1\ 2) & (1\ 3) + (2\ 3) & (1\ 4) + (2\ 4) + (3\ 4) \\
 \hline
 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} & \begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} & \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \\
 \hline
 \end{array}
 \end{array} .$$

$$\left. \begin{array}{l}
 \gamma(u) = (0, 1, 2, -1) \\
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 \end{array} \right\} \text{weights}$$

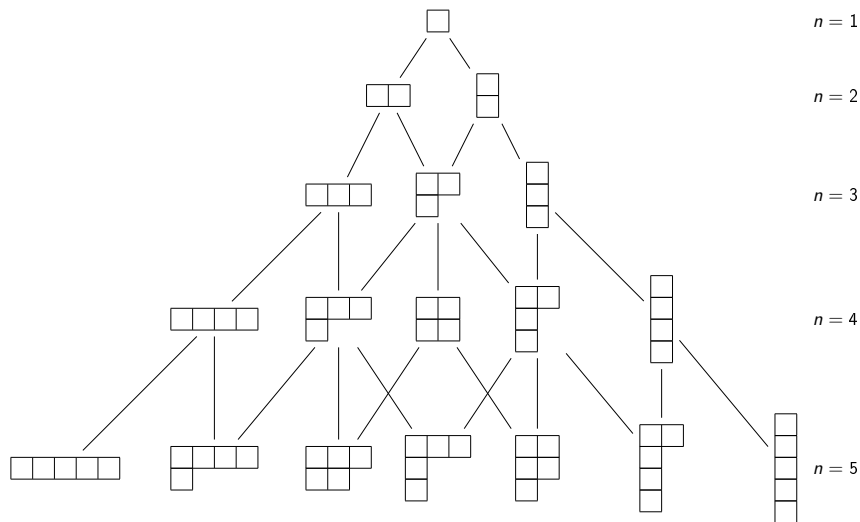
## Theorem

$$\mathbb{B} \simeq \mathbb{Y}$$

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### └ Different Approach



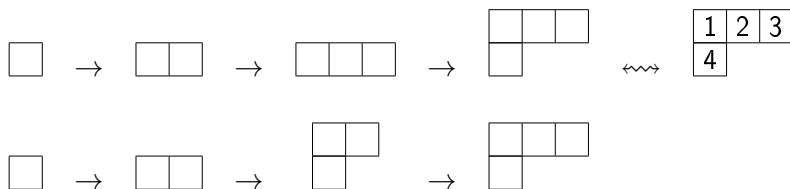
# Example



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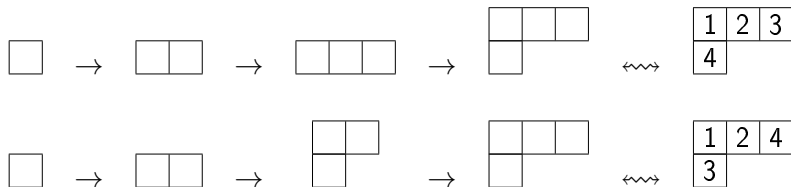


# Example

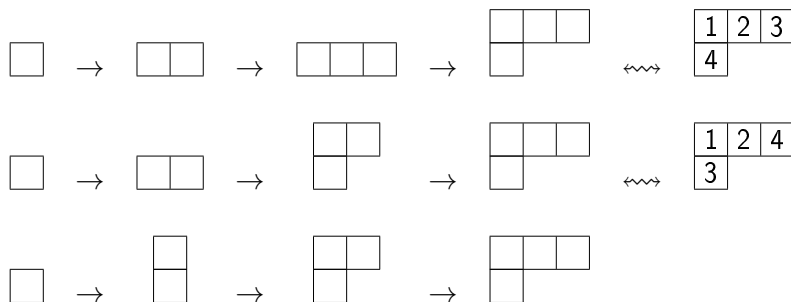




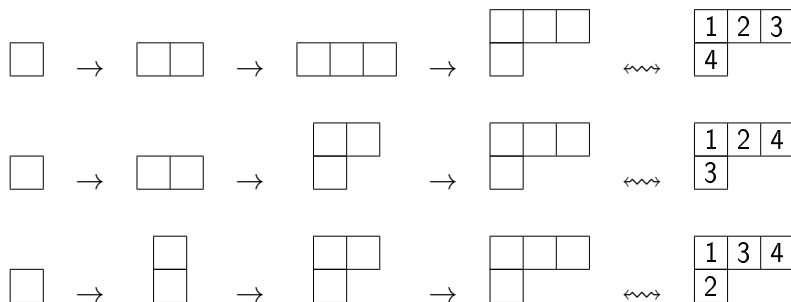
# Example



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## Example

Consider

$$Q_1 = \begin{array}{|c|c|c|} \hline 1 & 2 & 3 \\ \hline 4 & & \\ \hline \end{array}, \quad Q_2 = \begin{array}{|c|c|c|} \hline 1 & 2 & 4 \\ \hline 3 & & \\ \hline \end{array} \quad \text{and} \quad Q_3 = \begin{array}{|c|c|c|} \hline 1 & 3 & 4 \\ \hline 2 & & \\ \hline \end{array}.$$

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We have:

$$\delta(Q_1) = (0, 1, 2, -1)$$

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# The Spectrum and the Residue

## Theorem

Let  $\Omega$  be the set of all elements

$$x = (x_1, \dots, x_n) \in \mathbb{C}^n$$

which verify the following properties:

1.  $x_1 = 0$ ;
2.  $\{x_i - 1, x_i + 1\} \cap \{x_1, \dots, x_{i-1}\} \neq \emptyset, \quad \forall i \in \{2, \dots, n\}$ ;
3. If  $x_i = x_j = a$ , for some  $i < j$ , then

$$\{a-1, a+1\} \subseteq \{x_{i+1}, \dots, x_{j-1}\}.$$



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We have

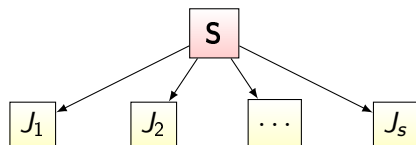
$$\Omega = \mathcal{E}_n = \mathcal{R}_n.$$

# Finite Semigroups Representation Theory



Finite Semigroup

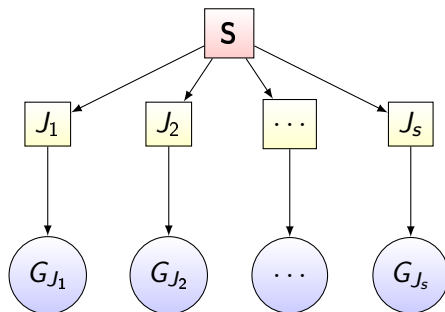
# Finite Semigroups Representation Theory



Finite Semigroup

$\mathcal{U}(S)$   
Regular  $\mathcal{J}$ -classes

# Finite Semigroups Representation Theory

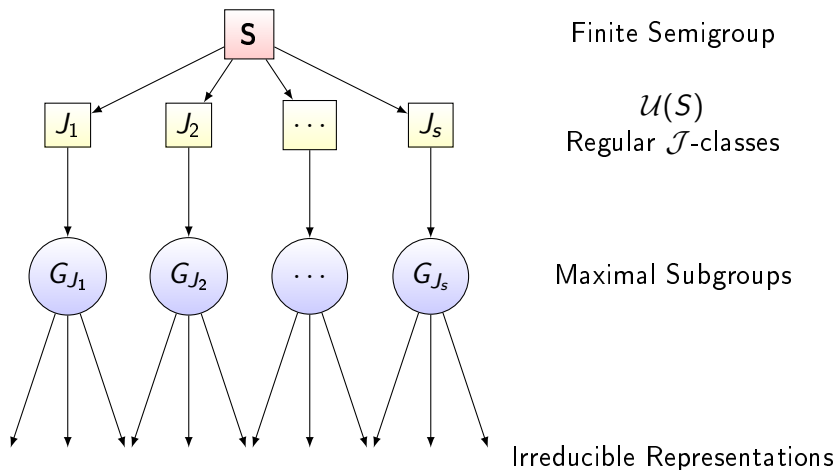


Finite Semigroup

$\mathcal{U}(S)$   
Regular  $\mathcal{J}$ -classes

Maximal Subgroups

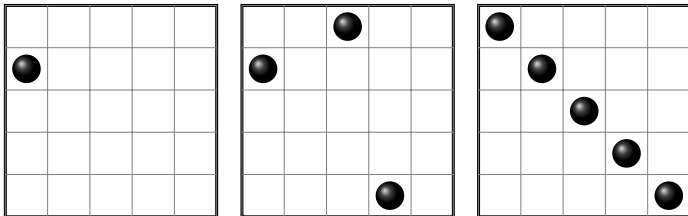
# Finite Semigroups Representation Theory



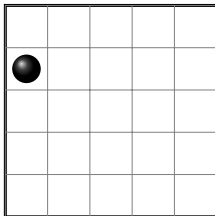
### Theorem[Clifford, Munn, Ponizovskii]

The number of irreducible representations of  $S$  (up to isomorphism) is equal to the number of irreducible representations of its maximal subgroups  $G_J$ , with  $J \in \mathcal{U}(S)$ .

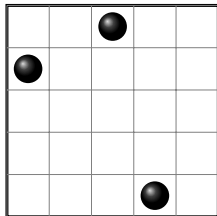
# The Rook Monoid



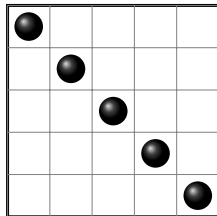
# The Rook Monoid



$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$



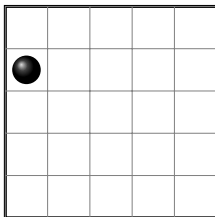
$$\begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$



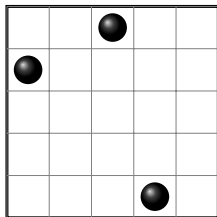
# The Rook Monoid



$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$



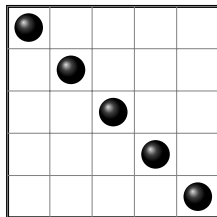
[2 1]



$$\begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$



[2 1 3][5 4]



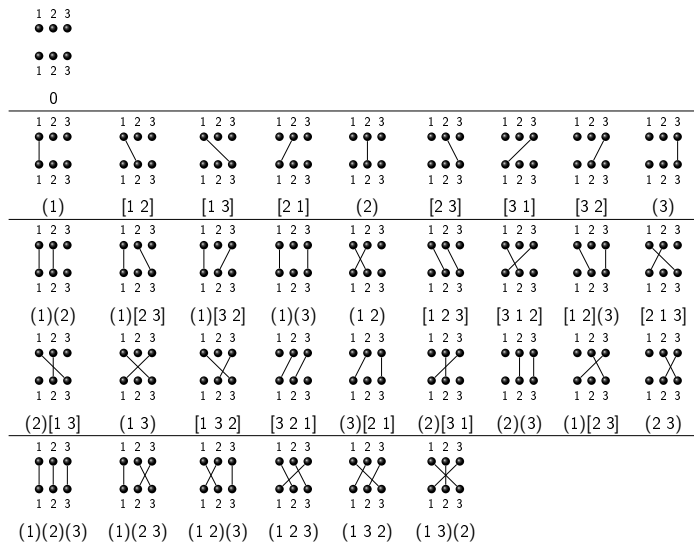
$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$



(1)(2)(3)(4)(5)

## └ The Rook Monoid

## └ Classical Approach



## The special case of the Rook Monoid

n.<sup>o</sup> of isoclasses of Irr. Rep. = sum of the n.<sup>o</sup> of isoclasses of Irr.  
Rep of its maximal subgroup  $G_J$

## The special case of the Rook Monoid

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The list of the maximal subgroups  $G_J$  of  $\mathcal{I}_n$  will be isomorphic to  $\mathcal{S}_0, \mathcal{S}_1, \dots, \mathcal{S}_n$ .

## The special case of the Rook Monoid

n.<sup>o</sup> of isoclasses of Irr. Rep. = sum of the n.<sup>o</sup> of isoclasses of Irr. Rep of its maximal subgroup  $G_J$



The list of the maximal subgroups  $G_J$  of  $\mathcal{I}_n$  will be isomorphic to  $\mathcal{S}_0, \mathcal{S}_1, \dots, \mathcal{S}_n$ .



$$|\text{IrrRep}(\mathcal{I}_n)| = \sum_{k=0}^n |\text{IrrRep}(\mathcal{S}_k)|$$

# Isoclasses of Irr. Rep. of $\mathcal{I}_n$

$\emptyset$

$n = 0$

# Isoclasses of Irr. Rep. of $\mathcal{I}_n$

 $\emptyset$  $n = 0$  $\emptyset$   $n = 1$

Isoclasses of Irr. Rep. of  $\mathcal{I}_n$  $\emptyset$  $n = 0$  $\emptyset$  $n = 1$  $\emptyset$  $n = 2$

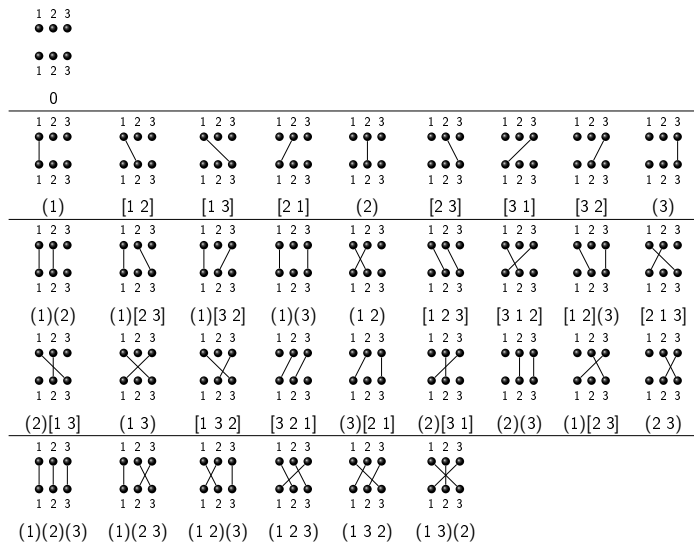


Isoclasses of Irr. Rep. of  $\mathcal{I}_n$  $\emptyset$  $n = 0$  $\emptyset$  $n = 1$  $\emptyset$  $n = 2$  $\emptyset$  $n = 3$

# Representation Theories of the Symmetric Group and the Rook Monoid

## The Rook Monoid

### Different Approach



## Representation Theories of the Symmetric Group and the Rook Monoid

## └ The Rook Monoid

## └ Different Approach

rank 0	rank 1			rank 2			rank 3
1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3   ●	1 2 3 ● ● ● ● ● ● 1 2 3   ●	1 2 3 ● ● ● ● ● ● 1 2 3   ●	1 2 3 ● ● ● ● ● ● 1 2 3   ●	1 2 3 ● ● ● ● ● ● 1 2 3   ●	1 2 3 ● ● ● ● ● ● 1 2 3   ●	1 2 3 ● ● ● ● ● ● 1 2 3   ●
$\mathcal{E}_\emptyset$	$\mathcal{E}_{\{1\}}$	$\mathcal{E}_{\{2\}}$	$\mathcal{E}_{\{3\}}$	$\mathcal{E}_{\{1,2\}}$	$\mathcal{E}_{\{1,3\}}$	$\mathcal{E}_{\{2,3\}}$	$\mathcal{E}_{\{1,2,3\}}$

rank 0	rank 1			rank 2			rank 3
1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ●   ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ●   ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ●   ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ●   ● ● ● 1 2 3	1 2 3 ● ● ●   ● ● ●   ● ● ● 1 2 3
$\varepsilon_{\emptyset}$	$\varepsilon_{\{1\}}$	$\varepsilon_{\{2\}}$	$\varepsilon_{\{3\}}$	$\varepsilon_{\{1,2\}}$	$\varepsilon_{\{1,3\}}$	$\varepsilon_{\{2,3\}}$	$\varepsilon_{\{1,2,3\}}$

$$\eta_0 = \varepsilon_{\emptyset}$$

$$\eta_1 = -3\varepsilon_{\emptyset} + \varepsilon_{\{1\}} + \varepsilon_{\{2\}} + \varepsilon_{\{3\}}$$

$$\eta_2 = 3\varepsilon_{\emptyset} - 2\varepsilon_{\{1\}} - 2\varepsilon_{\{2\}} - 2\varepsilon_{\{3\}} + \varepsilon_{\{1,2\}} + \varepsilon_{\{1,3\}} + \varepsilon_{\{2,3\}}$$

$$\eta_3 = -\varepsilon_{\emptyset} + \varepsilon_{\{1\}} + \varepsilon_{\{2\}} + \varepsilon_{\{3\}} - \varepsilon_{\{1,2\}} - \varepsilon_{\{1,3\}} - \varepsilon_{\{2,3\}} + \varepsilon_{\{1,2,3\}}$$

rank 0	rank 1			rank 2			rank 3
1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3
$\varepsilon_\emptyset$	$\varepsilon_{\{1\}}$	$\varepsilon_{\{2\}}$	$\varepsilon_{\{3\}}$	$\varepsilon_{\{1,2\}}$	$\varepsilon_{\{1,3\}}$	$\varepsilon_{\{2,3\}}$	$\varepsilon_{\{1,2,3\}}$

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$$\eta_3 = -\varepsilon_\emptyset + \varepsilon_{\{1\}} + \varepsilon_{\{2\}} + \varepsilon_{\{3\}} - \varepsilon_{\{1,2\}} - \varepsilon_{\{1,3\}} - \varepsilon_{\{2,3\}} + \varepsilon_{\{1,2,3\}}$$

In this case:

$$\mathcal{CI}_3 \simeq M_1(\mathbb{CS}_0) \oplus M_3(\mathbb{CS}_1) \oplus M_3(\mathbb{CS}_2) \oplus M_1(\mathbb{CS}_3)$$

rank 0	rank 1			rank 2			rank 3
1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3	1 2 3 ● ● ● ● ● ● 1 2 3
$\varepsilon_\emptyset$	$\varepsilon_{\{1\}}$	$\varepsilon_{\{2\}}$	$\varepsilon_{\{3\}}$	$\varepsilon_{\{1,2\}}$	$\varepsilon_{\{1,3\}}$	$\varepsilon_{\{2,3\}}$	$\varepsilon_{\{1,2,3\}}$

$$\eta_0 = \varepsilon_\emptyset$$

$$\eta_1 = -3\varepsilon_\emptyset + \varepsilon_{\{1\}} + \varepsilon_{\{2\}} + \varepsilon_{\{3\}}$$

$$\eta_2 = 3\varepsilon_\emptyset - 2\varepsilon_{\{1\}} - 2\varepsilon_{\{2\}} - 2\varepsilon_{\{3\}} + \varepsilon_{\{1,2\}} + \varepsilon_{\{1,3\}} + \varepsilon_{\{2,3\}}$$

$$\eta_3 = -\varepsilon_\emptyset + \varepsilon_{\{1\}} + \varepsilon_{\{2\}} + \varepsilon_{\{3\}} - \varepsilon_{\{1,2\}} - \varepsilon_{\{1,3\}} - \varepsilon_{\{2,3\}} + \varepsilon_{\{1,2,3\}}$$

In this case:

$$\mathbb{C}\mathcal{I}_3 \simeq M_1(\mathbb{C}S_0) \oplus M_3(\mathbb{C}S_1) \oplus M_3(\mathbb{C}S_2) \oplus M_1(\mathbb{C}S_3)$$

$$\mathbb{C}\mathcal{I}_n \simeq \mathbb{C}\mathcal{I}_n\eta_0 \oplus \dots \oplus \mathbb{C}\mathcal{I}_n\eta_n \simeq M_{\binom{n}{0}}(\mathbb{C}S_0) \oplus \dots \oplus M_{\binom{n}{n}}(\mathbb{C}S_n)$$

$\therefore \mathbb{C}\mathcal{I}_n$  is semisimple.

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