

Tree representations via ordinal machines

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Abstract. We study sets of reals computable by *ordinal Turing machines* with a tape of length the ordinals that are steered by a standard Turing program. The machines halt at some ordinal time or diverge. We construct tree representations for ordinal semi-decidable sets of reals from ordinal computations. The aim is to generalize uniformization results to classes of ordinal semi-decidable sets defined by bounds on the halting times of computations. We further briefly examine the jump structure and nondeterminism.

1 Introduction

Ordinal computability studies generalized computability theory by means of classical machine models that operate on ordinals instead of natural numbers. Starting with Joel Hamkins' and Andy Lewis' Infinite Time Turing Machines (ITTM) [1], recent years have seen several of those models which provided alternate approaches and new aspects for various ideas from logic, set theory and classical areas of generalized computability theory. With ITTMs, the machine may carry out a transfinite ordinal number of steps while writing 0s and 1s on tapes of length ω . This is achieved by the addition of a limit rule that governs the behavior of the machine at limit times. The 0s and 1s on the ω -long tape are interpreted as subsets of ω (*reals*). It turns out that the sets of reals semi-decidable by these machines form a subset of Δ_2^1 . Similar studies have been carried out for infinite time register machines (ITRMs), whose computable reals are exactly the reals in $L_{\omega_{CK}}$ [7].

Another direction of ordinal computability lifts classical computability to study not the subsets of ω , but of an arbitrary ordinal α , or even the class Ord of all ordinals. In this case, both space and time are set to that ordinal α , i.e. in the Turing context, we deal with machines that utilize a tape of length α and either stop in less than α many steps or diverge. The computation is steered by a standard Turing program and a finite number of ordinal parameters less than α . This approach unveils strong connections to Gödel's universe of constructible sets and the classical work on α -recursion theory [8].

In the present paper, we aim between these two approaches by analyzing the computable sets of reals of Turing machines with Ord space *and* time but without allowing arbitrary ordinal parameters. We work with *ordinal Turing machines* (OTMs), the machine model introduced in [6]. Let us briefly review the basic features, for more detail and background the reader is referred to the original paper.

An OTM uses the binary alphabet on a one-sided infinite tape whose cells are indexed by ordinal numbers. At any ordinal point in time, the machine head is located on one of these cells and the machine is in one of finitely many machine states indexed by natural numbers. Since we utilize both Ord space and time, there is no need to use multiple tapes in our definition; any fixed finite number of tapes can be simulated by interleaving the tapes into one. A typical program instruction has the form $(a, s, a', s', d) \in \{0, 1\} \times \omega \times \{0, 1\} \times \omega \times \{-1, 1\}$ and is interpreted as the instruction “*If the symbol currently read by the machines read-write head is a and the machine is currently in state s , then overwrite a with the symbol a' , change the machine state to s' , and move the head according to d either to the left or to the right*”. At successor times in the course of the computation, the machine behaves like a standard Turing machine, with the following exception: If the machine head rests on a cell indexed by a limit ordinal or 0 and a “*move left*”-instruction is carried out, then the head is set to position 0. The machine accesses the transfinite by the following lim inf-rule:

At a limit time λ , the machine state is set to the \liminf of the states of previous time, i.e., the least state that was assumed cofinally often in the previous steps. Similarly, we set the tape content for each cell individually to the \liminf of the previous cell contents; in other words, a cell contains a 0 at time λ if it contained a 0 cofinally often before λ , and it contains a 1 at time λ otherwise. It is natural to set the head position to the cell indexed by the \liminf over the indices of the cells visited at previous steps in which the machine's state was the same as in the limit.

These ordinal machines may be used to describe sets of reals. In order to input a real or set of ordinals into an ordinal Turing machine, we start the computation with an initial tape content coding the real or set of ordinals; for a real the initial tape contents is a sequence of numbers 0 and 1 written in the cells with finite index. Note that our basic definitions do not involve ordinal parameters as in [6, Definition 2.5], hence our main results are about pointclasses defined without parameters. Since elements of ${}^\omega\omega$ can be coded in ${}^\omega 2$ via Gödel pairing, we can have elements of ${}^\omega\omega$ as input. We will refer to elements of ${}^\omega\omega$ as reals. Let us denote the OTM computation by a program P on input x as $P(x)$ and abbreviate the statement “ $P(x)$ halts” as $P(x) \downarrow$.

Definition 1. *A set of reals $A \subseteq {}^\omega\omega$ is called OTM semi-decidable if there is an ordinal Turing machine that halts if and only if the initial tape content was an element of A . A is called OTM decidable if its characteristic function χ_A is an OTM computable function.*

Our motivation is to use ordinal machines to refine uniformization results in descriptive set theory. Many results in descriptive set theory have simple proofs using admissible sets [3]; we go further than [3] in providing explicit algorithms for the constructions. In section 2, we define an algorithm for searching for infinite branches in the Shoenfield tree, to prove that the Σ_2^1 sets of reals are exactly the OTM semi-decidable sets of reals. As a consequence, we re-establish Shoenfield's absoluteness from the perspective of ordinal computability. The fact that the Σ_2^1 sets of reals are exactly the OTM semi-decidable sets of reals may be alternatively obtained from Σ_2^1 absoluteness and the fact that bounded truth in L is an OTM computable relation (for the latter see [6]). In section 3, we introduce a tree representation for Σ_2^1 sets that is based on finite fragments of OTM computations. The main result of this paper is the application of this representation and the algorithm in section 2 to prove uniformization for classes of OTM semi-decidable sets of reals defined by upper bounds on the halting times of computations. Section 4 introduces a notion of nondeterministic OTM computations. Applying our algorithm from section 2 to the tree representation establishes that nondeterministically OTM decidable sets are already deterministically so. We then show that the jump structure of our machines depends on set theoretic assumptions. Let us refer to [4] and [5] for the set theoretic background.

2 Computing the Shoenfield tree

In this section, we define an OTM algorithm searching for branches in the Shoenfield tree. For technical reasons, let us fix the following OTM computable functions. The Gödel pairing function is a bijection $\langle \cdot, \cdot \rangle : \text{Ord} \times \text{Ord} \rightarrow \text{Ord}$. Elements of Baire space can be represented as subsets of ω by coding their graph via Gödel pairing. The function $o : \omega \rightarrow {}^{<\omega}\omega$ is a computable bijection providing a computable enumeration of the basic open sets $O(i)$ of the Baire space ${}^\omega\omega$, where $O(i)$ denotes the basic open set defined by the sequence $o(i)$.

We will make use of the standard tree representation for Π_1^1 sets due to Luzin and Sierpiński. Recall that a set $B \subseteq {}^k({}^\omega\omega)$ is Π_1^1 if there is a tree T on ${}^k\omega \times \omega$ such that $x \in B$ if and only if T_x is well-founded and the relation $\{(x, i) \mid o(i) \in T_x\}$ is computable. Let us call T the *Luzin-Sierpiński tree* for B . The tree T_x is well-founded if and only if there is an order-preserving embedding of T_x into some countable ordinal α . To check whether $x \in B$, we can look for a suitable infinite branch in the tree S on ${}^k\omega \times \omega_1$ of all pairs (s, u) with $s \in {}^k({}^n\omega)$ and $u \in {}^n\omega_1$ for some $n \in \omega$ where u codes an order-preserving map $f_u : T_s \cap \{o(i) \mid i < \text{length}(u)\} \rightarrow \omega_1$. This is the *Shoenfield tree* projecting to B .

Let us first define an algorithm searching the Shoenfield tree for a Π_1^1 sets $B \subseteq {}^\omega\omega$. Let T be the Luzin-Sierpiński tree for B . The algorithm shall halt on input $x \in {}^\omega\omega$ if and only if $x \in B$. Depth-first-search

(DFS) is employed to find an infinite branch in the subtree of S that consists of the pairs (s, u) , where $s = x \upharpoonright n$ for some $n \in \omega$. In other words, we will search S_x , which is a tree on ω_1 . Clearly, membership in S of any given pair (s, u) is OTM decidable in every admissible set, as the property $o(i) \in T_s$ is computable. Note that ω may be used as a constant, since the constant function with value ω is OTM computable.

Algorithm 1

set $\alpha = 0$

MAIN:

set $u = ()$;

set $n = 0$;

call DFS(u);

$\alpha ++$;

call MAIN;

DFS(u):

if $n = \omega$ then stop;

if $(x \upharpoonright n, u) \in S$ then set $n ++$ and set $u = u \frown 0$ and call DFS(u) and set $n --$ and set

$u = u \upharpoonright n$;

if $u(n) < \alpha$ set $u(n) ++$ and call DFS(u);

The algorithm starts with the empty sequence $u = ()$ and in stage $\alpha = 0$. Whenever DFS(u) is called, all possible extensions of u by a single ordinal $\beta < \alpha$ are tried. When all $\beta < \alpha$ have been tried, DFS(u) ends. If a feasible extension $u \frown \beta \in S_x$ is found, the recursion will immediately try to extend it further and DFS($u \frown \beta$) is called. Whenever the algorithm tries an extension $u \frown \beta$ that is not in S_x , this extension is not followed further and $u \frown (\beta + 1)$ is tried next. If the length n of u has reached ω , a branch is found, i.e., u codes an order preserving embedding of T_x into the ordinal α . If no branch can be found, the recursion eventually breaks down, α is incremented, and the algorithm starts over with the empty sequence.

Throughout the algorithm, the variable u is stored in an extra tape whose n -th cell contains a 1 if and only if $n \leq \langle p, q \rangle$ and $u(p) = q$ and 0 otherwise. Therefore, the variable also contains the desired value at limit times.

Lemma 1. *The algorithm will find the lexicographically least infinite branch through S_x , if there is one.*

Proof. It is clear that if the algorithm finds a branch, it will find the lexicographically least. So we have to show that this branch is eventually found. Let $v \in {}^\omega \omega_1$ be the lexicographically least branch of S_x and let γ be the supremum of the ordinals in v . The tree $S_x \cap {}^{<\omega} \gamma$ is countable. Observe that the algorithm visits exactly the nodes of $S_x \cap {}^{<\omega} \gamma$ in the stages $\alpha < \gamma$ and that every node is visited only once. Since this subtree contains no branches, the algorithm sets $\alpha = \gamma$ after countably many steps. Note that in stage γ , the algorithm will first visit the countably many sequences $w \in S_x$ that are lexicographically smaller than $v \upharpoonright \text{length}(w)$. No node w that is lexicographically greater than $v \upharpoonright \text{length}(w)$ is visited before the algorithm examines every initial segment of v , so the algorithm eventually finds the branch in countable time.

Now consider a Σ_2^1 set $A \subseteq {}^\omega \omega$ and a Π_1^1 set $B \subseteq {}^\omega \omega \times {}^\omega \omega$ such that $p(B) = A$. We will modify the above algorithm to semi-decide the set A . Let $(T \subseteq {}^2 \omega \times \omega)^{<\omega}$ be the Luzin-Sierpiński tree for B . The Shoenfield tree S for B is the tree of all (s, t, u) where u codes an order-preserving embedding $f_u : T_{s,t} \rightarrow \text{Ord}$. Since $B = p([S])$ and $A = p(B)$, we have $x \in A$ if and only if the tree S_x (on $\omega \times \omega_1$) has an infinite branch. In order to find such a branch for a given x , the algorithm proceeds in stages $\alpha \in \text{Ord}$. In each stage α , depth-first-search is employed to find an infinite branch in the subtree of S_x which consists of the pairs (t, u) where $t \in {}^{\text{length}(u)} \alpha$.

Algorithm 2

set $\alpha = 0$;

MAIN:

set $t = ()$;

set $u = ()$;

set $n = 0$;

call DFS(t, u);

set $\alpha ++$;

call MAIN;

DFS(t, u):

if $n = \omega$ then stop;

if $u(n) = \alpha$ then set $u(n) = 0$ and set $t(u) ++$;

if $t(n) = \omega$ then set $n --$ and set $t = t \upharpoonright n$ and set $u = u \upharpoonright n$;

if $(x \upharpoonright n, t, u) \in S$ then set $n ++$ and set $t = t \frown 0$ and set $u = u \frown 0$ and call DFS(t, u) and

set $n --$ and set $t = t \upharpoonright n$ and set $u = u \upharpoonright n$;

set $u(n) ++$ and call DFS(t, u);

Here in every call of DFS(t, u), the algorithm tries to extend t and u simultaneously by all pairs (m, β) with $m \in \omega$ and $\beta < \alpha$. Again, if $(t \frown m, u \frown \beta) \in S_x$, the sequence is immediately extended further, i.e. DFS($t \frown m, u \frown \beta$) is called. Otherwise, $(t \frown m, u \frown \beta + 1)$ is tried next. If for all $\beta < \alpha$ $(t \frown m, u \frown \beta)$ cannot be extended further, then $(t \frown m + 1, u \frown 0)$ is tried next, and so on.

Lemma 2. *The algorithm will find the lexicographically least z such that $S_{x,z}$ has a branch, and the lexicographically least branch v through $S_{x,z}$, if such a real z exists.*

Proof. Assume z and v are as required. As in Lemma 1, we can see that before stage γ (where γ is the supremum of the range of the embedding coded by v), only countably many nodes are visited. In stage γ , only countably many nodes are visited before the branch (z, v) is found.

It is straightforward to generalize this algorithm to semi-decide Σ_2^1 subsets of ${}^k\omega$. From the algorithms, we obtain short proofs of several results in classical descriptive set theory.

Corollary 1. *Suppose M is a transitive model of KP with $\omega_1 \subseteq M$. Then Σ_2^1 relations are absolute between M and V .*

Proof. Since OTM computations are absolute between transitive models of KP (see [6, Lemma 2.6]), so is membership in Σ_2^1 sets.

Corollary 2. *Every Σ_2^1 binary relation on the reals has a Σ_2^1 uniformization and every Π_1^1 binary relation on the reals has a Π_1^1 uniformization.*

Proof. Suppose $A \subseteq {}^\omega\omega \times {}^\omega\omega$ is a Σ_2^1 set. The algorithm semi-deciding $(x, y) \in A$ can be modified to search for a y given x as input. As we added the search for sequences $t \in {}^{<\omega}\omega$ to Algorithm 1 to obtain Algorithm 2, we may also add another search for $s \in {}^{<\omega}\omega$ with $(s, t, u) \in S_x$. An argument analogous to Lemmas 1 and 2 proves that the lexicographically least branch (y, z, v) through S_x is found. This corresponds to the lexicographically least branch through $S_{x,y}$, therefore $(x, y) \in A$. For any Π_1^1 binary relation, a similar modification of Algorithm 1 yields an algorithm semi-deciding a uniformization such that for any pair (x, y) in the uniformizing function, the algorithm halts before the least (x, y) -admissible $\omega_1^{x,y}$ above ω . Hence the uniformization is Π_1^1 by the Spector-Gandy Theorem.

This immediately implies

Corollary 3. *Every nonempty Σ_2^1 set of reals has a Σ_2^1 member, i.e. some x such that $\{x\}$ is a Σ_2^1 set, and every nonempty Π_1^1 set of reals has a Π_1^1 member.*

The proof of Corollary 2 shows that any function from the reals to the reals with OTM semi-decidable graph is OTM computable. Note that this is false when we consider OTM programs P such that $P(x)$ halts before ω_1^x for all x with $P(x) \downarrow$. Let us consider a Π_1^1 function, obtained via Π_1^1 uniformization f , mapping a real x to a code for a wellfounded countable model containing x of the theory T , where T is the extension KP requiring that there is an admissible ordinal. Although its graph is semi-decidable by such a program, it is easy to see that f is not OTM computable by a program of this type.

Corollary 4. *Every Σ_2^1 set is the union of ω_1 many Borel sets.*

Proof. Given a Σ_2^1 set A , let P be an OTM which terminates on input x if and only if $x \in A$. Let A_β denote the set of reals x such that $P(x)$ terminates before stage β . Then A is the union of the sets A_β . To see that each A_β is Borel, let a_β be a real coding the supremum γ_β over the halting times of the algorithm if restricted to at most β stages.¹ Then a real x is an element of A_β if and only if for some (for every) real c coding a computation along a_β , this computation halts. This shows that A_β is Δ_1^1 and hence Borel by Suslin's Theorem.

Corollary 5. *Every Σ_2^1 set has a Σ_2^1 norm.*

Proof. Let A be a Σ_2^1 set and let P_A be an algorithm semi-deciding A . The desired norm is given by the map ϕ where P_A halts at time $\phi(x)$ on input x . Let $x \leq y$ ($x < y$) if $P(x)$ halts (strictly) before $P(y)$, or $P(y)$ does not halt. Then $y \in A$ and $x \leq y$ imply $x \in A$. Using the algorithm, it is easy to see that the relations \leq and $<$ are OTM semi-decidable. Hence ϕ is a Σ_2^1 norm on A .

Note that we cannot obtain a Σ_2^1 norm whose initial segments are uniformly Borel. This would imply the existence of an uncountable sequence of distinct Borel sets of bounded rank, however this does not follow from ZF [2, Theorem 4.5].

In order to describe the supremum of the ordinals appearing as the halting time of some OTM program, let δ_2^1 denote the supremum of lengths of Δ_2^1 wellorders on sets of natural numbers. Let $\delta_2^1(x)$ denote the supremum of the length of Δ_2^1 wellorders in the parameter x on sets of natural numbers. Note that a real x is Δ_2^1 if and only if $\{x\}$ is Δ_2^1 or even just Σ_2^1 .

Corollary 6. *The supremum of halting times of OTMs with input x is $\delta_2^1(x)$.*

Proof. Suppose y codes a Δ_2^1 wellorder in the parameter x of type γ . Since we may assume that y is OTM computable, consider the algorithm searching for the next element in the wellorder. The algorithm halts as soon as every natural number has appeared at a time at least γ . If P is a program, let us consider the Π_1^1 set in the parameter x of pairs (y, z) such that y codes a wellorder w with a maximal element l and domain the natural numbers and z codes a halting computation along w on input x which halts at l . This set contains a Π_1^1 singleton (y, z) in the parameter x by Corollary 2. Then y codes a Δ_2^1 wellorder in the parameter x whose order type is the length of the computation.

As an example of a Σ_2^1 wellorder of length δ_2^1 , let $m <_{halt} n$ if P_m and P_n both halt on empty input and P_m halts before P_n , or P_m and P_n halt simultaneously and $m < n$.

3 Tree representations from computations

In this section, we construct a tree representation for an OTM semi-decidable set of reals from finite fragments of OTM computations. The tape content over an entire halting OTM computation on countable input by a program P can be viewed as an $\omega_1 \times \omega_1$ matrix filled with zeroes and ones. Every row represents the tape content at a given time. If we add a state and a head position per row, the computation is entirely captured in the resulting diagram:

¹ If the algorithm terminates in stage β , the machine halts after at most $(\omega^\omega \cdot \beta^\omega) \cdot \beta$ many steps.

		tape →														
		state	head	0	1	2	3	4	5	6	7	8	9	...	ω	...
time ↓	0	0	0	0	0	0	0	0	0	0	0	0	0	...	0	...
	1	1	1	1	0	0	0	0	0	0	0	0	0	...	0	...
	2	0	2	1	0	0	0	0	0	0	0	0	0	...	0	...
	3	1	3	1	0	1	0	0	0	0	0	0	0	...	0	...
	4	0	4	1	0	1	0	0	0	0	0	0	0	...	0	...
	5	1	5	1	0	1	0	0	0	0	0	0	0	...	0	...
	6	0	6	1	0	1	0	1	0	0	0	0	0	...	0	...
	7	1	7	1	0	1	0	1	0	0	0	0	0	...	0	...
	8	0	8	1	0	1	0	1	0	1	0	0	0	...	0	...
	9	1	9	1	0	1	0	1	0	1	0	0	0	...	0	...
	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮
ω	0	ω	1	0	1	0	1	0	1	0	1	0	...	0	...	
$\omega + 1$	1	$\omega + 1$	1	0	1	0	1	0	1	0	1	0	...	1	...	
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮

We will approximate similar diagrams by adding single bits of information. A *tape bit* $(\alpha, \beta, c, \lambda)$ will consist of:

1. a coordinate (α, β) in the $\omega_1 \times \omega_1$ matrix representing time α and tape cell β
2. the cell content $c \in \{0, 1\}$
3. a countable limit ordinal (or zero) λ – this number will be used to control the limit behavior.

Per row we also need a *machine bit* $[\alpha, s, \gamma, \lambda]$ containing the following information:

1. some time α
2. a machine state s of P
3. a head position $\gamma \in \omega_1$
4. a countable limit ordinal (or zero) λ – this number will be used to control the limit behavior.

A finite set of tape and machine bits can be coded into a countable ordinal; fix such a coding. We will now define the tree T on $\omega \times \omega_1$: A pair $(s, u) \in {}^n \omega \times {}^n \omega_1$ is in T if and only if

1. The set coded by u_j contains the bits coded by u_i for $0 \leq i \leq j < n$ and natural numbers c_i for $i < j$ deciding which bits belong to u_i . The remaining elements of the set coded by u_j are exactly the bits required by the following conditions.
2. Every u_i contains at most one machine bit for each α and at most one machine bit and for every pair of α and β .
3. For every tape bit $(0, n, c, \cdot)$ of u_i with $i \geq n$, we have that $c = s_n$, i.e. s serves as initial segment of the initial tape contents of the partial computation.
4. u_0 contains the machine bit $[0, 0, \cdot, \cdot]$ and the tape bit $(0, 0, 0, \cdot)$. Also it contains a machine bit $[\alpha, s, \gamma, \cdot]$ plus a tape bit $(\alpha, \gamma, c, \cdot)$ where P does not contain an instruction for the situation (c, s) , i.e. α is a halting time. So the beginning and the end of the partial computation are fixed.
5. As soon as we have information about a tape cell at time α , we also know the machine state and head position: If u_i contains a tape bit $(\alpha, \cdot, \cdot, \cdot)$, it also contains a machine bit $[\alpha, \cdot, \cdot, \cdot]$.
6. We always know which tape contents is read by the read-write head: If u_i contains a machine bit $[\alpha, \cdot, \gamma, \cdot]$, it contains a tape bit $[\alpha, \gamma, \cdot, \cdot]$.
7. If u_i contains a tape bit $(\alpha, \beta, c, \cdot)$, u_{i+1} contains bits immediately above and below along the time axis: Let $[\alpha, s, \gamma, \cdot]$ be the corresponding machine bit. If $\beta = \gamma$ we require u_{i+1} to contain a tape bit $(\alpha + 1, \gamma, \cdot, \cdot)$ and a machine bit $[\alpha + 1, \cdot, \cdot, \cdot]$ as required by the program P . If α is a successor, we also similarly require the tape and machine bit of the form $[\alpha - 1, \cdot, \cdot, \cdot]$ that P implies. Except for those tape bits, all the other tape cells should not change their content, so we add tape bits $(\alpha + 1, \beta, c, \cdot)$ if $\beta \neq \gamma$. Again, if α is a successor, we add such tape bits $(\alpha - 1, \beta, c, \cdot)$ for all β but the one for which we already added such a bit according to P .

8. For tape bits of limit times we have to ensure that the tape contents are inferior limits over earlier times: If λ is a limit ordinal, and $(\lambda, \beta, c, \cdot)$ is a tape bit of u_i . Suppose $c = 0$. Then there is a tape bit $(\alpha, \beta, 0, \cdot)$ with $\alpha < \lambda$ in u_{i+1} and $\alpha > \alpha'$ for all bits $(\alpha', \beta, \cdot, \cdot)$ in u_i with $\alpha' < \lambda$. If $c = 1$ then there is a tape bit $(\alpha, \beta, 1, \lambda)$ in u_{i+1} with $\alpha < \lambda$ and where α is larger than any time of a similar bit in u_i . Let α' be minimal such that u_{i+1} contains a tape bit of the form $(\alpha', \beta, 1, \lambda)$. Then every tape bit for tape cell β and time $\bar{\alpha}$ between α and λ in u_{i+1} must be of the form $(\bar{\alpha}, \beta, 1, \cdot)$.
9. We also want the machine state at limit times to be a lim inf: If λ is a limit ordinal and u_i contains a machine bit $[\lambda, s, \cdot, \cdot]$, u_{i+1} contains a machine bit $[\alpha, s, \cdot, \lambda]$ where $\alpha < \lambda$ and where α is larger than any time of a similar bit in u_i . Let α' be minimal such that u_{i+1} contains a machine bit of the form $[\alpha', s, \cdot, \lambda]$. Then every machine bit for time $\bar{\alpha}$ between α and λ in u_{i+1} must be of the form $[\bar{\alpha}, s', \cdot, \cdot]$ where $s' \geq s$.
10. We also want to make the head position at limit times a lim inf as in the definition of OTMs. If λ is a limit ordinal, then for every machine bit $[\lambda, s, \gamma, \cdot]$ of u_i one of the following conditions hold: Either there is a machine bit $[\alpha, s, \gamma, \lambda]$ in u_{i+1} with $\alpha < \lambda$ where α is larger than any time of a similar bit in u_i and for every machine bit in u_{i+1} of the form $[\alpha', s, \gamma', \cdot]$ where α' is between α and γ we have $\gamma' \geq \gamma$. Or, alternatively, u_{i+1} does not contain a bit of the form $[\alpha, s, \gamma, \lambda]$, then we require that there is a bit $[\alpha, s, \gamma', \lambda]$ in u_{i+1} that is not in u_i where $\gamma' < \gamma$ and γ' is greater or equal to any $\gamma'' < \gamma$ in any bit of u_{i+1} .

This means that every entry of the matrix given by u_i is extended both up- and downwards along the time axis in u_{i+1} while respecting the behavior of the program P and the limit rules involved in the definition of OTMs.

Let us, in the following, refer to the set of α where u_i contains a bit of the form $(\alpha, \cdot, \cdot, \cdot)$ as $\text{dom}(u_i)$. Moreover, let $\text{dom}(u)$ be the set of those α that occur in some u_i , $i \in \omega$,

Lemma 3. T projects to the set of reals semi-decided by P .

Proof. First let x be semi-decidable by P , i.e. $P(x) \downarrow$. We claim that the halting computation C implies a branch of T_x . Let $(\lambda_i)_{i \in \omega}$ be an enumeration of the limit times involved in C . Let $[\lambda_i, s_i, \gamma_i, \cdot]$ be the corresponding machine bits, and $(\lambda_i, \gamma_i, c_i, \cdot)$ the corresponding tape bits according to C , for $i \in \omega$. We can make sure that u_i contains both $[\lambda_i, s_i, \gamma_i, \cdot]$ and $(\lambda_i, \gamma_i, c_i, \cdot)$ and tape and machine bits $[\alpha, \cdot, \gamma, \cdot]$, $(\alpha, \gamma, \cdot, \cdot)$ with $\lambda_m < \alpha < \lambda_n$ for any $m < n < i$. Let us close $(u_i)_{i < \omega}$ under above rules using bits compatible with C . It is clear that for any two consecutive limits λ_k and λ_l , there is some u_i which contains bits $(\alpha, \cdot, \gamma, \cdot)$, $(\alpha, \gamma, \cdot, \cdot)$ with $\lambda_k < \alpha < \lambda_l$. Since all bits are chosen from C , the gaps between the λ_i can be filled and $(u_i)_{i < \omega}$ forms a branch in T_x .

Now let $(u_i)_{i \in \omega}$ be a branch of T_x . We need to prove that the computation C by P on input x halts. Let $(\lambda_i)_{i \in \omega}$ be an enumeration of the limits in $\text{dom}(u)$.

Claim. The ordinals in $\text{dom}(u)$ are exactly the ordinals $\lambda_j + n$ for $j, n \in \omega$.

Proof (Claim). By above rules it is clear that every ordinal of the form $\lambda_j + n$ is in $\text{dom}(u)$. Suppose that $\mu + n \in \text{dom}(u_i)$ where $\mu \neq \lambda_j$ for all $j \in \omega$. Then it follows from the rules that $\mu \in \text{dom}(u_{i+n})$, a contradiction.

The set of bits in $(u_i)_{i \in \omega}$ induce a partial matrix U of the type pictured above. We call a submatrix *according to P* , if the machine state, head position, and tape contents change only as dictated by P .

Claim. For $\lambda \in (\lambda_i)_{i \in \omega}$ the submatrix of U induced by the rows $\lambda + n$ for all $n \in \omega$ is according to P .

Proof (Claim). Let $n \in \omega$ and choose i minimal such that $\exists m \lambda + m \in \text{dom}(u_i)$. The rules dictate that u_{i+n-m} contains unique machine bits for all rows $\lambda + m, \lambda + m + 1, \dots, \lambda + n$ and also for all rows between $\min\{\lambda, \lambda + m - n\}$ and $\lambda + m$. Those machine bits and also the tape contents covered by bits present in u_i are changed only according to P . Of course, new tape cells might have been introduced by tape bits in u_j , $j > i$. But for any such given tape cell β , its content is kept constant except for actions of P .

It remains to show that at limit times, machine state, head positions, and tape contents are inferior limits.

Claim. Let λ be in $(\lambda_i)_{i \in \omega}$. Let $(\alpha_j)_{j < \nu}$ be an increasing enumeration of $\text{dom}(u) \cap \lambda$. Then:

- (i) For every tape bit $(\lambda, \beta, c, \cdot)$, c is the inferior limit over the d in tape bits of the form $(\alpha_j, \beta, d, \cdot)$ in $\bigcup_{i \in \omega} u_i$.
- (ii) For every machine bit $(\lambda, s, \cdot, \cdot)$, s is the inferior limit over the r in machine bits of the form $(\alpha_j, r, \cdot, \cdot)$ in $\bigcup_{i \in \omega} u_i$.
- (iii) For every machine bit $(\lambda, s, \gamma, \cdot)$, γ is the inferior limit over the δ in machine bits of the form $(\alpha_j, s, \delta, \cdot)$ in $\bigcup_{i \in \omega} u_i$.

Proof (Claim).

- (i) Choose u_i such that $(\lambda, \beta, c, \cdot)$ is in u_i . Let $((\alpha_k, \beta, d_k, \cdot))_{k \in \mu}$ be an increasing (in α_k) enumeration of the tape bits in $(u_j)_{i < j < \omega}$ where $\alpha_j < \lambda$. First consider $c = 0$. The rules imply that $(d_k)_{k \in \mu}$ contains an unbounded sequence of 0s, hence c is in fact the inferior limit. Now suppose $c = 1$. In u_{i+1} a tape bit of the form $(\alpha, \beta, 1, \lambda)$ is added and all d_k where $\alpha_k > \alpha$ are ≥ 1 .
- (ii) Choose u_i such that $(\lambda, s, \cdot, \cdot)$ is in u_i . Let $((\alpha_k, s_k, \cdot, \cdot))_{k \in \mu}$ be an increasing (in α_k) enumeration of the machine bits in $(u_j)_{i < j < \omega}$ where $\alpha_j < \lambda$. In u_{i+1} a machine bit of the form $(\alpha, s, \cdot, \lambda)$ is added, where α is greater than any time of a similar bit in u_{i+1} . Indeed in every u_j where $j > i$ such a bit is added, so $(s_k)_{k < \mu}$ contains s unboundedly often. Also, the rules imply that every $s_k \geq s$ for all $\alpha_k \geq \alpha$.
- (iii) Choose u_i such that $(\lambda, s, \gamma, \cdot)$ is in u_i . Let $((\alpha_k, s, \gamma_k, \cdot))_{k \in \mu}$ be an increasing (in α_k) enumeration of the machine bits in $(u_j)_{i < j < \omega}$ where $\alpha_j < \lambda$ (note that we only consider bits with machine state s). *Case 1.* In u_{i+1} a machine bit of the form $(\alpha, s, \gamma, \lambda)$ is added, where α is greater than any time of a similar bit in u_{i+1} . Indeed in every u_j where $j > i$ such a bit is added, so $(\gamma_k)_{k < \mu}$ contains γ unboundedly often. Also, the rules imply that every $\gamma_k \geq \gamma$ for all $\alpha_k \geq \alpha$. *Case 2.* No such bit is added in any u_j , $i < j$. Then by the rules, $(\gamma_k)_{k \in \mu}$ is strictly increasing below γ . Note that by the rules there is no head position in u that is between $\sup_{k \in \mu}(\gamma_k)$ and γ . So even if $\liminf_{k < \mu}(\gamma_k) < \gamma$, the partial computation behaves as if γ was indeed the lim inf.

Let us order the set of tape bits and the set of machine bits lexicographically. If $u = \{u_0 < \dots < u_m\}$ and $v = \{v_0 < \dots < v_n\}$ are (codes for) finite sets of tape bits or finite sets of machine bits, let $u <_{lex} v$ if u is an initial segment of v or $u_i <_{lex} v_i$ for the least i with $u_i \neq v_i$. Suppose u_n, v_n are codes for finite sets as in the definition of the tree T of partial computations. Then we can decode sequences $u = \{u_0 < \dots < u_n\}$ and $\{v_0 < \dots < v_n\}$ from u_n and v_n such that u_{i+1} contains exactly the bits necessary to extend u_i for all $i < n$, and similarly for v_i . Let us define a wellordering of such codes by $u_n <_{code} v_n$ if u is an initial segment of v or $u_i <_{lex} v_i$ for the least i with $u_i \neq v_i$.

Lemma 4. T has pointwise leftmost branches with respect to $<_{code}$.

Proof. We claim that for every input x on which the computation halts, the tree T_x has a branch b so that $b_n <_{code} c_n$ for every branch c of T_x and for every n . Let us consider the computation with input x . Let $b_0 = \{[0, 0, 0, \cdot], (0, 0, 0, \cdot), [\alpha, s, \gamma, \cdot], (\alpha, \gamma, c, \cdot)\}$, where α is the halting time, s is the machine state at time α , γ is the head position at time α , and c is the content of cell γ at time α . Let b_{n+1} be the \leq_{lex} -least extension of b_n which describes a fragment of the computation as the definition of T . Suppose towards a contradiction that c is a branch in T_x and n is minimal with $c_n <_{code} b_n$. We can decode sequences $u = \{b_0 < \dots < b_n\}$ and $v = \{c_0 < \dots < c_n\}$ from b_n and c_n . Then $b_i <_{code} c_i$ for all $i < n$ by minimality and hence $b_i <_{lex} c_i$. Since $c_n <_{code} b_n$, $b_i = c_i$ for all $i < n$. This contradicts the choice of b_n .

In particular, the tree induces a Σ_2^1 scale on the set semi-decided by P .

A natural question is whether there is a tree T projecting to a Σ_2^1 universal set A such that T_x has a unique infinite branch for every $x \in A$. Let us argue that the existence of such a tree is not provable in ZF. Assuming the existence of such a tree, we can easily convert it into a tree S with the property that there is a unique $b \in S_x$ for every $x \in A$ and $b_x \neq b_y$ for all $x \neq y$ by coding the first coordinate into the second. Since for each $\alpha < \omega_1$ the projection of S restricted to ordinals below α is an injective image of a closed set and hence Borel, there is an n such that the set B of values of $b_x(n)$ for $x \in A$ is unbounded in ω_1 . Let us choose the leftmost branch (x_α, b_α) in S with $b_\alpha(n) = \alpha$ for each $\alpha \in B$. We have defined an uncountable sequence $(x_\alpha : \alpha \in B)$ of distinct reals. However, there is no such sequence in the symmetric forcing extension for the collapse $Col(\omega, < \kappa)$ below an inaccessible cardinal κ .

The tree representation allows us to generalize the results in section 2 to sets of reals semi-decided by ordinal machines with upper bounds on the halting times.

Definition 2. *Suppose f is a function from the reals to the ordinals. We call f superadditive if $f(x) \leq f(\langle x, y \rangle)$ for all reals x and y . Let us call f admissible if it is superadditive and $f(x)$ is x -admissible for all reals x .*

In fact, we consider only additive Turing invariant functions.

Definition 3. *Suppose f is superadditive. Let us say that a set of reals A is f -semi-decidable or Γ_f if there is a OTM program P semi-deciding A such that P halts before time $f(x)$ on input x if it halts at all.*

The classes Γ_f for admissible f with values strictly above ω range from Π_1^1 to Σ_2^1 .

Lemma 5. *Let $f(x) = \omega_1^x$ and $g(x) = \delta_2^1(x)$ (see section 2). Then the Π_1^1 sets are exactly the f -semi-decidable sets and the Σ_2^1 sets are exactly the g -semi-decidable sets.*

Proof. Suppose that A is f -semi-decidable and x is a real. Then $x \in A$ if and only if in every countable model of KP, there is a halting computation with input x . Suppose A is Π_1^1 and $x \in A$ if and only if T_x is wellfounded. Then $\text{rank}(T_x) < \omega_1^x$ and hence the algorithm searching for a branch in the Shoenfield tree halts before ω_1^x . The statement for Σ_2^1 sets follows from Corollary 6.

Corollary 7. *Suppose f is superadditive. Then every Γ_f set has a Γ_f norm.*

Proof. Suppose a set in Γ_f is semi-decidable by a program P with halting time bounded by f . Let $\phi(x)$ be the halting time of P on input x . The superadditivity of f implies that ϕ is a Γ_f -norm as in the proof of Corollary 5.

Corollary 8. *Suppose f is admissible. Then every Γ_f binary relation has a Γ_f uniformization.*

Proof. Suppose a relation in Γ_f is semi-decidable by a program P with halting time bounded by f . We apply the algorithm for searching through the Shoenfield tree to the tree of partial computations. Let us consider the algorithm Q which on input (x, y) searches for a real z and a branch in the tree of halting computations of P with input (x, z) . The algorithm will find the lexicographically least such pair, if there is any. In this case the computation halts before $\alpha = f(\langle x, y \rangle)$, since α is admissible and hence the tree of partial computations of P with input $\langle x, y \rangle$ has a branch in $L_\alpha[x, y]$. If $y = z$ we let Q halt and diverge otherwise. Notice that for any real x in the domain of the relation there is a lexicographically least pair consisting of a real $g(x)$ and a branch through the tree of partial computations on input $(x, g(x))$. Hence for any x in the domain there is a real z with $Q(x, z) \downarrow$. Since Q diverges for all inputs (x, z) with $z \neq g(x)$, we have found a uniformization.

4 Nondeterministic ordinal machines, oracles, and jumps

In [6, Definition 1] the *programs* that steer the computations of OTMs are defined with the following condition: If the machine is currently in state s and the machine's read-write head currently reads symbol c , then the program contains at most one command for that situation. This way, when Koepke defines the *ordinal computation* by a program P , he can refer to the unique command in a given situation. Instead, for the present section, we shall drop the above restriction on programs and instead define ordinal computations in a way that, in successor steps, the lexicographically least instruction (if there is one that suits the current situation) is chosen to determine the next machine step. This allows us to define *non-deterministic* ordinal computations as follows.

Definition 4. *Given program P and an input (i.e. an initial tape configuration), the non-deterministic ordinal Turing computation (NOTM computation) by P is defined like the ordinal computation by P ([6, Definition 2]), except that in successor steps any suitable command may define the machine's next step.*

NOTM computations may be used to define sets of reals.

Definition 5. *A set of reals $A \subseteq {}^\omega\omega$ is NOTM semi-decidable if there is a program P such that*

$$x \in A \leftrightarrow \text{there is a halting NOTM computation by } P \text{ on input } x$$

By a Mostowski collapse argument, we obtain for every such $x \in A$ a countable halting NOTM computation by P on input x . As in the classical case, given a coding of the “choices” that a NOTM computation makes, NOTM decidability can be verified deterministically.

Lemma 6. *There is a program Q such that for every program P and every real input x , there is a real z such that the OTM computation by Q on inputs P , x , and z halts if and only if the NOTM computation by P on input x halts.*

Proof. Let us define z to code two reals z_1 and z_2 . Let z_1 code a well-order on ω of order type the (countable) length of the NOTM computation by P on input x . Let z_2 be such that in machine step $\text{otp}_{z_1}(i)$, the OTM computation by P on input x selects the $z_2(i)$ -th least command P contains for that situation. Note that both otp and $\text{otp}_{z_1}^{-1}$ are OTM computable functions. Now the program Q is essentially a universal OTM which selects the $z_2(i)$ -th command in P in the $\text{otp}_{z_1}(i)$ -th simulation step.

An immediate question is whether NOTMs compute more sets of reals than OTMs.

Proposition 1. *Every NOTM computable set of reals is already OTM computable.*

Proof. Let $A \subseteq {}^\omega\omega$ and suppose that Q is the program from Proposition 6. By Proposition 6, A is NOTM semi-decidable if and only if there is a program P so that for every input x there is a real z such that the OTM computation by Q on inputs P , x , and z halts. Since this is a Σ_2^1 statement, A is Σ_2^1 and hence OTM semi-decidable.

The approach of trying out every coding of choices one after the other could fail if for a given x every certificate z was non-constructible. Let us search for a certificate via the tree of partial computations; this can alternatively be done by applying Shoenfield absoluteness and searching through L , using the OTM computable recursive truth predicate from [6].

Lemma 7. *Given a program P and an element (s, t) of the full tree on $\omega \times \omega_1$, we can OTM decide the question whether or not (s, t) is an element of the tree of partial computations according to P .*

Proof. We first have the OTM check whether t is of the correct type. If yes, we can easily check the finitely many conditions if t is a partial computation by P on some input that is compatible with s .

With the preceding lemma, we can use a variant of Algorithm 2 to find branches in the tree of partial computations. Since propositions 1 and 2 hold also for our algorithm operating on the tree of partial computations, we get:

Proposition 2. *If A is NOTM semi-decidable by the program P , then, given x as an input, the algorithm will find a real $z \in {}^\omega\omega$ such that the OTM computation by Q on inputs P , x , and z if $x \in A$ and diverges otherwise.*

Proof. If x is in A , there is a z in L such that $Q_{\text{OTM}}(P, x, z) \downarrow$. An argument analogous to propositions 1 and 2 shows that given a real x , the algorithm will find a branch of the form (x, c) in the tree T of partial computations by P , if any exists. From c the desired z can be easily decoded.

Let us now consider ordinal machines with a set of reals as oracle as in [1]. In a query state in a computation, the program asks whether the sequence on the initial segment of length ω of the tape is an element of the set. Let us write $P^A(x)$ for the OTM computation by the program P with oracle A on input x . Let us also fix a computable enumeration $(P_n \mid n \in \omega)$ of all programs.

Definition 6. *The halting problem relative to a set of reals A or jump of A is defined as $A^\blacktriangledown = \{(n, x) \mid P_n^A(x) \downarrow\}$.*

The halting problem 0^\blacktriangledown is a Σ_2^1 set, in fact we have

Proposition 3. *The halting problem 0^\blacktriangledown is Σ_2^1 universal. If $n \geq 1$ and $V = L$, then the iterated jump $0^{\blacktriangledown n}$ is Σ_{n+1}^1 universal.*

Proof. Every halting computation with countable input halts at a countable time. Hence $(m, x) \in 0^{\blacktriangledown n}$ is described by a Σ_{n+1}^1 formula stating the existence of a wellorder w on the natural numbers with largest element l together with a sequence indexed by w , coding a computation of P_m with input x and oracle $0^{\blacktriangledown(n-1)}$ halting at l . Let us suppose that A is defined by the formula $\exists x \varphi(x, y)$, where φ is Π_n^1 . We consider a program searching through L for a witness for φ as in [6], using the oracle $0^{\blacktriangledown(n-1)}$ to verify $\varphi(x)$ for reals x . This program identifies A as a section of $0^{\blacktriangledown n}$.

In particular, the Σ_{n+1}^1 sets are exactly the OTM semi-decidable sets in a Σ_n^1 oracle for $n \geq 1$, if $V = L$. Let us show that this remains true when $\kappa \geq \omega_1$ many Cohen reals are added to L by the forcing $Add(\omega, \kappa)$.

Lemma 8. *Suppose that $V = L[G]$, where G is $Add(\omega, \kappa)$ -generic over L , and $\kappa \geq \omega_1$. Then $0^{\blacktriangledown n}$ is Σ_{n+1}^1 universal for all $n \geq 1$.*

Proof. Suppose that x is a real in $L[G]$. There are an $Add(\omega, 1)$ -generic filter g_0 with $L[x] = L[g_0]$ and an $Add(\omega, \kappa)$ -generic filter g_1 over $L[g_0]$ with $L[G] = L[g_0][g_1]$. Let us consider a formula $\exists y \varphi(x, y)$ where φ is Π_2^1 . Then $L[G] \models \exists y \varphi(x, y)$ holds if and only if $\exists \sigma \in N \Vdash_{Add(\omega, 1)}^{L[g_0]} \varphi(y, \sigma)$ holds, where N is the set of nice $Add(\omega, 1)$ -names for reals in $L[g_0]$. Since nice names for reals are coded by reals, this is a Σ_3^1 statement in $L[g_0]$. In a similar fashion, we can express any Σ_{n+1}^1 statement about x in $L[G]$ by a Σ_{n+1}^1 statement in $L[g_0]$ for all $n \geq 1$, uniformly in x . Every such set is a section of $0^{\blacktriangledown n}$ by the argument in the previous proposition.

It is also consistent with ZFC that the iterated jumps have a lower complexity. Note that the assumption that $\omega_1^{L[x]} < \omega_1$ for every real x may be obtained by forcing with the Levy collapse $Col(\omega, < \kappa)$ below an inaccessible cardinal κ .

Lemma 9. *Suppose that $\omega_1^{L[x]} < \omega_1$ for every real x . Then $0^{\blacktriangledown n}$ is a Δ_3^1 set for all $n \geq 1$.*

Proof. Let us consider the Δ_3^1 set A of pairs (x, y) where y codes $L_\gamma[x]$ and γ is the least x -admissible ordinal above $\omega_1^{L[x]}$. We compute the truth value of $x \in 0^{\blacktriangledown n}$ in $L_\gamma[x]$, where γ is the least x -admissible ordinal above $\omega_1^{L[x]}$, using an algorithm which has access to n distinct tapes of length $\omega_1^{L[x]} + 1$. The original program runs on tape n . Whenever the oracle $0^{\blacktriangledown i}$ is called on tape i , the oracle is computed on tape $i - 1$ by a subroutine of length $\omega_1^{L[x]} + 1$. The Δ_3^1 description of A provides us with a Δ_3^1 description of the set of pairs (x, n) with $x \in 0^{\blacktriangledown n}$.

The two lemmas together show that the complexity of $0^{\blacktriangledown n}$ for $n \geq 2$ is independent of the size of the continuum.

5 Further questions

A set of reals is Σ_2^1 in a countable ordinal α if there is a Σ_2^1 formula $\varphi(x, y)$ such that for all reals y coding α and all reals x , $x \in A$ if and only if $\varphi(x, y)$ holds, i.e. the Σ_2^1 definition is independent of the coding of α . We leave open whether the sets of reals with a Σ_2^1 definition in an ordinal α , evaluated in $V^{Col(\omega, \alpha)}$, are exactly the OTM semi-decidable sets of reals with input α . If so, this might be used for a proof of uniformization for these classes.

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