A rough outline of the proof of the K-theoretic Farrell-Jones conjecture for CAT(-1) groups

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- **1** The natural inclusions induce isomorphisms $\bigoplus_i K_*(\mathcal{A}_i) \cong K_*(\bigoplus_i \mathcal{A}_i)$. This is also called continuity of algebraic K-theory.

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- **3** every map $g: U \to A$ to an object $A \in \mathcal{A}$ factors through one of the compositions;
- For $U, V \in \mathcal{U}$ the posets $I_{U \oplus V}$ and $I_U \times I_V$ are equivalent (i.e. cofinal in each other as subposets of all decompositions).

Karoubi-filtrations : quotients

Now we can define a quotient category \mathcal{U}/\mathcal{A} whose objects are the same as the objects from \mathcal{U} , but whose morphism sets $\operatorname{Hom}_{\mathcal{U}/\mathcal{A}}(U,U')$ is the quotient of $\operatorname{Hom}_{\mathcal{U}}(U,U')$ by the subgroup of all morphisms that factor through some $A \in \mathcal{A}$,

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Exercise

Show that equivalent choices of decompositions give the same quotient category.



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If all A_i are equal, then we could also allow morphisms that mix the degree. This will be a very important example.

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- let for a subset S of \mathbb{N} and an object $U = (B_i)_{i \in \mathbb{N}}$ the restriction $U|_S$ be the object with $(U|_S)_i = U_i$ for $i \in S$ and $(U|_S)_i = 0$ otherwise.





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Remark

Thus $K_n\mathcal{B}=K_{n+1}(\mathcal{U}/\mathcal{B})$ and hence we could use these constructions to define negative K-theory in terms of K_0 of other categories.

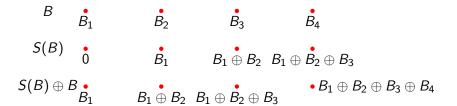
Pictures of the swindle

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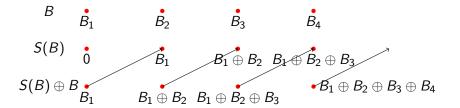
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The full subcategories of objects with compact support are the same. Thus the left arrow is an isomorphism. The middle arrow is an isomorphism since both categories are flasque. Thus the third arrow is also an isomorphism. This is not obvious! The underlying functor is not a equivalence of additive categories.

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- An object in C(X; A) is a collection of objects $(A_x)_{x \in X}$ of objects of A such that its *support* $\{x \mid A_x \neq 0\}$ is locally finite.
- A morphism $\varphi: (A_x)_{x \in X} \to (B_y)_{y \in Y}$ is a collection of morphisms $\varphi_{x,y}: A_x \to B_y$ such that its *support* $\{(x,y) \mid \varphi_{x,y} \neq 0\}$ is row and column finite.



Figure: Sketch of a morphism

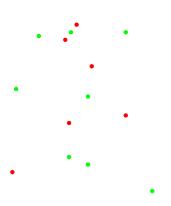


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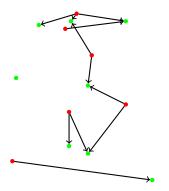


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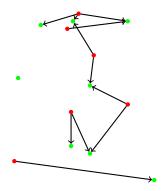


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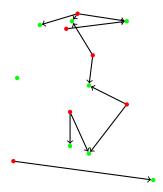


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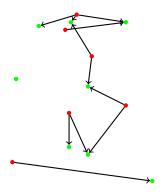


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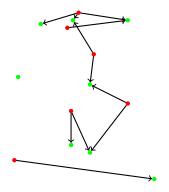


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- Object control conditions can be pulled back. The intersection of two object control conditions $\mathcal{F}, \mathcal{F}'$ consists of all subsets of the form $F \cap F'$ for some $F \in \mathcal{F}, F' \in \mathcal{F}'$.
- Now we can look at the subcategory of $\mathcal{C}(X, \mathcal{A})$ that consists of all objects such that their support is contained in a subset of our object condition.

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- An example of such a morphism control condition is the metric control condition \mathcal{E}_d . Morphism control conditions are also known as coarse structures. Pull backs and intersections of morphism control conditions work the same way.
- Now we can look at the subcategory $C(X, \mathcal{E}, \mathcal{F}; \mathcal{A})$ of $C(X; \mathcal{A})$ that consists of all objects such that their support is contained in a set in our object control condition \mathcal{F} and of all morphisms whose support is contained in a subset of our morphism control condition \mathcal{E} .

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$$(g^*C)_x := g^*C_{gx}; \qquad (g^*\varphi)_{x,y} := (g^*\varphi_{gx,gy}).$$

Let $\mathcal{C}(X,\mathcal{E},\mathcal{F};\mathcal{A})^G$ denote the fixed point category, i.e. the subcategory with $A_X=g^*A_{g_X}$ for all $x\in X$ and $(g^*\varphi)_{x,y}:=(g^*\varphi_{g_X,g_Y}).$



•1

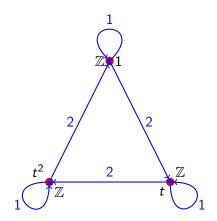
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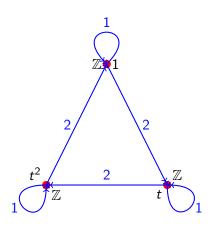
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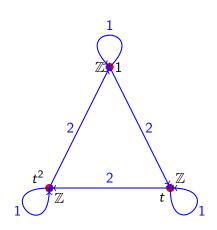




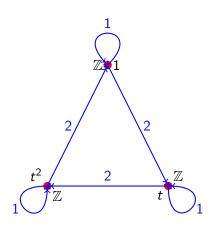




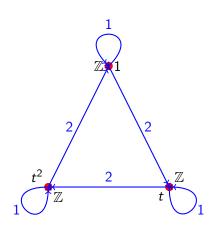
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- E is symmetric and invariant under the diagonal G-action;
- **③** For every $x \in X$ and any G-invariant neighborhood U of (x, ∞) in $X \times [1, \infty)$ there is a (smaller) G-invariant neighborhood V such that

$$(U^c \times V) \cap E = \emptyset \wedge (V^c \times U) \cap E = \emptyset.$$



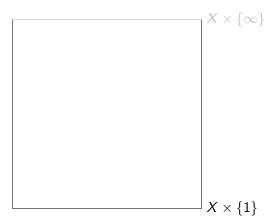


Figure: A morphism satisfying the continuous control condition

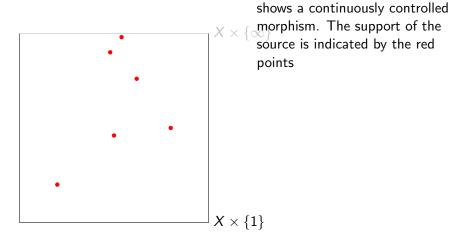
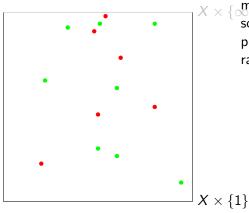


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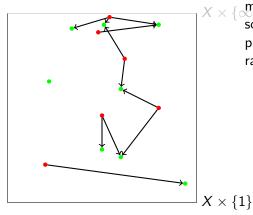


The figure on the left hand side



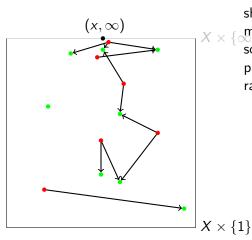
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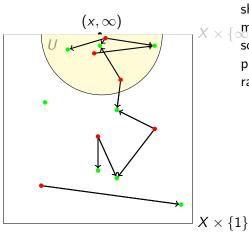
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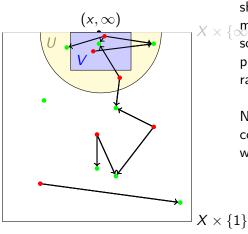
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The figure on the left hand side shows a continuously controlled X × {morphism. The support of the source is indicated by the red points and the support of the range by the green points.

Note that there is no arrow connecting a point inside V with a point outside U.

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A G-homology theory is a covariant functor H_* from the category of G-CW-pairs to the category of \mathbb{Z} -graded abelian groups satisfying:

• Excision,.i.e. for a G-CW-pair (X,A) and a G-subcomplex $B \subset A^{\circ}$ we have $H_*(X \setminus B, A \setminus B) \cong H_*(X,A)$ induced by the inclusion;

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- G-homotopy invariance;
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- Continuity, i.e. $H_*(\coprod_i X_i) \cong \bigoplus_i H_*(X_i)$.

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$$\mathcal{C}^{G}(G\times Y\times [1,\infty), p_{Y\times [1,\infty)}^{-1}(\mathcal{E}_{G-cc}^{Y})\cap p_{G}^{-1}(\mathcal{E}_{d_{G}}^{G}), p_{G\times Y}^{-1}(\mathcal{F}_{G-c}^{G\times Y}); \mathcal{A})^{\infty}.$$

Let us first examine, what happens for a homogeneous space G/H.

• Since $G \times G/H$ is discrete, we can consider by cocompactness the (equivalent) subcategory consisting of all objects, whose support lies above the orbit of $(1, H) \in G \times G/H$.

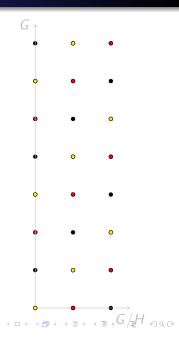
- Since $G \times G/H$ is discrete, we can consider by cocompactness the (equivalent) subcategory consisting of all objects, whose support lies above the orbit of $(1, H) \in G \times G/H$. This subcategory could also be written as $\mathcal{C}^G(G; \ldots)$ where we pull back the control conditions.
- We can simplify the continuous control condition. For a given point (gH, ∞) we can choose U of the form $\{gH\} \times [C, \infty)$.

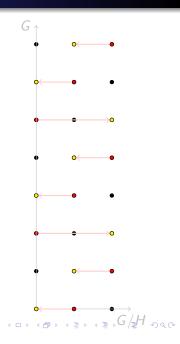
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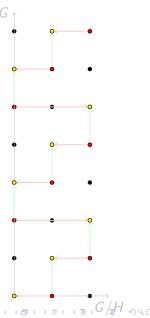
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- We can simplify the continuous control condition. For a given point (gH, ∞) we can choose U of the form $\{gH\} \times [C, \infty)$. The resulting V is WLOG also of the form $\{gH\} \times [C', \infty)$. Thus for any point gH we can find a bound C'.
- By G-equivariance we can even assume that there is a uniform bound C' such that all arrows $\varphi_{(g,gH,t),(g',g'H,t')}$ that start or end above C' have gH = g'H.

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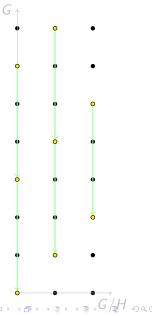
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- Now we have simplified the situation as far as possible; if we assume that A was the category of f.g., free R-modules, then this category is equivalent to the category of f.g. free RH-modules, i.e.

$$K_{*+1}(\mathcal{D}^{\mathsf{G}}(\mathsf{G}/\mathsf{H};\mathcal{A}))=K_{*}^{\mathsf{alg}}(\mathsf{RH}).$$



After moving the support to one orbit the G-equivariant control condition ensures that nonzero morphisms $\varphi_{(g,gH,t),(g'g,g'gH,t')}$ can only appear for $g' \in H$ for t,t' large.



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In order to verify the Eilenberg-Steenrod axioms, we should first define a relative version. Recall that the inclusion of $\mathcal{C}(\{0\};\mathcal{A})$ into $\mathcal{C}(\mathbb{N};\mathcal{A})$ is not a Karoubi-filtration; we have to take all objects isomorphic to an object from $\mathcal{C}(\{0\};\mathcal{A})$. Let (Y,Z) be a G-CW-pair. The same happens for $\mathcal{D}^G(Z;\mathcal{A}) \to \mathcal{D}^G(Y;\mathcal{A})$. Let $\mathcal{D}^G(Y,Z;\mathcal{A})$ denote the quotient.

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Thus we have a long exact sequence of a pair.

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Exercise

Show that this functor is a equivalence.

The crucial idea is that the continuous control ensures that if we fix a morphism in $\mathcal{D}^G(Y,B)$ and go far enough in the $[1,\infty)$ -direction, any arrow starting in A will end in B.

• We first claim that it suffices to show that both inclusions $i_0: X \to X \times \{0\} \subset X \times [0,1]$ and i_1 induce isomorphisms $K_*(\mathcal{D}^G(X)) \to K_*(\mathcal{D}^G(X \times [0,1]))$.

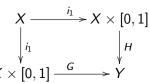
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- Given a homotopy $H: X \times [0,1] \to Y$ between f,g and let $F,G: X \times [0,1] \to Y$ denote the maps $(x,t) \mapsto f(x)$ resp. g(x).

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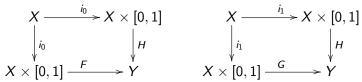
$$X \xrightarrow{i_0} X \times [0,1] \qquad X \xrightarrow{i_1} X \times [0,1]$$

$$\downarrow_{i_0} \qquad \downarrow_{H} \qquad \qquad \downarrow_{i_1} \qquad \downarrow_{H}$$

$$X \times [0,1] \xrightarrow{F} Y \qquad X \times [0,1] \xrightarrow{G} Y$$

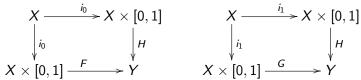


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- After applying $K_*(\mathcal{D}^G(-))$ the maps i_0 and i_1 turn into isomorphisms and thus F, H, G induce the same maps.
- $f_* = (i_0 \circ F)_* = (i_0 \circ G)_* = g_*$ and thus homotopy invariance follows.



We have to show that $\mathcal{D}^G(X) \to \mathcal{D}^G(X \times [0,1])$ is an isomorphism. We can view the left category as a full subcategory of the right category and after fattening (replacing it by the subcategory of all objects isomorphic to something on the left) we obtain a Karoubi-filtration.

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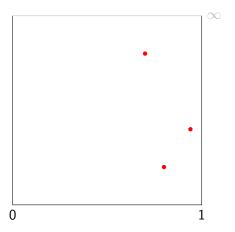


Figure: red: A, green: S(A), both: $A \oplus S(A)$, black: $S(A) \oplus A \rightarrow S(A)$, blue: $S(A) \rightarrow S(A) \oplus A$

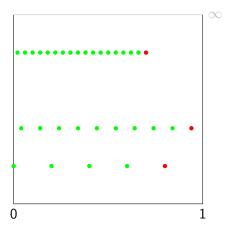


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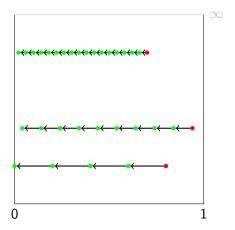
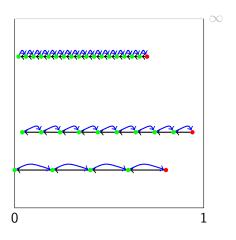


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Making the steps arbitrarily small for $h \to \infty$ we obtain equivariant continuous control. One composition is the identity, the other one is identity everywhere except on the leftmost dots.

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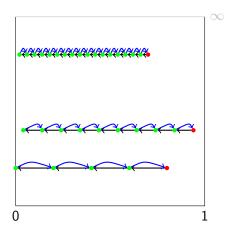


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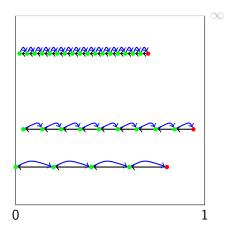


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Continuity

It follows immediately from the definition that $\mathcal{D}^G(\coprod_i X_i) \cong \bigoplus_i \mathcal{D}^G(X_i)$ as additive categories.

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Identifying the assembly map

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Lemma

 $\mathcal{O}^{G}(*; A)$ is flasque. Hence its K-theory vanishes.

Proof of the lemma

The continuous control condition is an empty condition for X = pt. For this reason the naive Eilenberg swindle given by

$$((g,pt,t),k)\mapsto (g,pt,t+k)$$

works.

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Thus the five lemma implies that the middle map is an isomorphism everywhere if and only if $K_*(\mathcal{O}^G(X); \mathcal{A})$ vanishes.

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For a sequence (Z_n, d_n) of metric spaces we can consider the product category

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$$\mathcal{O}^{G}(X,(Z_{n},d_{n})_{n\in\mathbb{N}};\mathcal{A})$$

denote the IIuf subcategory consisting of those morphisms that admit a uniform bound α .



Functoriality in Z

A sequence of maps $f_n: Z_n \to Z'_n$ induces a functor

$$\mathcal{O}^G(X,(Z_n,d_n)_{n\in\mathbb{N}};\mathcal{A})\to\mathcal{O}^G(X,(Z_n',d_n')_{n\in\mathbb{N}};\mathcal{A}),$$

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if for every α there is a $\beta(\alpha)$ such that $d_n(z_n, z_n') < \alpha \Rightarrow d'_n(f_n(z_n), f_n(z_n')) < \beta(\alpha)$.

The diagram

$$\bigoplus_{n} \mathcal{O}^{G}(E, G \times |\mathcal{U}(n)|, d_{1})$$

$$\downarrow^{(3)}$$

$$\mathcal{O}^{G}(E, (G \times \overline{X}, d_{C(n)}))_{n \in \mathbb{N}}) \xrightarrow{(2)} \mathcal{O}^{G}(E, (G \times |\mathcal{U}(n)|, d_{n}^{1})_{n \in \mathbb{N}})$$

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The map (1) exists after applying K-theory and it is a section of $pr_k \circ inc$ for all k. Morally this means that (1) is a kind of a diagonal embedding.

The diagram: Step 3

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The inclusion (3) is an equivalence on K-theory for a sequence $|\mathcal{U}(n)|$ of simplicial complexes of dimension at most N (independent of n) and metrics on $G \times |\mathcal{U}(n)|$ with certain properties. This is the crucial step!

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Now we need maps $F_{\mathcal{U}(n)}$ to simplicial complexes. Given a locally finite open cover \mathcal{U} of a metric space Z, we obtain a continuous (with I^1 -topology) map

$$F_{\mathcal{U}}: Z \to |\mathcal{U}(n)|$$
 $z \mapsto [[\sum_{U \in \mathcal{U}, z \in U} d(z, U^c)U]].$

The conditions above on the functoriality in the sequence of open covers give rise to certain conditions on those covers.

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Let (Y_n, d_n^{∞}) be the disjoint union of the *N*-simplices where the distance is the *n*-times the l^1 -distance, if the two points lie in the same simplex and infinite otherwise.



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Proof

by Induction on N. The attaching of N-simplices gives a diagram

$$\begin{split} \mathcal{L}((\partial Y_n, d_n^\infty)_{n \in \mathbb{N}})^{>\oplus} & \longrightarrow \mathcal{L}((Y_n, d_n^\infty)_{n \in \mathbb{N}})^{>\oplus} \\ & \downarrow & \downarrow \\ \mathcal{L}((X_n^{N-1}, d_n)_{n \in \mathbb{N}})^{>\oplus} & \longrightarrow \mathcal{L}((X_n, d_n)_{n \in \mathbb{N}})^{>\oplus}, \end{split}$$

After fattening both categories on the left (as before) both rows turn into Karoubi-filtrations. The induced map on the quotient will be an equivalence (\blacksquare_1) .

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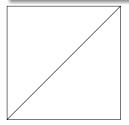
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Exercise

For any two points x, y in different N-simplices of a simplicial complex there is a point z in an n-1-simplex with $d^1(x,z) \le 2d^1(x,y)$ (and thus $d^1(y,z) \le 3d^1(x,y)$).

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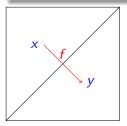
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The idea to factorize a morphism is shown in the picture above; glue the modules over y at z=z(x,y). The estimations from the lemma give the control conditions.

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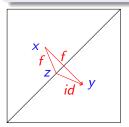
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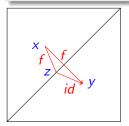
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$$H: [0,1] \times Y_n \times E \rightarrow E$$

such that

$$H_0(y, e) = e;$$
 $H_1(y, e) = i(p(y))$



Now define for every point (g, y, e, t) in $G \times Y_n \times E \times [1, \infty)$ a sequence of points

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This completes the proof of \blacksquare_2 and thus the proof that (3) is an equivalence in K-theory.



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G-covers

Let X be a G-space and \mathcal{F} be a family of subgroups of G. A G-cover of X is a collection \mathcal{U} of open sets such that:

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G-covers

Let X be a G-space and \mathcal{F} be a family of subgroups of G. A G-cover of X is a collection \mathcal{U} of open sets such that:

- For $g \in G, u \in \mathcal{U}$ we have $gU \in \mathcal{U}$;
- If $gU \cap U \neq \emptyset$, then gU = U;
- For every U we have that the subgroup $\{g \in G \mid gU = U\}$ lies in the family \mathcal{F} ;

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• The normalizers of the open sets in the cover lie in \mathcal{F} (Here $\mathcal{F}=\mathcal{VC}yc$).



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- Luckily for a CAT(-1) group all point stabilizers in \overline{X} are virtually cyclic and thus there is some hope that this approach works.
- For CAT(0)-groups there can be fixed points in \overline{X} and a lot of the diagram has to be reworked.

Definition

For a CAT(-1) space X define

$$FS(X) := \{ f : \mathbb{R} \to X \mid \exists -\infty \le a \le b \le \infty : f_{[a,b]} \text{ is a unit speed geodesic, } f_{(-\infty,a]}, f_{[b,\infty)} \text{ are constant} \}.$$

The function $d(f,f'):=\int_{\mathbb{R}}\frac{d_X(f(t),f'(t))}{2e^{|t|}}$ defines a metric on it which generates the compact open topology. A (geometric) G-action on X induces a (geometric) G-action on FS(X). Furthermore precomposition with translations gives a \mathbb{R} -action Φ on FS(X) commuting with the G action.

The evaluation map $f \mapsto f(0)$ is proper with compact, contractible fibers; Heuristically the flow space wants to mimic the unit ball bundle in the tangent bundle of a Riemannian manifold.

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\square_3 : long covers of the flow space

Theorem (Bartels-Lück-Reich)

Let G act geometrically on a CAT(-1)-space X. There is a natural number N such that for any R>0 there is an $\varepsilon>0$ and a $\mathcal{VC}yc$ cover of FS(X) of dimension at most N such that for every $f\in FS(X)$ there is an open set containing $B_{\varepsilon}(\Phi_{[-R,R]}f)$.

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The goal is now to define a map $G \times \overline{X} \to FS(X)$ such that every set of the form $\{(gh^{-1}, hx) \mid |h| \leq \beta\}$ gets mapped into one of the sausages $B_{\varepsilon}(\Phi_{[-R,R]}f)$.

Choose a basepoint $x_0 \in X$ and define a map

$$i_{x_0}: G imes \overline{X} o FS(X), \qquad i_{x_0}(g,x)(t) := egin{cases} gx_0 & t \leq 0 \\ gx & t \geq d(x,y) \ , \\ c_{gx_0,gx}(t) & ext{else} \end{cases}$$

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The key idea is now to postcompose with flowing by a large enough number T towards x.



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$$d_{FS}(\Phi_T f, \Phi_{T+r}(f')) < \varepsilon,$$

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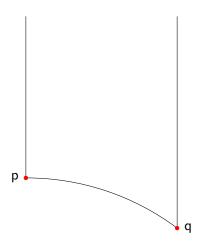
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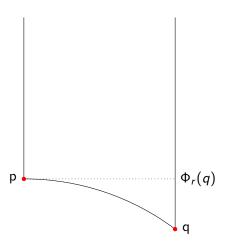
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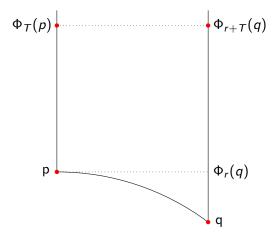
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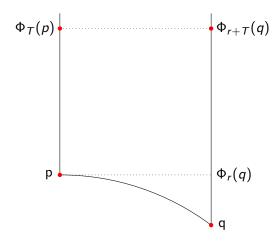
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A picture in the Poincaré half plane of a generic ideal triangle. Recall that in this model points of the same y coordinate (i.e. of with the value of the Busemann function of the point at infinity of the triangle) get arbitrarily close together if we move them upwards.

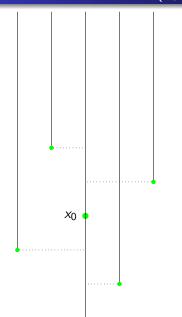
 X_0

The green dots are the set $B = \{ hx_0 \mid h \in B_{\beta}(1) \}, \text{ then }$ $i_{x_0}(\{(h^{-1}, hx) \mid h \in B_{\beta}(1)\})$ consists of those geodesics that start at some point in B at time 0 and go towards the point at infinity x. Two elements f, f' in the flow space are close, if $\sup_{t \in [-R,R]} d_X(f(t),f'(t))$ is small. Basically d(f(0), f'(0)) has the highest weight

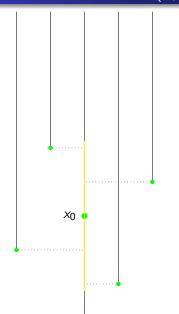


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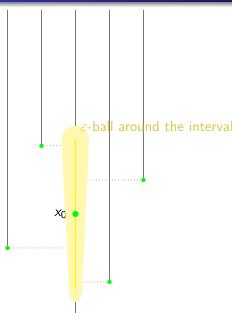
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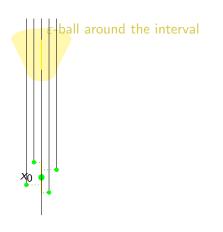
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If you let the interval flow long enough before taking the ε -neighborhood, the resulting set will be much bigger in the horizontal direction. This comes from the Poincare-halfplane model.

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The whole talk is based on the following papers:

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