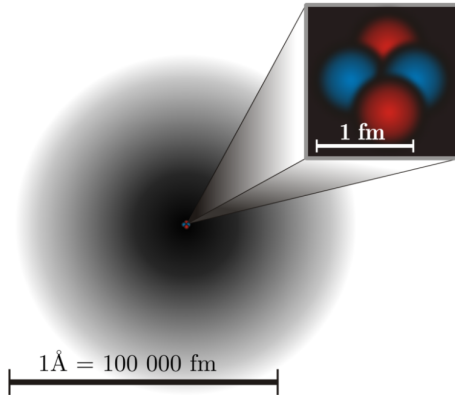


Matrices and moduli

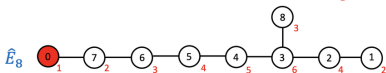
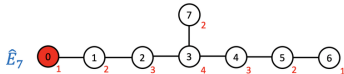
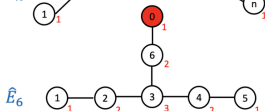
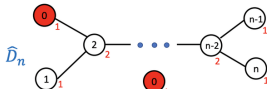
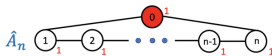
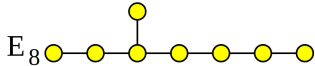
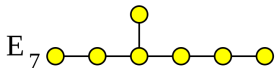
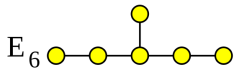
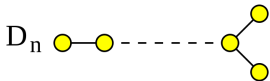
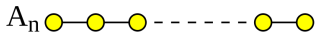
Or: Almost all = boring?

Accept **Change** what you cannot change **accept**



August 2023

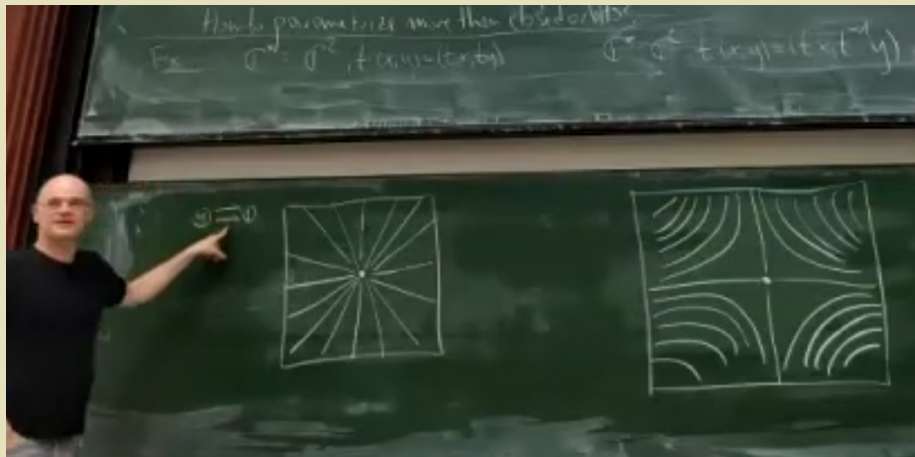
Matrix problems – the algebraic approach



- ▶ **Recall** Some matrix problems can be associated with quivers
- ▶ **Recall** Matrix problems are doable only in the finite and affine ADE types
- ▶ Otherwise, the algebraic approach is doomed to fail and classifications get **wild**

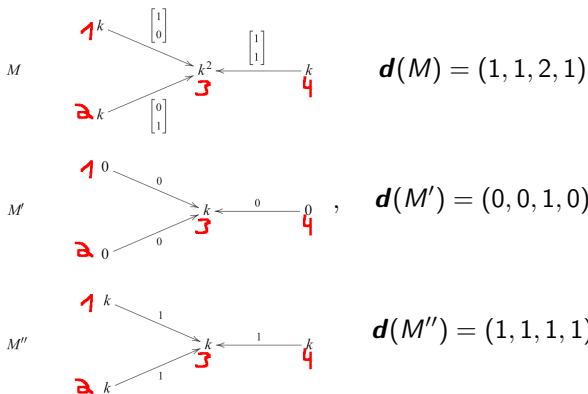
Today

A geometric approach to matrix problems
following Reinecke's Felix Klein lecture 2020 (ask Dr. google for 5 brilliant video lectures)



But first let me wrap-up the algebraic approach

Matrix problems – the algebraic approach



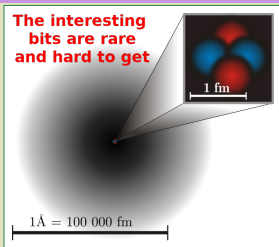
- ▶ The classification of inde. is hopeless in general
- ▶ But for almost all inde. the classification is actually pretty easy
- ▶ We will see this momentarily dimension vector d wise

General phenomena

“Really difficult”

often means

“easy almost all of the time, but hard for some cases”



I will show you now a fun example of this phenomena!

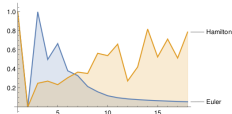
- ▶ The classical
- ▶ But for all

The example is not related to quivers but this is how I learned this stuff ;-)
and we go back to quivers afterwards

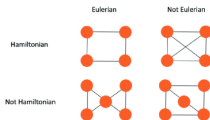
- ▶ We will see this momentarily dimension vector d wise

Matrix problems – the algebraic approach

Almost all (random) graphs are Hamiltonian; almost no (random) graph is Eulerian



- ▶ Hamiltonian = has a cycles that visits all vertices; Eulerian = has a cycles that visits all edges; looks similar, but is different:

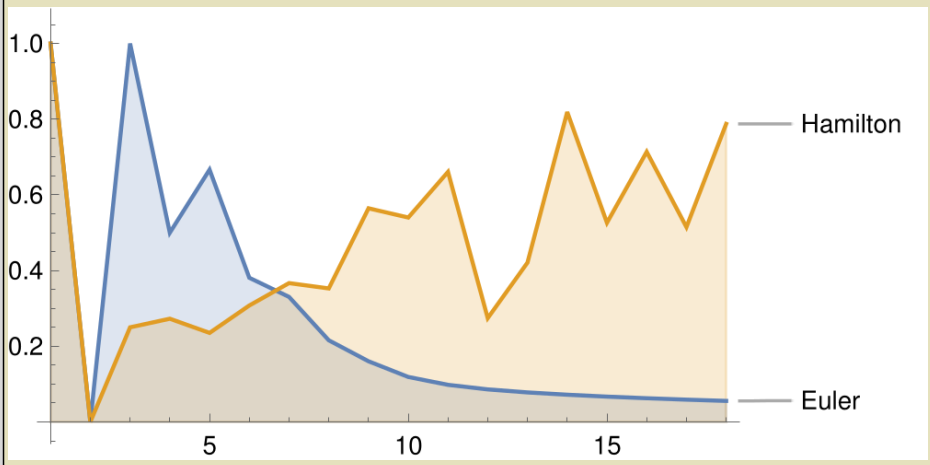


- ▶ Crucial (Almost all \neq all) and (almost no \neq no)!

- ▶ Checking whether a graph is Hamiltonian is NP complete = difficult as hell
- ▶ But for almost all graphs there are efficient algorithm to check this
- ▶ So the difficulty is very concentrated

Matrix problems – the algebraic approach

Almost all graphs are Hamiltonian:



- ▶ But for almost all graphs there are **efficient algorithm** to check this
- ▶ So the difficulty is **very concentrated**

Matrix problems – the algebraic approach

Triple Kronecker: $K^3 = \textcircled{1} \Rightarrow \textcircled{2}$

$$J_n(\lambda) = \begin{pmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \lambda & 1 \\ & & & \lambda \end{pmatrix}, \quad id_n = \begin{pmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

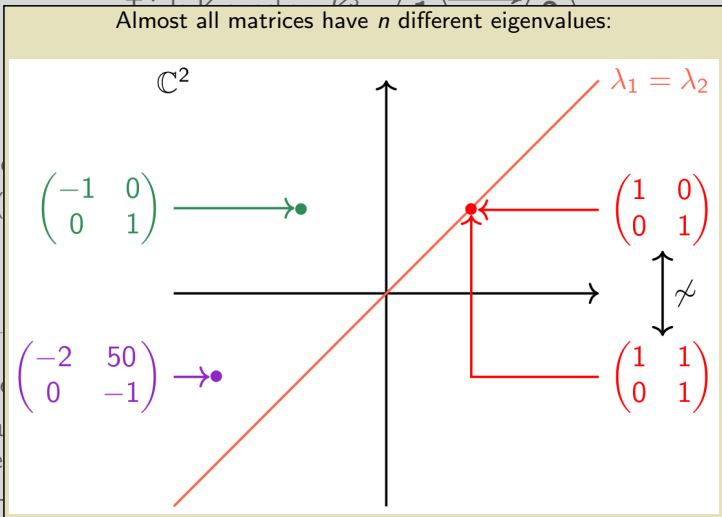
Kronecker's normal form for $(A, B) \approx (A', B')$:

$$L_n = \begin{pmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & 0 & 1 \end{pmatrix}, \quad L_n^T = \begin{pmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & 0 & 1 \end{pmatrix}^T$$

- ▶ Take $\mathbf{d} = (n, n)$ for K^3
- ▶ Assume that A is invertible, B is diagonalizable with pairwise different eigenvalues
- ▶ Using Kronecker's normal form we can assume that $A = id_n$ and $B = \text{diag}(\lambda_1, \dots, \lambda_n)$

Matrix problems – the algebraic approach

Almost all matrices have n different eigenvalues:



- ▶ Take
- ▶ Assume
- eigen
- ▶ Using

$$A = id_n \text{ and } B = \text{diag}(\lambda_1, \dots, \lambda_n)$$

Matrix problems – the algebraic approach

Triple Kronecker: $K^3 = \textcircled{1} \implies \textcircled{2}$

$$J_n(\lambda) = \begin{pmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \lambda & 1 \\ & & & \lambda \end{pmatrix}, \quad id_n = \begin{pmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

Kronecker's normal form for $(A, B) \approx (A', B')$:

$$L_n = \begin{pmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & 0 & 1 \end{pmatrix}, \quad L_n^T = \begin{pmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & 0 & 1 \end{pmatrix}^T$$

- ▶ The subgroup $H \subset GL_n \times GL_n$ fixing (A, B) consists of diagonal matrices $\text{diag}(h_1, \dots, h_n)$ acting on C by conjugation: $c_{i,j} \mapsto h_i/h_j \cdot c_{i,j}$
- ▶ Thus, we can assume that

$$C = \begin{pmatrix} c_{1,1} & c_{1,2} & \dots & c_{1,n-1} & c_{1,n} \\ 1 & c_{2,2} & \dots & c_{2,n-1} & c_{2,n} \\ c_{3,1} & 1 & \dots & c_{3,n-1} & c_{3,n} \\ & & \dots & & \\ c_{n,1} & c_{n,2} & \dots & 1 & c_{1,n} \end{pmatrix}, \quad c_{i,j} \neq 0$$

Theorem (folklore ~1970s)

Almost all inde. K^3 -reps with dimension (vector) (n, n) are of the form $(id_n, \text{diag}(\lambda_1, \dots, \lambda_n), C)$ as in the background

A bit more effort shows something similar for other dimensions vectors and quivers

The bait It is often very easy to classify almost all indecomposables

Kronecker's normal form for

$$(A, B) \approx (A', B')$$

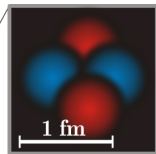
$$L_n = \begin{pmatrix} 0 & 1 & & & \\ & \ddots & \ddots & & \\ & & 0 & 1 & \\ & & & 0 & 1 \end{pmatrix}, \quad L_n^T = \begin{pmatrix} 0 & 1 & & & \\ & \ddots & \ddots & & \\ & & 0 & 1 & \\ & & & 0 & 1 \end{pmatrix}^T$$

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Matrix problems – the algebraic approach

The interesting bits are rare and hard to get



1 Å = 100 000 fm

The algebraic approach get us to the empty space of the atom

The geometric approach should get us a bit closer to the interesting bits

$$C = \begin{pmatrix} c_{1,1} & c_{1,2} & \dots & c_{1,n-1} & c_{1,n} \\ 1 & c_{2,2} & \dots & c_{2,n-1} & c_{2,n} \\ c_{3,1} & 1 & \dots & c_{3,n-1} & c_{3,n} \\ \dots & \dots & \dots & \dots & \dots \\ c_{n,1} & c_{n,2} & \dots & 1 & c_{1,n} \end{pmatrix}, \quad c_{i,j} \neq 0$$

For completeness (I will not recall what root systems are)

Theorem (Kac~1980)

For an arbitrary quiver we only have two cases:

- (a) If \mathbf{d} is a positive real root, then \exists inde. rep. with dimension \mathbf{d}
- (b) If \mathbf{d} is a positive imaginary root, then \exists inde. rep. with dimension \mathbf{d} parametrized by $1 - 1/2(\mathbf{d}, \mathbf{d})$ parameters

$$(A, B) \approx (A', B')$$

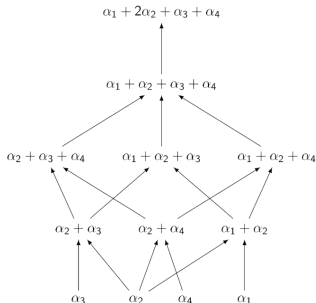
Example (type D_4)

SageMath with `Phi = RootSystem(['D',4]).root_poset();` produces:

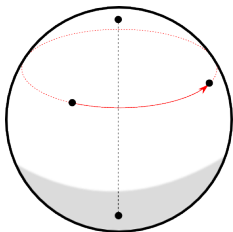
The 3-subspace problem is of finite representation type (D_4); the indecomposables are (up to "permutation of legs"):

$$\begin{array}{c}
 0 \xrightarrow{0} \mathbf{k} \xleftarrow{0} 0 \quad \mathbf{k} \xrightarrow{0} 0 \xleftarrow{0} 0 \quad \mathbf{k} \xrightarrow{1} \mathbf{k} \xleftarrow{0} 0 \\
 \uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow \\
 0 \quad \quad \quad 0 \quad \quad \quad 0
 \end{array}$$

$$\begin{array}{c}
 \mathbf{k} \xrightarrow{1} \mathbf{k} \xleftarrow{0} 0 \\
 \uparrow \\
 \mathbf{k}
 \end{array}
 \quad
 \begin{array}{c}
 \mathbf{k} \xrightarrow{\binom{1}{0}} \mathbf{k} \oplus \mathbf{k} \xleftarrow{\binom{0}{1}} \mathbf{k} \\
 \uparrow \binom{1}{1} \\
 \mathbf{k}
 \end{array}$$



Moduli spaces – semisimple case



- **Basic idea** Fix \mathbf{d} , and M of dimension \mathbf{d} , and consider the affine \mathbb{C} -space

$$R_{\mathbf{d}} = R_{\mathbf{d}}(Q) = \bigoplus_{i \rightarrow j} \text{hom}_{\mathbb{C}}(M_i, M_j)$$

$G_{\mathbf{d}} = \prod_i GL(M_i)$ acts on $R_{\mathbf{d}}$ via base change, and $G_{\mathbf{d}}$ -orbits correspond bijectively to the iso. classes of Q -reps of dimension \mathbf{d}

- **Task** Find a subset $U \subset R_{\mathbf{d}}$, an algebraic variety X and a morphism $\pi: U \rightarrow X$ whose fibers are precisely the $G_{\mathbf{d}}$ -orbits in U

Problem

Take the 5-Kronecker quiver $\textcircled{1} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \textcircled{2}$ and $M(\lambda, \mu)$ for $(\lambda, \mu) \neq (0, 0)$ and $\mathbf{d} = (2, 3)$:

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ \lambda & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & \mu \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Lemma (easy) $M(\lambda, \mu) \cong M(\alpha, \beta)$ if and only if $\exists t \in \mathbb{C}^*$ such that $\lambda = t\alpha$ and $\mu = t^{-1}\beta$

Let U be the set of all $M(\lambda, \mu)$

Then $\lim_{\lambda \rightarrow 0} M(\lambda, 1) = M(0, 1)$ and $\lim_{\mu \rightarrow 0} M(1, \mu) = M(1, 0)$ in U

Hence, there can not be a continuous map $\pi: U \rightarrow X$ since

$$M(\lambda, 1) \cong M(1, \mu) \text{ but } M(0, 1) \not\cong M(1, 0)$$

bijectionally to the iso. classes of Q -reps of dimension \mathbf{d}

- **Task** Find a subset $U \subset R_{\mathbf{d}}$, an algebraic variety X and a morphism $\pi: U \rightarrow X$ whose fibers are precisely the $G_{\mathbf{d}}$ -orbits in U

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Take the 5-Kronecker quiver $\textcircled{1} \begin{matrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{matrix} \textcircled{2}$ and $M(\lambda, \mu)$ for $(\lambda, \mu) \neq (0, 0)$ and $\mathbf{d} = (2, 3)$:

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$$M(\lambda, 1) \cong M(1, \mu) \text{ but } M(0, 1) \not\cong M(1, 0)$$

bijectively to the iso. classes of Q -reps of dimension \mathbf{d}

The above example is just one of the typical problems in defining quotients:

it shows that the potential “orbit space U/G_d ” would be non-separated

Usually set-theoretical quotients have a bad topology – need something better!

Moduli spaces – semisimple case

$$\begin{array}{ccc} R_d & \xrightarrow{f} & Y \\ \pi \downarrow & \nearrow \exists! \bar{f} & \\ X & & \end{array}$$

- ▶ G_d acts on R_d as before, (X, π) should be universal
- ▶ In the cat. of sets with a G_d -action we get the “bad” quotient $X = R_d/G_d$,
in the cat. of alg. varieties with a G_d -action we get the “better” quotient $X = R_d//G_d$
- ▶ **Theorem ((Hilbert–)Mumford \sim (1893,)1965)** $R_d//G = \text{Spec}(\mathbb{C}[R_d]^{G_d})$
and parametrizes the closed orbits

$$\begin{array}{ccc} R_d & \xrightarrow{f} & Y \\ \pi \downarrow & \nearrow & \\ X & & \end{array} \quad \exists! \bar{f}$$

- ▶ **Theorem (Le Bruyn–Procesi ~1990)** $R_d // G = \text{Spec}(\mathbb{C}[R_d]^{G_d})$ and parametrizes iso. classes of semisimple Q -reps of dimension \mathbf{d}
- ▶ Closed orbit \Leftrightarrow semisimple
- ▶ Call $M_d^{ss} = R_d // G$ the moduli space of semisimple Q -reps of dimension \mathbf{d}

Moduli spaces – semisimple case

“Proof” of Closed orbit \Leftrightarrow semisimple

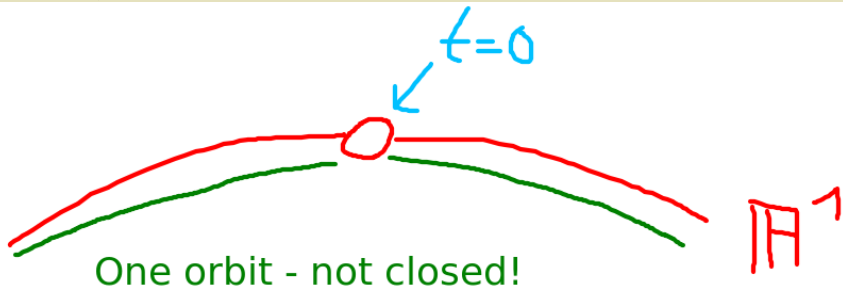
If a Q -rep of dimension 2 of $(\mathbf{1})^\curvearrowright$ is not semisimple

then we can assume that we have the matrix $\begin{pmatrix} \lambda & t \\ 0 & \lambda \end{pmatrix}$

For $t \neq 0$ this is a nontrivial Jordan block up to base change

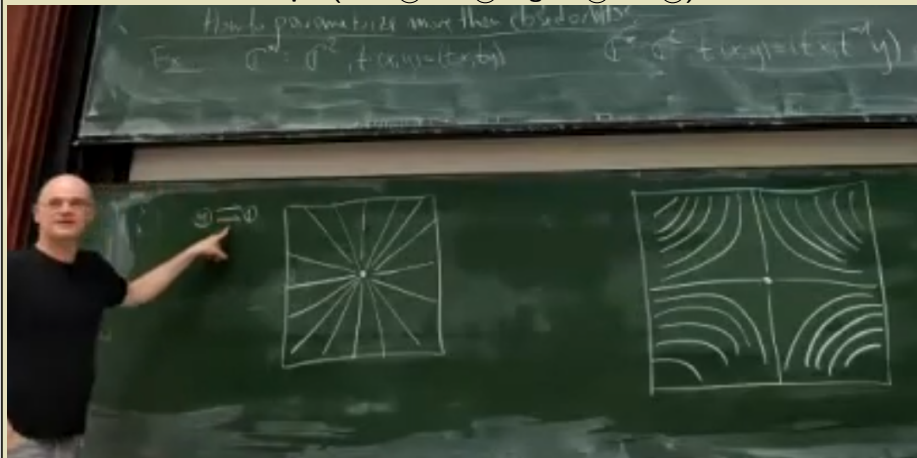
For $t = 0$ this is a direct sum of two $1d$ simples

Thus, the orbit of the nontrivial Jordan block is not closed and looks like



► Call $M_d^{ss} = R_d // G$ the moduli space of semisimple Q -reps of dimension d

Example (left: $\textcircled{1} \rightrightarrows \textcircled{2}$, right: $\textcircled{1} \longleftrightarrow \textcircled{2}$)



For $d = (1, 1)$, the action of $G_d \cong \mathbb{C}^*$ is $t(x, y) = (tx, ty)$ and $t(x, y) = (tx, t^{-1}y)$

The orbit spaces are as above

The closed orbits are $(0, 0)$; plus hyperbolas on the right

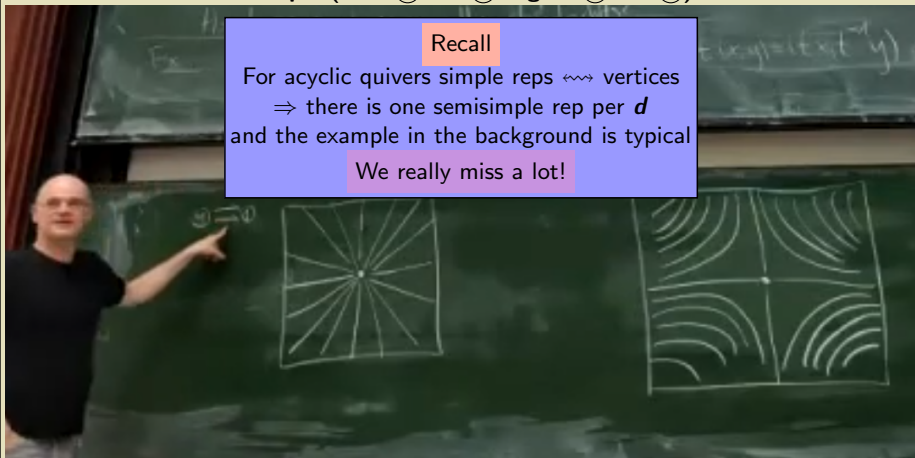
We miss a lot!

Example (left: $① \rightrightarrows ②$, right: $① \longleftrightarrow ②$)

Recall

For acyclic quivers simple reps \longleftrightarrow vertices
 \Rightarrow there is one semisimple rep per d
and the example in the background is typical

We really miss a lot!



For $d = (1, 1)$, the action of $G_d \cong \mathbb{C}^*$ is $t(x, y) = (tx, ty)$ and $t(x, y) = (tx, t^{-1}y)$

The orbit spaces are as above

The closed orbits are $(0, 0)$; plus hyperbolas on the right

We miss a lot!

Moduli spaces – semisimple case

Example (Jordan quiver $(1 \rightrightarrows)$)

$d = (2)$, $G_d = GL_2(\mathbb{C})$ acting on $R_d = Mat_2(\mathbb{C})$ by conjugation

There are “obvious” $GL_2(\mathbb{C})$ -invariant functions:

the trace $tr(_)$ and the determinant $det(_)$

Lemma $\mathbb{C}[Mat_2(\mathbb{C})]^{GL_2(\mathbb{C})}$ is generated by $tr(_)$ and $det(_)$

Lemma $tr(_)$ and $det(_)$ are algebraically independent

Hence, $\mathbb{C}[Mat_2(\mathbb{C})]^{GL_2(\mathbb{C})} \cong \mathbb{C}[X, Y]$ and $Mat_2(\mathbb{C})//GL_2(\mathbb{C})$ is affine 2-space

► **Theorem (Le Bruyn–Procesi ~1990)** $R_d//G = Spec(\mathbb{C}[R_d]^{G_d})$ and parametrizes iso. classes of semisimple Q -reps of dimension \mathbf{d}

► Closed orbit \Leftrightarrow semisimple

► Call $M_d^{ss} = R_d//G$ the moduli space of semisimple Q -reps of dimension \mathbf{d}

Moduli spaces – semisimple case

Example (Jordan quiver $\textcircled{1} \curvearrowright$)

$d = (2)$, $G_d = GL_2(\mathbb{C})$ acting on $R_d = Mat_2(\mathbb{C})$ by conjugation

There are “obvious” $GL_2(\mathbb{C})$ -invariant functions:

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Lemma $tr(_)$ and $det(_)$ are algebraically independent

Hence, $\mathbb{C}[Mat_2(\mathbb{C})]^{GL_2(\mathbb{C})} \cong \mathbb{C}[X, Y]$ and $Mat_2(\mathbb{C})//GL_2(\mathbb{C})$ is affine 2-space

Example (Jordan quiver $\textcircled{1} \curvearrowright$ - second)

For $d = (n)$ we have that $\mathbb{C}[Mat_n(\mathbb{C})]^{GL_n(\mathbb{C})} = \mathbb{C}[e_i(_) | i = 1, \dots, n]$

The $e_i(_)$ are the coefficients of the characteristic polynomial

Alternatively, a diagonalizable matrix mod base change is determined by its eigenvalues!

► Call $M_d^{ss} = R_d//G$ the moduli space of semisimple Q -reps of dimension d

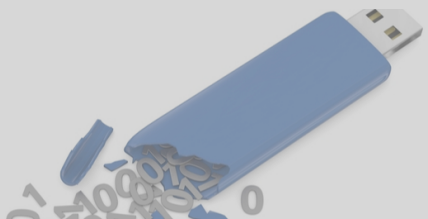
Moduli spaces – semisimple case



- ▶ **Theorem (Le Bruyn–Procesi ~1990)** $\mathbb{C}[R_d]^{G_d}$ is generated by “traces along oriented cycles”
- ▶ **Problem 1** The theory is trivial for quivers without oriented cycles
- ▶ **Problem 2** In general, we loose a lot, e.g. the Jordan normal form for **1** ↻



- ▶ **Theorem (Le Bruyn–Procesi ~1990)** $\mathbb{C}[R_d]^{G_d}$ is generated by “traces along oriented cycles”
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Example (Jordan quiver $\textcircled{1}$ - third)

We only need to be able to calculate the eigenvalues so we could also take $\text{tr}(A)$, $\text{tr}(A^2)$ etc. as ring generators

- ▶ **Theorem (Le Bruyn–Procesi ~1990)** $\mathbb{C}[R_d]^{G_d}$ is generated by “traces along oriented cycles”
- ▶ **Problem 1** The theory is trivial for quivers without oriented cycles
- ▶ **Problem 2** In general, we lose a lot, e.g. the Jordan normal form for $\textcircled{1}$

Example ($\circlearrowleft 1 \circlearrowright$)

For $d = (2)$ one can show that $\mathbb{C}[Mat_n(\mathbb{C}) \times Mat_n(\mathbb{C})]^{GL_n(\mathbb{C})}$ is generated by $tr(A)$ $tr(A^2)$, $tr(AB) = tr(BA)$, $tr(B)$ and $tr(B^2)$

Moreover, $R_d // G_d$ is affine 5-space



- ▶ **Theorem (Le Bruyn–Procesi ~1990)** $\mathbb{C}[R_d]^{G_d}$ is generated by “traces along oriented cycles”
- ▶ **Problem 1** The theory is trivial for quivers without oriented cycles
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Example (↺①↻)

For $d = (2)$ one can show that $\mathbb{C}[Mat_n(\mathbb{C}) \times Mat_n(\mathbb{C})]^{GL_n(\mathbb{C})}$ is generated by $tr(A)$, $tr(A^2)$, $tr(AB) = tr(BA)$, $tr(B)$ and $tr(B^2)$

Moreover, $R_d//G_d$ is affine 5-space

Example (① $\xrightleftharpoons[t]{s}$ ② with s and t arrows)

For $d = (1, 1)$ one can show that the invariant ring is generated by $tr(s_i t_j) = s_i t_j$

Moreover, $R_d//G_d \cong Cone(\mathbb{P}^{s-1} \times \mathbb{P}^{t-1} \hookrightarrow \mathbb{P}^{s+t-1})$ (via Segre embedding)

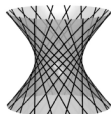
Example (Segre embedding for $s = t = 2$)

$\mathbb{P}^1 \times \mathbb{P}^1 \rightarrow \mathbb{P}^3$ with $([s_0 : s_1], [t_0 : t_1]) \mapsto [s_0 t_0 : s_0 t_1 : s_1 t_0 : s_1 t_1]$ gives



$\mathbb{P}^1 \times \mathbb{P}^1$

f



$X \subset \mathbb{P}^3$

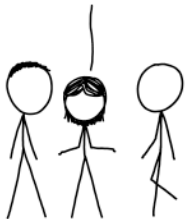
- ▶ The orien
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for ①↻

Beyond these cases this gets very difficult

OUR FIELD HAS BEEN STRUGGLING WITH THIS PROBLEM FOR YEARS.



STRUGGLE NO MORE! I'M HERE TO SOLVE IT WITH ALGORITHMS!



SIX MONTHS LATER:

WOW, THIS PROBLEM IS REALLY HARD.

YOU DON'T SAY.



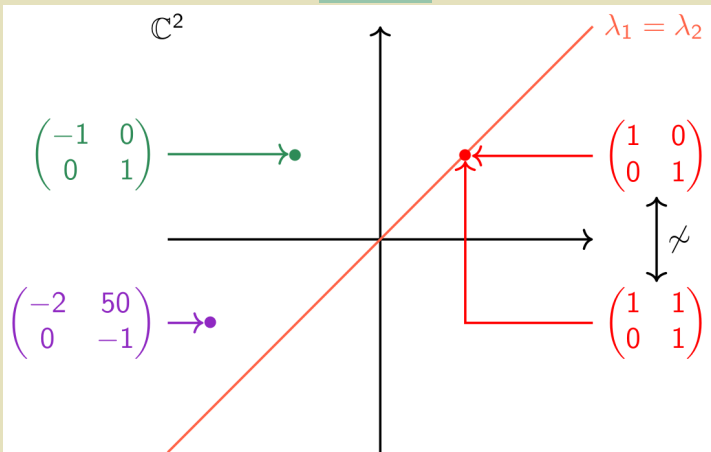
► Theorem (Le Bruyn + Procesi ~1990) $C_n[k, \lambda]$ is generated by "traces along oriented cycles"

► Problem 1 The theory is trivial for quivers without oriented cycles

► Problem 2 In general, we lose a lot, e.g. the Jordan normal form for $\textcircled{1}$

Moduli spaces – semisimple case

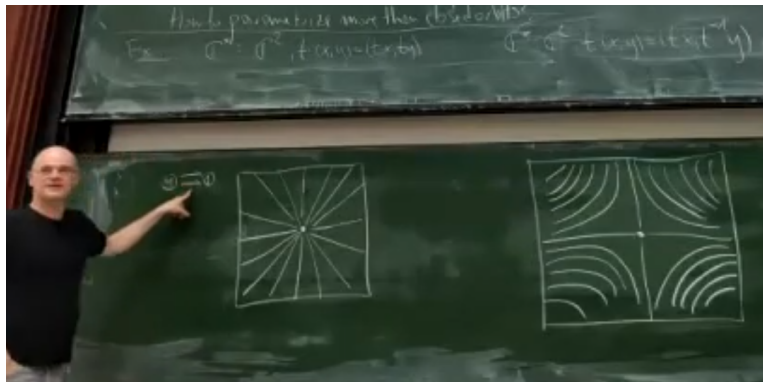
Note that this geometric approach is a bit better than the algebraic “generic” results



► **Problem 1** The theory is trivial for quivers without oriented cycles

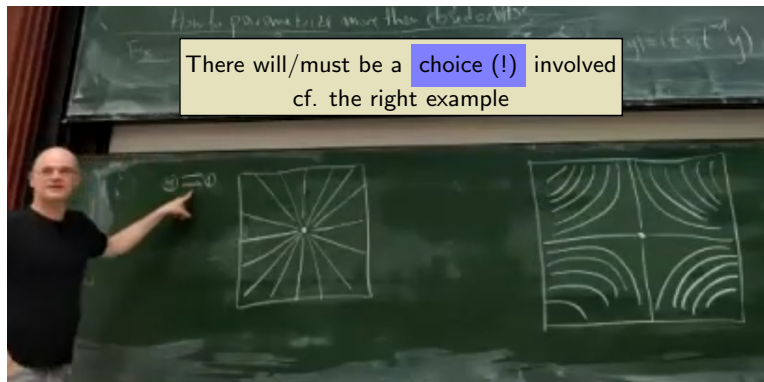
► **Problem 2** In general, we lose a lot, e.g. the Jordan normal form for **1** ↻

Moduli spaces – beyond semisimple



- ▶ **Issue** The GIT approach only sees closed orbits = semisimple things
- ▶ **Left** Getting rid of the origin would “solve” that issue
- ▶ **Right** Getting rid of the origin and one axis would “solve” that issue

Moduli spaces – beyond semisimple

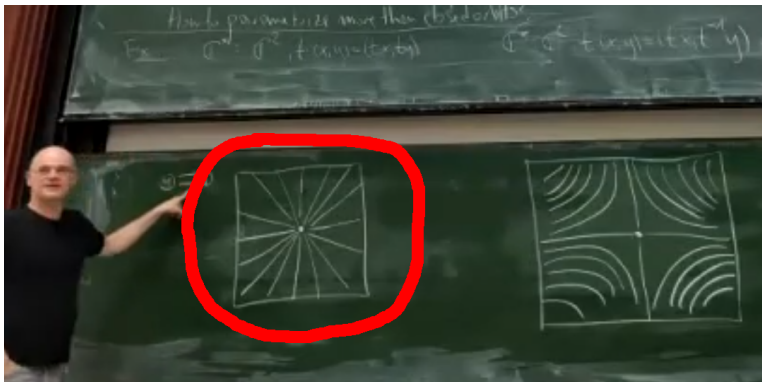


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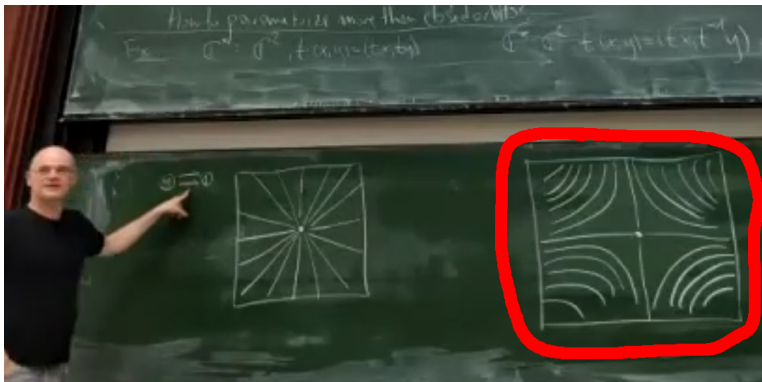
- ▶ Choose a character $\chi: G_d \rightarrow \mathbb{C}^*$, e.g. the determinant
- ▶ χ -semiinvariants $\mathbb{C}[R_d]_\chi^{G_d} = \{f \mid f(g \circ v) = \chi(g)^N f(v) \text{ for some weight } N\}$;
graded by weight
- ▶ χ -semistable $R_d^{sst} = \{v \mid f(v) \neq 0 \text{ for some } f \text{ of weight } > 0\}$
- ▶ Quotient $\pi: R_d^{sst} \rightarrow \text{Proj}(\mathbb{C}[R_d]_\chi^{G_d}) = R_d^{sst} // G_d$
- ▶ **Theorem (Mumford ~1965)** $M^{sst} = R_d^{sst} // G_d$ parametrizes the closed orbits in R_d^{sst}
- ▶ Recall that $\text{Proj}(S) = \{P \subset S \text{ homogeneous and prime with } S_+ \not\subset P\}$

Moduli spaces – beyond semisimple



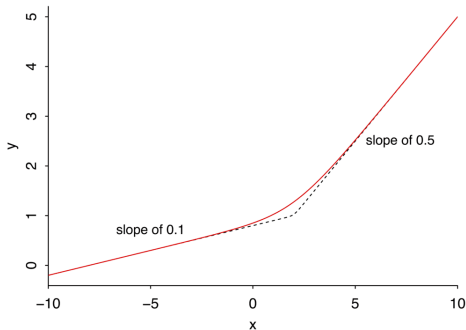
- ▶ Character $\chi = \det$ (equals id since 1d case)
- ▶ χ -semistable points $R_{(1,1)}^{sst} \cong \mathbb{C}^2 \setminus \{(0,0)\}$
- ▶ Invariants and moduli $\mathbb{C}[R_{(1,1)}^{sst}]_{\chi}^{G_d} \cong \mathbb{C}[X_{deg1}, Y_{deg1}]$ and $Proj(\mathbb{C}[X, Y]) = \mathbb{P}^1$

Moduli spaces – beyond semisimple



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Moduli spaces – beyond semisimple



► Choose $\Theta \in (\mathbb{Z}\text{vertices})^*$, and define the **slope** $= \Theta(\mathbf{d}(V)) / \dim V \in \mathbb{Q}$

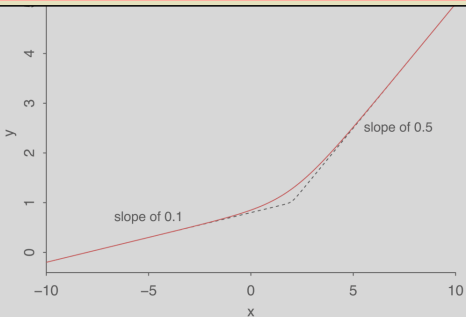
► Define

Θ -semistable		The slope is weakly decreasing on nontrivial(!) subreps
Θ -stable		same but with $<$
Θ -polystable		direct sum of Θ -stable of the same slope

Theorem (King, Schofield–van den Bergh ~1994)

R_d^{sst} (for χ_Θ obtained from Θ) = Θ -semistable reps; and

$$M^{sst} = R_d^{sst} // G_d \xrightarrow{1:1} \Theta\text{-polystable reps of dimension } d$$



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Example

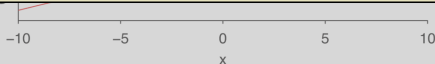
Take $\Theta = 0$ so that $\chi(g) = 1$, then the slope is always zero

Θ -semistable = all Q -reps

Θ -stable = simple Q -reps

Θ -polystable = semisimple Q -reps

We thus recover the setting from before



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Example (① \rightleftarrows ②) with $m \geq 2$ edges)

Take $\Theta(d_1, d_2) = d_1$, and $d = (1, d \leq m)$

Θ -semistable = all Q -reps

$$M^{sst} = \text{Grassmannian } G(d, m)$$

To see this is nontrivial, but here is a sketch!

A Q -rep of dimension $(1, d)$ is a collection of m column vectors of size d

The determinants of the $\binom{m}{d} - 1$ minors generate the invariants

These satisfy the Plücker relations

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In general computations are difficult

Moduli spaces – beyond semisimple



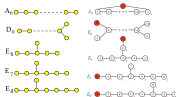
-
- For every $\Theta \neq 0$ and every \mathbb{Q} -rep M there $\exists!$ filtration

$$0 = M_0 \subset M_1 \subset \dots \subset M_k = M$$

such that:

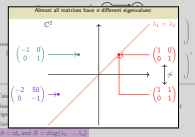
- M_i/M_{i-1} is Θ -stable
 - The slope of the M_i/M_{i-1} is strictly decreasing
- For $\Theta = 0$ the above “specializes” to the Jordan–Hölder theorem
- We can thus (at least in some sense) describe all \mathbb{Q} -reps

Matrix problems – the algebraic approach



- Recall Some matrix problems can be associated with quivers
- Recall Matrix problems are decidable only in the finite and affine ADE types
- Otherwise, the algebraic approach is doomed to fail and classifications get messy

Matrix problems – the algebraic approach



Recall that $\lambda_1 = \lambda_2$ and $\lambda_1 = \lambda_2$ along $\lambda_1 = \lambda_2$

Moduli spaces – beyond semistable



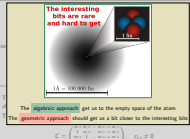
- Choose a character $\chi: G_m \rightarrow C^*$, e.g. the determinant
- χ -semistable $C[RG_m^{\chi}] = f | f(g \cdot v) = \chi(g)^m f(v)$ for some weight m , graded by weight
- χ -semistable $R^0 = \{v | f(v) \neq 0 \text{ for some } f \text{ of weight } > 0\}$
- Quotient $e: R^0 \rightarrow Proj(C[RG_m^{\chi}]) = R^0 // G_m$
- Theorem (Mumford–1965) $M^{\text{st}} = R^0 // G_m$ parametrizes the closed orbits in R^0
- Recall that $Proj(S) = \{P \subset S \text{ homogeneous and prime with } S_0 \subset P\}$

Matrix problems



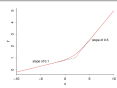
- The classical approach
- But for almost all graphs there are efficient algorithms to check this
- We will see this momentarily

Matrix problems – the algebraic approach



- The algebraic approach get us to the empty space of the atom
- The geometric approach should get us a bit closer to the interesting bits

Moduli spaces – beyond semistable



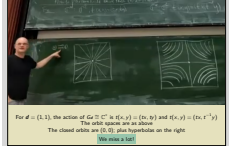
- Choose $\Theta \in (\mathbb{Z}/m\mathbb{Z})^*$, and define the slope $\mu_{\Theta} = \Theta(d(V)) / \dim V \in \mathbb{Q}$
- Define Θ -semistable Θ -stable Θ -polystable

Matrix problems – the algebraic approach



- But for almost all graphs there are efficient algorithms to check this
- So the difficulty is very concentrated

Moduli spaces – beyond semistable



For $d = (1, 1)$, the action of $G_m \times C^* \curvearrowright C^2 = (x, y) \mapsto (tx, ty)$ and $(x, y) \mapsto (x, y^{-1}y)$

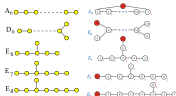
Moduli spaces – beyond semistable



- For every $\Theta \neq 0$ and every \mathbb{Q} -rep M there \exists filtration $M_0 \subset M_1 \subset \dots \subset M_n = M$
- such that:
 - M_i/M_{i-1} is Θ -stable
 - The slope of the M_i/M_{i-1} is strictly decreasing
- For $\Theta = 0$ the above "specializes" to the Jordan–Hölder theorem
- We can thus (at least in some sense) describe all \mathbb{Q} -reps

There is still much to do...

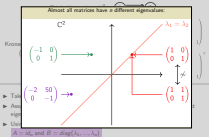
Matrix problems – the algebraic approach



- ▶ **Recall** Some matrix problems can be associated with quivers
- ▶ **Recall** Matrix problems are decidable only in the finite and affine ADE types
- ▶ Otherwise, the algebraic approach is doomed to fail and classifications get **messy**

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Matrix problems – the algebraic approach



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Moduli spaces – beyond semisimple



- ▶ **Choose a character** $\chi: G_m \rightarrow C^*$, e.g. the determinant
- ▶ **χ -semiinvariants** $C[R_m^G]^\chi = \{f \in R_m^G \mid f(\chi \mathcal{O}_V) = \chi(\lambda)^m f(V) \text{ for some weight } m\}$, graded by weight
- ▶ **χ -seminstable** $R_m^\chi = \{f \in R_m^G \mid f \neq 0 \text{ for some } f \text{ of weight } > 0\}$
- ▶ **Quotient** $e: R_m^\chi \rightarrow \text{Proj}(C[R_m^G]^\chi) = R_m^\chi // G_m$
- ▶ **Theorem (Mumford–1965)** $M^{\text{st}} \subset R_m^\chi // G_m$ parametrizes the closed orbits in R_m^χ
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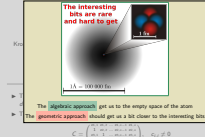
Matrix problems



- ▶ The classification is **really difficult** – other means
- ▶ But for almost all graphs there are **efficient algorithms** to check this
- ▶ We will see this momentarily: **deformation vector of vertex**

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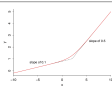
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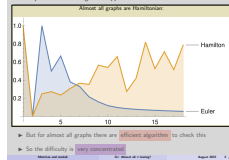
Moduli spaces – beyond semisimple



- ▶ Choose $\Theta \in (\mathbb{Z}/m\mathbb{Z})^*$, and define the **slope** $\Theta = \Theta(d(V)) / \dim V \in \mathbb{Q}$
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Matrix problems – the algebraic approach



- ▶ But for almost all graphs there are **efficient algorithms** to check this
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Example (left): **right:**

For $d = (1, 1)$, the action of $G_m \curvearrowright C^2$ is $t(x, y) = (tx, ty)$ and $t(x, y) = (tx, t^{-1}y)$.
The orbit spaces are as above.
The closed orbits are $\{0, 0\}$ plus hyperbolas on the right.
We miss a bit!

Moduli spaces – beyond semisimple



- ▶ For every $\Theta \neq 0$ and **every** \mathbb{Q} -rep M there **\exists filtration**

- $M_0 \subset M_1 \subset \dots \subset M_r = M$
- such that:
 - M_i/M_{i-1} is Θ -stable
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▶ For $\Theta = 0$ the above "specializes" to the Jordan–Hölder theorem

▶ **We can thus (at least in some sense) describe all \mathbb{Q} -reps**

Thanks for your attention!