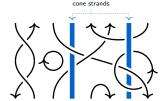
Link invariants and $\mathbb{Z}_{2\mathbb{Z}}$ -orbifolds

Or: What makes types ABCD special?

Daniel Tubbenhauer



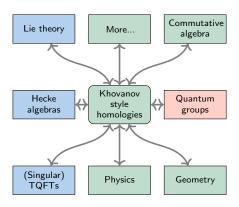
Joint work in progress (take it with a grain of salt) with Catharina Stroppel and Arik Wilbert (Based on an idea of Mikhail Khovanov)

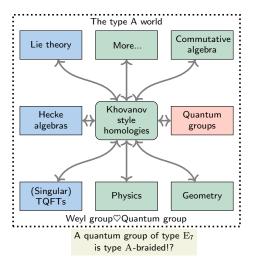
January 2018

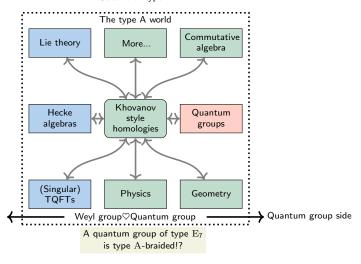
Khovanov style homologies

Commutative Lie theory More... algebra Khovanov Hecke Quantum style algebras groups homologies (Singular) TQFTs Physics Geometry

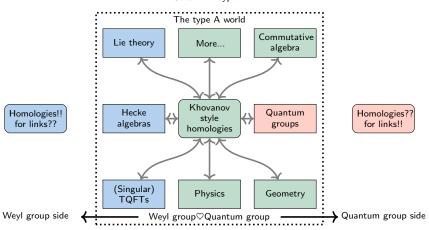
My beloved gadget with many connections.

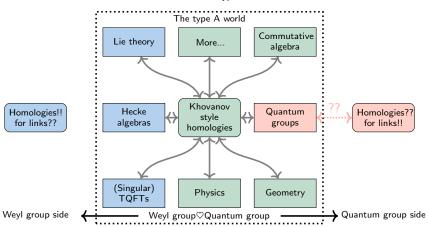


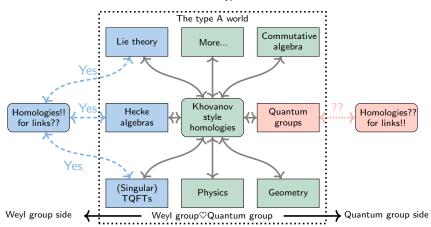


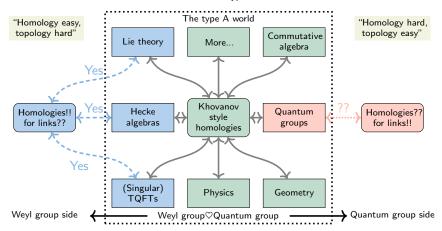


Weyl group side









- **1** Tangle diagrams of $\mathbb{Z}_{2\mathbb{Z}}$ -orbifold tangles
 - Diagrams
 - Tangles in $\mathbb{Z}/_{2\mathbb{Z}}$ -orbifolds
- Topology of Artin braid groups
 - The Artin braid groups: algebra
 - Hyperplanes vs. configuration spaces
- Invariants
 - Reshetikhin-Turaev-like theory for some coideals
 - \bullet Polynomials and homologies for ${\mathbb Z}/_{\!2{\mathbb Z}}\text{-orbifold tangles}$

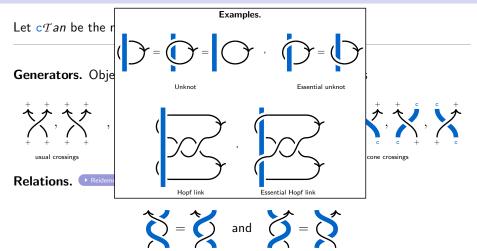
Let cTan be the monoidal category defined as follows.

Generators. Object generators $\{+,-,c\}$, morphism generators

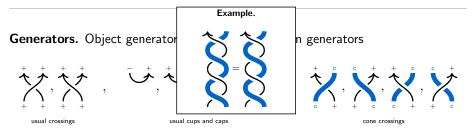


Relations. ightharpoonup Reidemeister type relations, and the ightharpoonup/2ightharpoonup-relations:

$$=$$
 and $=$



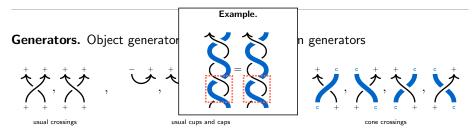
Let $c\mathcal{T}an$ be the monoidal category defined as follows.



Relations. Preidemeister type relations, and the $\mathbb{Z}/_{2\mathbb{Z}}$ -relations:

$$=$$
 and $=$

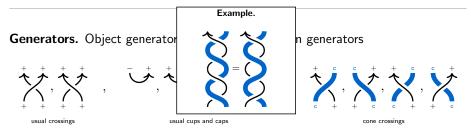
Let cTan be the monoidal category defined as follows.



Relations. ightharpoonup Reidemeister type relations, and the ightharpoonup/2ightharpoonup-relations:

$$=$$
 and $=$

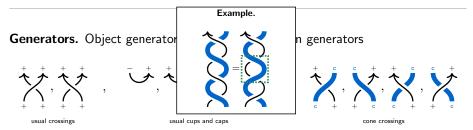
Let $c\mathcal{T}an$ be the monoidal category defined as follows.



Relations. Preidemeister type relations, and the $\mathbb{Z}/_{2\mathbb{Z}}$ -relations:

$$=$$
 and $=$

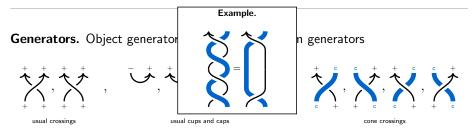
Let cTan be the monoidal category defined as follows.



Relations. Preidemeister type relations, and the $\mathbb{Z}/_{2\mathbb{Z}}$ -relations:

$$=$$
 and $=$

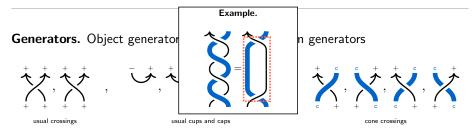
Let cTan be the monoidal category defined as follows.



Relations. ightharpoonup Reidemeister type relations, and the ightharpoonup/2ightharpoonup-relations:

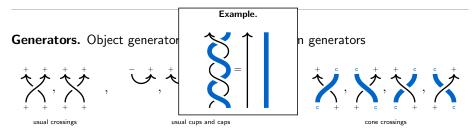
$$=$$
 and $=$

Let cTan be the monoidal category defined as follows.



Relations. Preidemeister type relations, and the $\mathbb{Z}/_{2\mathbb{Z}}$ -relations:

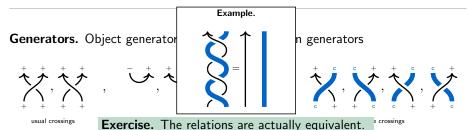
Let cTan be the monoidal category defined as follows.



Relations. ightharpoonup Reidemeister type relations, and the ightharpoonup/2ightharpoonup-relations:

$$=$$
 and $=$

Let $c\mathcal{T}an$ be the monoidal category defined as follows.



Relations. ightharpoonup Reidemeister type relations, and the ightharpoonup/ $_2$ Z-relations:

"Definition". An Porbifold is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/z_z - z}{cone point}$







"Definition". An Poblifold is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/_{z=-z}}{cone point}$







"Definition". An Porbifold is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/z = -z}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/_{z=-z}}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/z_z - z}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10\textit{rb} = \mathbb{R}^2 / \mathbb{Z}_{/2\mathbb{Z}} \qquad \underset{\mathbb{Z}_{/2\mathbb{Z}} \text{ action}}{\overset{\mathbb{R}^2}{\longrightarrow}} \rightsquigarrow X_{c_10\textit{rb}} \approx \underset{\text{cone point}}{\overset{\mathbb{R}^2/z = -z}{\longrightarrow}}$$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10\mathit{rb} = \mathbb{R}^2 / \mathbb{Z}_{2\mathbb{Z}}$$
 $\overset{\mathbb{R}^2}{\sim}$ $\sim X_{c_10\mathit{rb}} \approx \overset{\mathbb{R}^2/_{z=-z}}{\sim}$ cone point







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/_{z=-z}}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/z_z - z}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}/_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/z = -z}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

$$c_10rb = \mathbb{R}^2/\mathbb{Z}_{2\mathbb{Z}}$$
 $\stackrel{\mathbb{R}^2}{\sim}$ $\sim X_{c_10rb} \approx \frac{\mathbb{R}^2/_{z=-z}}{cone point}$







"Definition". An Problem is locally modeled on the standard Euclidean space modulo an action of some finite group.

Main example. $\mathbb{Z}_{2\mathbb{Z}}$ acts on \mathbb{R}^2 by rotation by π around a fixed point c:

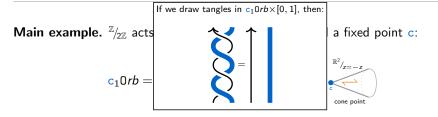
$$c_10\mathit{rb} = \mathbb{R}^2 / \mathbb{Z}_{2\mathbb{Z}}$$
 $\overset{\mathbb{R}^2}{\sim}$ $\sim X_{c_10\mathit{rb}} \approx \overset{\mathbb{R}^2/_{z=-z}}{\sim}$ cone point







"Definition". An Poblifold is locally modeled on the standard Euclidean space modulo an action of some finite group.









Pioneers of algebra

Let Γ be a ▶ Coxeter graph.

Artin \sim **1925, Tits** \sim **1961**++. The Artin braid groups and its Coxeter group quotients are given by generators-relations:

$$\mathcal{A}r_{\Gamma} = \langle b_{i} \mid \underbrace{\cdots b_{i}b_{j}b_{i}}_{m_{ij} \text{ factors}} = \underbrace{\cdots b_{j}b_{i}b_{j}}_{m_{ij} \text{ factors}} \rangle$$

$$\mathcal{W}_{\Gamma} = \langle s_{i} \mid s_{i}^{2} = 1, \underbrace{\cdots s_{i}s_{j}s_{i}}_{m_{ij} \text{ factors}} = \underbrace{\cdots s_{j}s_{i}s_{j}}_{m_{ij} \text{ factors}} \rangle$$

Artin braid groups generalize classical braid groups, Coxeter groups Weyl groups.

We want to understand these better.

Pioneers of algebra

Let Γ be a ▶ Coxeter graph .

Artin \sim **1925, Tits** \sim **1961**++. The Artin braid groups and its Coxeter group quotients are given by generators-relations:

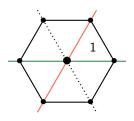
Only algebra:
$$\mathcal{A}r_{\Gamma} = \langle b_i \mid \underbrace{\cdots b_i b_j b_i}_{m_{ij} \text{ factors}} = \underbrace{\cdots b_j b_i b_j}_{m_{ij} \text{ factors}} \rangle$$

$$\mathcal{W}_{\Gamma} = \langle s_i \mid s_i^2 = 1, \underbrace{\cdots s_i s_j s_i}_{m_{ij} \text{ factors}} = \underbrace{\cdots s_j s_i s_j}_{m_{ij} \text{ factors}} \rangle$$

Artin braid groups generalize classical braid groups, Coxeter groups Weyl groups.

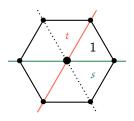
We want to understand these better.

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):



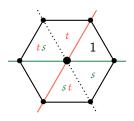
 $\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):



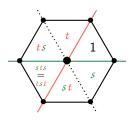
 $\mathcal{W}_{A_2} \text{ acts freely on } \mathbf{M}_{A_2} = \mathbb{R}^2 \setminus \text{hyperplanes. Set } \mathbf{N}_{A_2} = \mathbf{M}_{A_2} / \mathcal{W}_{A_2}.$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):



 $\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):



 $\mathcal{W}_{A_2} \text{ acts freely on } \mathbf{M}_{A_2} = \mathbb{R}^2 \setminus \text{hyperplanes. Set } \mathbf{N}_{A_2} = \mathbf{M}_{A_2} / \mathcal{W}_{A_2}.$

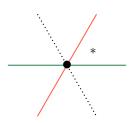
 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):

Coxeter ~1934, Tits ~1961. This works in ridiculous generality.

(Up to some minor technicalities in the infinite case.)

 $\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$

 $\mathcal{W}_{A_2} = \langle s, t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):

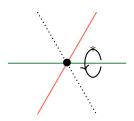


 $\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$

Complexifying the action: $\mathbb{R}^2 \leadsto \mathbb{C}^2$, $M_{A_2} \leadsto M_{A_2}^{\mathbb{C}}$, $N_{A_2} \leadsto N_{A_2}^{\mathbb{C}}$. Then:

$$\pi_1(\mathbb{N}_{\Lambda_s}^{\mathbb{C}}) \cong \mathcal{A}r_{\Lambda_s} = \langle \mathcal{B}_s, \mathcal{B}_t \mid \mathcal{B}_s \mathcal{B}_t \mathcal{B}_s = \mathcal{B}_t \mathcal{B}_s \mathcal{B}_t \rangle$$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):

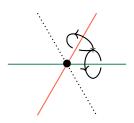


$$\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$$

Complexifying the action: $\mathbb{R}^2 \leadsto \mathbb{C}^2$, $M_{A_2} \leadsto M_{A_2}^{\mathbb{C}}$, $N_{A_2} \leadsto N_{A_2}^{\mathbb{C}}$. Then:

$$\pi_1(\mathbb{N}_{\Lambda_s}^{\mathbb{C}}) \cong \mathcal{A}r_{\Lambda_s} = \langle b_s, b_t \mid b_s b_t b_s = b_t b_s b_t \rangle$$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):

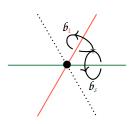


 $\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$

Complexifying the action: $\mathbb{R}^2 \leadsto \mathbb{C}^2$, $M_{A_2} \leadsto M_{A_3}^{\mathbb{C}}$, $N_{A_2} \leadsto N_{A_3}^{\mathbb{C}}$. Then:

$$\pi_1(\mathbb{N}_{\Lambda_s}^{\mathbb{C}}) \cong \mathcal{A}r_{\Lambda_s} = \langle b_s, b_t \mid b_s b_t b_s = b_t b_s b_t \rangle$$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):



 $\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$

Complexifying the action: $\mathbb{R}^2 \leadsto \mathbb{C}^2$, $M_{A_2} \leadsto M_{A_2}^{\mathbb{C}}$, $N_{A_2} \leadsto N_{A_2}^{\mathbb{C}}$. Then:

$$\pi_1(\mathbf{N}_{\mathbf{A}_2}^{\mathbb{C}}) \cong \mathcal{A}r_{\mathbf{A}_2} = \langle \mathbf{b}_{s}, \mathbf{b}_{t} \mid \mathbf{b}_{s} \mathbf{b}_{t} \mathbf{b}_{s} = \mathbf{b}_{t} \mathbf{b}_{s} \mathbf{b}_{t} \rangle$$

 $\mathcal{W}_{A_2}=\langle s,t \rangle$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection):

Brieskorn ~1971, van der Lek ~1983. This works in ridiculous generality.

(Up to some minor technicalities in the infinite case.)

$$\mathcal{W}_{A_2} \text{ acts freely on } \mathtt{M}_{A_2} = \mathbb{R}^2 \setminus \mathsf{hyperplanes}. \text{ Set } \mathtt{N}_{A_2} = \mathtt{M}_{A_2}/\mathcal{W}_{A_2}.$$

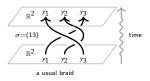
Complexifying the action: $\mathbb{R}^2 \leadsto \mathbb{C}^2$, $M_{A_2} \leadsto M_{A_3}^{\mathbb{C}}$, $N_{A_2} \leadsto N_{A_3}^{\mathbb{C}}$. Then:

$$\pi_1(\mathbf{N}_{\mathbf{A}_2}^{\mathbb{C}}) \cong \mathcal{A}r_{\mathbf{A}_2} = \langle \mathbf{b}_{s}, \mathbf{b}_{t} \mid \mathbf{b}_{s} \mathbf{b}_{t} \mathbf{b}_{s} = \mathbf{b}_{t} \mathbf{b}_{s} \mathbf{b}_{t} \rangle$$

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{A}$ via configuration spaces.

Example. Take $Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

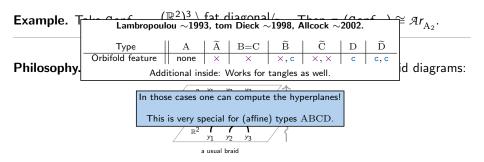
Philosophy. Having a configuration spaces is the same as having braid diagrams:



Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

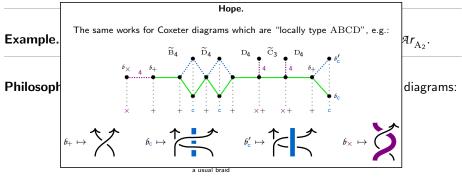
Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{A}$ via configuration spaces.



Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

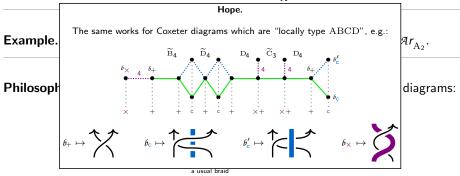
Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{A}$ via configuration spaces.



But we can't compute the hyperplanes...

Crucial. Note that – by explicitly calculating the ▶ equations defining the hyperplanes – one can directly check that:

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{\mathrm{A}}$ via configuration spaces.



In words: The $\mathbb{Z}/_{2\mathbb{Z}}$ -orbifolds provide the Crucial. framework to study Artin braid groups of classical (affine) type - one can directly c and their "glued-generalizations".

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{\mathrm{A}}$ via configuration spaces.

Example. Take $Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

Philosophy. Having a configuration spaces is the same as having braid diagrams:



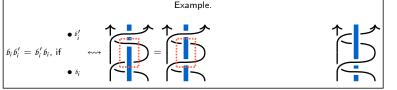
Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{\mathrm{A}}$ via configuration spaces.

Example. Take $Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

Philosophy. Having a configuration spaces is the same as having braid diagrams:



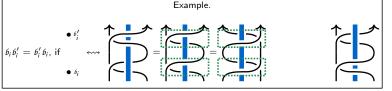
Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{A}$ via configuration spaces.

Example. Take
$$Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$$
. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

Philosophy. Having a configuration spaces is the same as having braid diagrams:

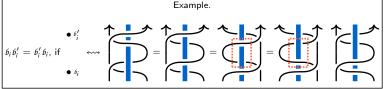


Crucial. Note that – by explicitly calculating the ◆ equations defining the hyperplanes – one can directly check that:

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{\mathrm{A}}$ via configuration spaces.

Example. Take $Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

Philosophy. Having a configuration spaces is the same as having braid diagrams:



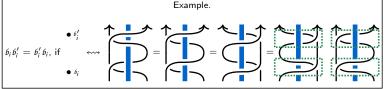
Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{A}$ via configuration spaces.

Example. Take
$$Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$$
. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

Philosophy. Having a configuration spaces is the same as having braid diagrams:



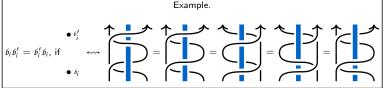
Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

Artin \sim **1925.** There is a topological model of $\mathcal{A}r_{A}$ via configuration spaces.

Example. Take
$$Conf_{A_2} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/}_{\mathfrak{S}_3}$$
. Then $\pi_1(Conf_{A_2}) \cong \mathcal{A}r_{A_2}$.

Philosophy. Having a configuration spaces is the same as having braid diagrams:



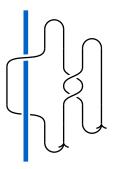
Crucial. Note that – by explicitly calculating the

• equations defining the hyperplanes – one can directly check that:

Reshetikhin–Turaev $\sim\!1991.$ Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an}\to \mathsf{well}\text{-behaved target category}.$

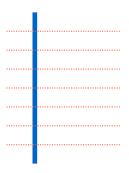
Today: Target categories = $\Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev $\sim\!1991.$ Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{RT}\colon \mathtt{u}\mathcal{T}\textit{an} \to \mathsf{well}\textrm{-behaved target category}.$

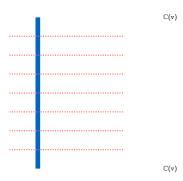
Today: Target categories $= \Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev ~1991. Construct link and tangle invariants as functors

 $u\mathcal{RT}$: $u\mathcal{T}an \rightarrow well$ -behaved target category.

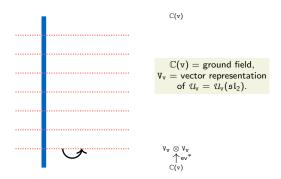
Today: Target categories = $\Re ep(\mathcal{U}_{v}(\mathfrak{sl}_{2}))$ and friends.



Reshetikhin–Turaev \sim **1991.** Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an}\to \mathsf{well}\text{-behaved target category}.$

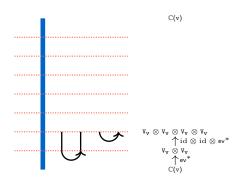
Today: Target categories $= \Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev \sim **1991.** Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an} \to \mathsf{well}\textrm{-behaved target category}.$

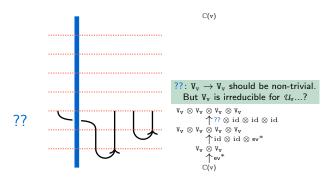
Today: Target categories $= \Re ep(\mathcal{U}_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev $\sim\!1991$. Construct link and tangle invariants as functors

 $u\mathcal{RT}\colon u\mathcal{T}\textit{an} \to \text{well-behaved target category}.$

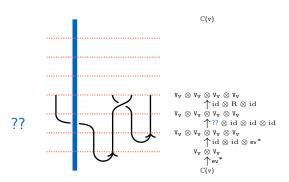
Today: Target categories = $\Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev $\sim\!1991$. Construct link and tangle invariants as functors

 $u\mathcal{RT}\colon u\mathcal{T}\textit{an} \to \text{well-behaved target category}.$

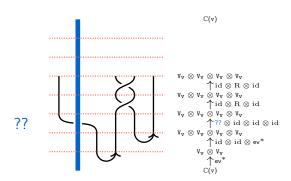
Today: Target categories = $\Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev \sim 1991. Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an}\to \mathsf{well}\text{-behaved target category}.$

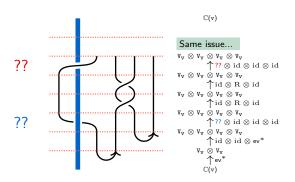
Today: Target categories $= \Re ep(\mathcal{U}_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev $\sim\!1991.$ Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an}\to \mathsf{well}\text{-behaved target category}.$

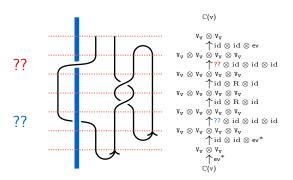
Today: Target categories = $\Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev $\sim\!1991.$ Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an}\to \mathsf{well}\text{-behaved target category}.$

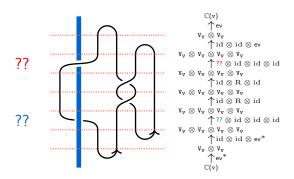
Today: Target categories = $\Re ep(U_v(\mathfrak{sl}_2))$ and friends.



Reshetikhin–Turaev $\sim\!1991.$ Construct link and tangle invariants as functors

 $\mathtt{u}\mathcal{R}\mathcal{T}\colon \mathtt{u}\mathcal{T}\textit{an}\to \mathsf{well}\textrm{-behaved target category}.$

Today: Target categories $= \Re ep(\mathcal{U}_v(\mathfrak{sl}_2))$ and friends.



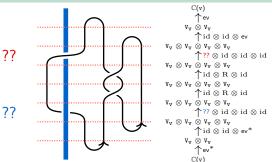
Reshetikhin–Turaev ~1991. Construct link and tangle invariants as functors

 $u\mathcal{RT}: u\mathcal{T}an \rightarrow well-behaved target category.$

Today: Target categories = $\Re ep(\mathcal{U}_{v}(\mathfrak{sl}_{2}))$ and friends.

Question. What could the $\mathbb{Z}_{2\mathbb{Z}}$ -analog be?

Orbifold-philosophy. We need something half-way in between $\mathbb{C}(v)$ and \mathcal{U}_v .



Half-way in between trivial \subset ?? $\subset \mathcal{U}_{v}$ – part I

Kulish–Reshetikhin \sim **1981.** \mathcal{U}_{v} is the associative, unital $\mathbb{C}(v)$ -algebra generated by E, F, $K^{\pm 1}$ subject to the usual relations.

Not really important...

$$V_{-} \stackrel{\mathsf{K} \leadsto \mathsf{v}^{-1}}{\overset{\mathsf{K} \leadsto \mathsf{v}}{\biguplus}} V_{+}$$

Define \mathcal{U}_{v} -intertwiners:

$$\begin{split} & \overset{\smile}{\cdot} : \mathbb{C}(\mathtt{v}) \to \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}}, \quad 1 \mapsto \mathtt{v}_{-} \otimes \mathtt{v}_{+} - \mathtt{v}^{-1} \mathtt{v}_{+} \otimes \mathtt{v}_{-}, \\ & \overset{\smile}{\wedge} : \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}} \to \mathbb{C}(\mathtt{v}), \quad \begin{cases} \mathtt{v}_{+} \otimes \mathtt{v}_{+} \mapsto \mathtt{0}, & \mathtt{v}_{+} \otimes \mathtt{v}_{-} \mapsto \mathtt{1}, \\ \mathtt{v}_{-} \otimes \mathtt{v}_{+} \mapsto -\mathtt{v}, & \mathtt{v}_{-} \otimes \mathtt{v}_{-} \mapsto \mathtt{0}, \end{cases} \\ & \overset{\smile}{\times} : \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}} \to \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}}, \quad \overset{\smile}{\times} = \mathtt{v} \, | \, \, | + \mathtt{v}^{2} \, \overset{\smile}{\sim}. \end{split}$$

Half-way in between trivial \subset ?? $\subset \mathcal{U}_{v}$ – part I

Kulish–Reshetikhin \sim **1981.** \mathcal{U}_v is the associative, unital $\mathbb{C}(v)$ -algebra generated by $E, F, K^{\pm 1}$ subject to the usual relations.

$$\begin{array}{lll} \mathtt{V}_{\mathtt{v}}\colon & \mathtt{E} \nu_{+} = 0, & \mathtt{F} \nu_{+} = \nu_{-}, & \mathtt{K} \nu_{+} = \mathtt{v} \nu_{+}, \\ \mathtt{E} \nu_{-} = \nu_{+}, & \mathtt{F} \nu_{-} = 0, & \mathtt{K} \nu_{-} = \mathtt{v}^{-1} \nu_{-}. & & & & & \\ \end{array}$$

Fact. \mathcal{U}_v is a Hopf algebra \Rightarrow We can tensor representations.

Define U_v -intertwiners:

$$\begin{split} & \overset{\smile}{\cdot} : \mathbb{C}(\mathtt{v}) \to \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}}, \quad 1 \mapsto \mathsf{v}_{-} \otimes \mathsf{v}_{+} - \mathtt{v}^{-1} \mathsf{v}_{+} \otimes \mathsf{v}_{-}, \\ & \overset{\smile}{\wedge} : \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}} \to \mathbb{C}(\mathtt{v}), \quad \begin{cases} \mathsf{v}_{+} \otimes \mathsf{v}_{+} \mapsto 0, & \mathsf{v}_{+} \otimes \mathsf{v}_{-} \mapsto 1, \\ \mathsf{v}_{-} \otimes \mathsf{v}_{+} \mapsto -\mathtt{v}, & \mathsf{v}_{-} \otimes \mathsf{v}_{-} \mapsto 0, \end{cases} \\ & \underset{\smile}{\times} : \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}} \to \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}}, \quad \underset{\smile}{\times} = \mathtt{v} \, | \, \, | + \mathtt{v}^{2} \, \underset{\smile}{\sim} . \end{split}$$

Half-way in between trivial \subset ?? $\subset \mathcal{U}_{v}$ – part I

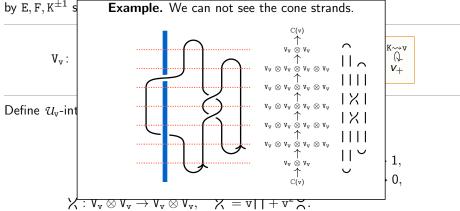
Kulish–Reshetikhin \sim **1981.** \mathcal{U}_{v} is the associative, unital $\mathbb{C}(v)$ -algebra generated by E, F, $K^{\pm 1}$ subject to the usual relations.

$$\begin{array}{c|c}
K \rightarrow v^{-1} & K \rightarrow v \\
\downarrow \downarrow & \downarrow \downarrow \downarrow \\
V_{-} & \stackrel{F}{\rightleftharpoons} & V_{+}
\end{array}$$

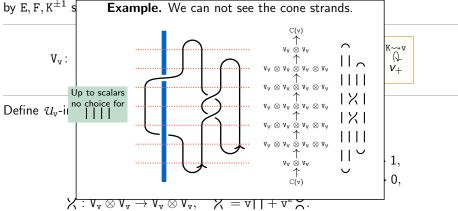
Define
$$v_{v}$$
 into v_{v} in v_{v} in

Half-way in between trivial \subset ?? $\subset U_v$ – part I

Kulish–Reshetikhin $\sim\!1981$. \mathcal{U}_v is the associative, unital $\mathbb{C}(v)$ -algebra generated



Kulish–Reshetikhin $\sim\!1981$. \mathcal{U}_v is the associative, unital $\mathbb{C}(v)$ -algebra generated



Let $c\mathcal{U}_v$ be the **Coolean** subalgebra of \mathcal{U}_v generated by $B = v^{-1}EK^{-1} + F$.

$$V_v$$
: $Bv_+ = v_-$, $Bv_- = v_+$. $v_- \stackrel{\searrow}{\longleftarrow} v_+$

$$v_- \stackrel{\stackrel{\mathsf{B}}{\longleftrightarrow}}{\longleftrightarrow} v_+$$

Define $\mathcal{C}\mathcal{U}_{v}$ -intertwiners:

$$\begin{array}{c} \mbox{$\dagger:$} \ \mbox{V_v} \rightarrow \mbox{V_v}, \quad \mbox{$v_+ \mapsto v_-$}, \ \mbox{$v_- \mapsto v_+$}, \\ \mbox{$\Psi:$} \ \mathbb{C}(\mbox{v}) \rightarrow \mbox{V_v} \otimes \mbox{V_v}, \quad \mbox{$1 \mapsto v_+ \otimes v_+ - v^{-1}v_- \otimes v_-$}, \\ \mbox{$A:$} \ \mbox{$V_v$} \otimes \mbox{$V_v$} \rightarrow \mathbb{C}(\mbox{v}), \quad \begin{cases} \mbox{$v_+ \otimes v_+ \mapsto -v$}, & \mbox{$v_+ \otimes v_- \mapsto 0$}, \\ \mbox{$v_- \otimes v_+ \mapsto 0$}, & \mbox{$v_- \otimes v_- \mapsto 1$}, \end{cases}$$

$$\mbox{\swarrow} = \mbox{\dagger} = \mbox{\swarrow} \quad \mbox{and} \quad \mbox{\swarrow} = \mbox{\downarrow} = \mbox{\swarrow}.$$

Aside. This drops out of a **Cooldeal Version** of Schur–Weyl duality.

Let $c\mathcal{U}_v$ be the coided subalgebra of \mathcal{U}_v generated by $B = v^{-1}EK^{-1} + F$.

$$V_v$$
: $Bv_+ = v_-$, $Bv_- = v_+$. $v_- \stackrel{\langle B \rangle}{\longleftarrow} v_+$

$$v_- \stackrel{\stackrel{\leftarrow}{\longleftarrow}}{\longrightarrow} v_+$$

Define $c \mathcal{U}_v$ -interty **Observation**. These are not \mathcal{U}_v -equivariant, but \circ and \circ are $\circ \mathcal{U}_{v}$ -equivariant.

$$\begin{split} & \Psi: \mathbb{C}(\mathtt{v}) \to \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}}, \quad 1 \mapsto \mathsf{v}_{+} \otimes \mathsf{v}_{+} - \mathtt{v}^{-1} \mathsf{v}_{-} \otimes \mathsf{v}_{-}, \\ & \\ & A: \mathtt{V}_{\mathtt{v}} \otimes \mathtt{V}_{\mathtt{v}} \to \mathbb{C}(\mathtt{v}), \quad \begin{cases} \mathsf{v}_{+} \otimes \mathsf{v}_{+} \mapsto -\mathtt{v}, & \mathsf{v}_{+} \otimes \mathsf{v}_{-} \mapsto 0, \\ \mathsf{v}_{-} \otimes \mathsf{v}_{+} \mapsto 0, & \mathsf{v}_{-} \otimes \mathsf{v}_{-} \mapsto 1, \end{cases} \end{split}$$

Aside. This drops out of a <u>Coideal version</u> of Schur–Wevl duality.

Let $c\mathcal{U}_v$ be the coided subalgebra of \mathcal{U}_v generated by $B = v^{-1}EK^{-1} + F$.

$$V_v$$
: $Bv_+ = v_-$, $Bv_- = v_+$. $v_- \stackrel{B}{\longleftrightarrow} v_+$

$$v_- \stackrel{\stackrel{\leftarrow}{\longleftarrow}}{\longrightarrow} v_+$$

Define coefficients (
$$\bullet$$
 \circ \circ) (1) = \bullet ($v_- \otimes v_+$) - v^{-1} \bullet ($v_+ \otimes v_-$) = 0

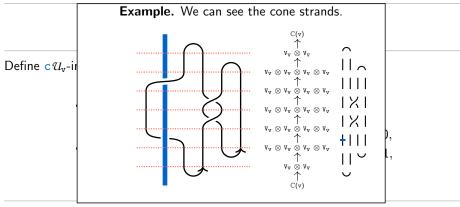
$$\begin{array}{c} \bullet \circ \bullet = | \text{ but } \bullet \neq |. \\ \bullet : \mathbb{C}(\mathbb{V}) \to \mathbb{V}_{\mathbb{V}} \otimes \mathbb{V}_{\mathbb{V}}, \quad 1 \mapsto v_+ \otimes v_+ - \mathbb{V} \quad v_- \otimes v_-, \\ \bullet : \mathbb{V}_{\mathbb{V}} \otimes \mathbb{V}_{\mathbb{V}} \to \mathbb{C}(\mathbb{V}), \quad \begin{cases} v_+ \otimes v_+ \mapsto -\mathbb{V}, & v_+ \otimes v_- \mapsto 0, \\ v_- \otimes v_+ \mapsto 0, & v_- \otimes v_- \mapsto 1, \end{cases}$$

$$\begin{array}{c} \bullet : \mathbb{V}_{\mathbb{V}} \otimes \mathbb{V}_{\mathbb{V}} \to \mathbb{C}(\mathbb{V}), \quad \begin{cases} v_+ \otimes v_+ \mapsto -\mathbb{V}, & v_+ \otimes v_- \mapsto 0, \\ v_- \otimes v_+ \mapsto 0, & v_- \otimes v_- \mapsto 1, \end{cases}$$

$$\begin{array}{c} \bullet : \mathbb{V}_{\mathbb{V}} \otimes \mathbb{V}_{\mathbb{V}} \to \mathbb{C}(\mathbb{V}), \quad \begin{cases} v_+ \otimes v_+ \mapsto -\mathbb{V}, & v_+ \otimes v_- \mapsto 0, \\ v_- \otimes v_+ \mapsto 0, & v_- \otimes v_- \mapsto 1, \end{cases}$$

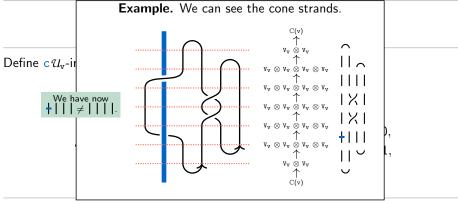
Aside. This drops out of a <u>Coideal version</u> of Schur–Wevl duality.

Let $c\,\mathcal{U}_v$ be the ${\color{red}}^{\hspace{-0.5cm}}$ subalgebra of \mathcal{U}_v generated by $B=v^{-1}EK^{-1}+F.$



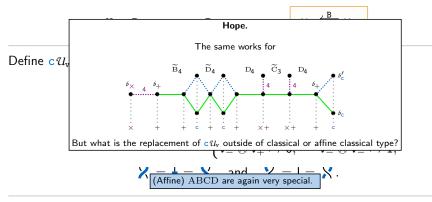
Aside. This drops out of a **Cooldeal Version** of Schur-Weyl duality.

Let $c\,\mathcal{U}_v$ be the $\ref{eq:coideal}$ subalgebra of \mathcal{U}_v generated by $B=v^{-1}EK^{-1}+F.$



Aside. This drops out of a **Coideal Version** of Schur-Weyl duality.

Let $c\mathcal{U}_v$ be the \bigcirc subalgebra of \mathcal{U}_v generated by $B=v^{-1}EK^{-1}+F$.



Aside. This drops out of a **Cooldeal Version** of Schur-Weyl duality.

Back to diagrams

Let $m\mathcal{A}rc$ be the monoidal category defined as follows.

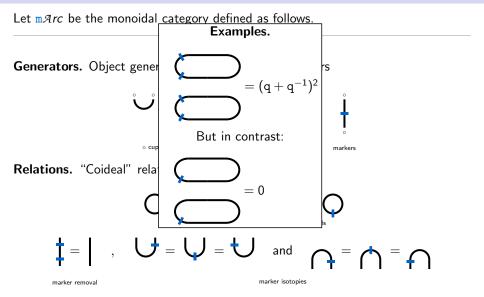
Generators. Object generator $\{o\}$, morphism generators



Relations. "Coideal" relations:

marker removal marker isotopies

Back to diagrams



We define a monoidal functor $\langle - \rangle_c : cTan \to mArc$ as follows. On objects,

$$\langle + \rangle_{c} = 0$$
 , $\langle - \rangle_{c} = 0$, $\langle c \rangle_{c} = \emptyset$

and on morphisms by

 $\left\langle \begin{array}{c} \\ \\ \\ \end{array} \right\rangle = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle$

We define a monoidal functor $\langle - \rangle_c : cTan \to mArc$ as follows. On objects,

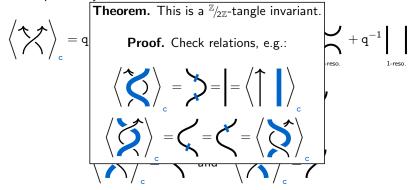
$$\langle + \rangle_{c} = 0$$
 , $\langle - \rangle_{c} = 0$, $\langle c \rangle_{c} = \emptyset$

and on morphisms by

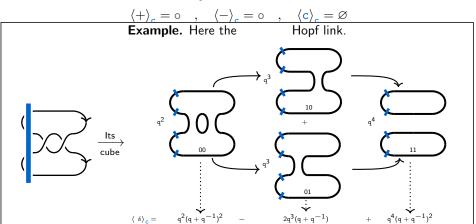
We define a monoidal functor $\langle - \rangle_c : cTan \to mArc$ as follows. On objects,

$$\langle + \rangle_{c} = 0$$
 , $\langle - \rangle_{c} = 0$, $\langle c \rangle_{c} = \emptyset$

and on morphisms by

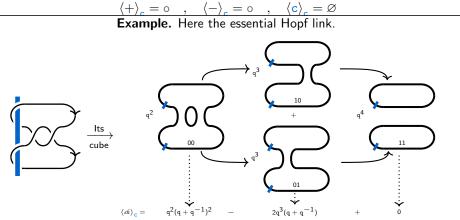


We define a monoidal functor $\langle - \rangle_{\tt c}:{\tt c}{\it Tan} \to {\tt m}{\it Arc}$ as follows. On objects,



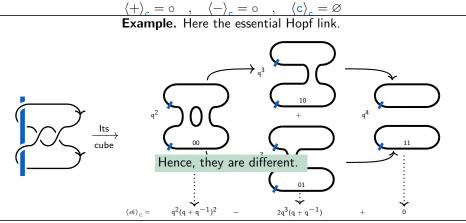
We define a monoidal functor $\langle - \rangle_{\tt c}:{\tt c}{\it Tan} \to {\tt m}{\it Arc}$ as follows. On objects,

$$\langle + \rangle_{c} = 0$$
 , $\langle - \rangle_{c} = 0$, $\langle c \rangle_{c} = \emptyset$

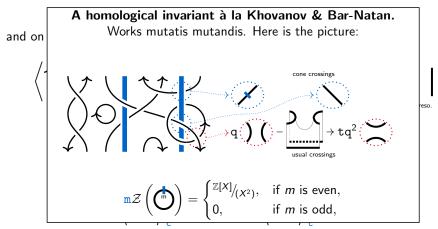


We define a monoidal functor $\langle - \rangle_c : cTan \to m\mathcal{A}rc$ as follows. On objects,

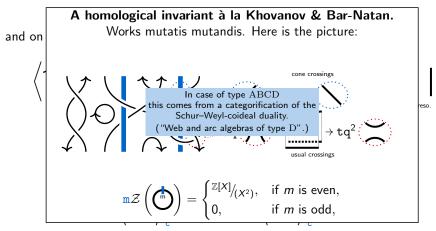
$$\langle + \rangle_{c} = 0$$
 , $\langle - \rangle_{c} = 0$, $\langle c \rangle_{c} = \emptyset$



We define a monoidal functor $\langle - \rangle_{\tt c} : {\tt c} \mathcal{T} {\tt an} \to {\tt m} \mathcal{A} {\tt rc}$ as follows. On objects,



We define a monoidal functor $\langle - \rangle_c : cTan \to m\mathcal{A}rc$ as follows. On objects,



We define a monoidal functor $\langle - \rangle_c : cTan \to mArc$ as follows. On objects,

$$\langle + \rangle_{c} = 0$$
 , $\langle - \rangle_{c} = 0$, $\langle c \rangle_{c} = \emptyset$

and on morphisms by



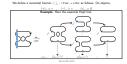


Artin ~1925. There is a topological model of 3r, via configuration spaces.

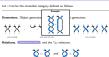
Example. Take $\mathrm{Conf}_{A_0} = (\mathbb{R}^2)^3 \setminus \mathrm{fat} \ \mathrm{diagonal/g}_3$. Then $\pi_2(\mathrm{Conf}_{A_0}) \cong \mathcal{R}_{f_{A_0}}$.



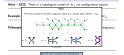
A polynomial invariant à la Jones & Kauffman



Tangle diagrams with cone strands



Configuration spaces



directly check that:

"Hyperplane picture equals configuration space picture."

A version of Schur's remarkable duality.



Ehrig-Stroppel, Bao-Wang ~2013. The actions of cU_r(pt₁) and S_r(D)×²/₂₂ on V²/₂ commute and generate each other's centralizer.

I follow hyperplanes

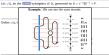
 $W_{\Lambda_2} = \langle \iota, \iota \rangle \text{ acts faithfully on } \mathbb{R}^2 \text{ by reflecting in hyperplanes (for each reflection):}$



 W_h acts freely on $\mathbb{N}_h := \mathbb{R}^2 \setminus \text{hyperplanes. Set } \mathbb{N}_h := \mathbb{N}_h \ / W_h$.

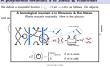
Complexifying the action: $\mathbb{R}^2 \to \mathbb{C}^2$, $\mathbb{H}_{A_\delta} \to \mathbb{H}_{A_\delta}^c$, $\mathbb{H}_{A_\delta} \to \mathbb{H}_{A_\delta}^c$. Then: $m(\mathbb{H}_{A_\delta}^C) \cong \Re_{A_\delta} = \langle \delta, \delta \mid \delta \delta \delta = \delta \delta \delta \rangle$

Half-way in between trivial $\subset \ref{eq:constraints} \subset u_r$ – part II



Aside. This drops out of a of Schur-Weyl duality.

A polynomial invariant à la Jones & Kauffman



his involves and Top and the

There is still much to do...

State Schoolses to the involves and "_{Just} addition





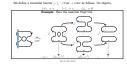
Artin ~1925. There is a topological model of Ar., via configuration spaces.

Example. Take $Conf_{A_n} = (\mathbb{R}^2)^3 \setminus \text{fat diagonal/g}_3$. Then $\pi_1(Conf_{A_n}) \cong \operatorname{Rr}_{A_n}$



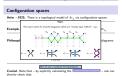
Crucial. Note that - by explicitly calculating the 'Hyperplane picture equals configuration space picture.'

A polynomial invariant à la Jones & Kauffman



State Schoolses to the involves and "_{Just} addition

Tangle diagrams with cone strands Let cTan be the monoidal category defined as follows 8-8 = 8-8



'Hyperplane picture equals configuration space picture.'

A version of Schur's remarkable duality.



Ehrle-Stroopel, Bao-Wane ~2013. The actions of ctL(et.) and sL(D)x2/on V^[14] commute and generate each other's centralizer.

I follow hyperplanes

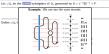
 $W_{-} = (\epsilon, \epsilon)$ acts faithfully on \mathbb{R}^2 by reflecting in hyperplanes (for each reflection)



 W_h acts freely on $H_h := \mathbb{R}^2 \setminus \text{hyperplanes}$. Set $H_h := H_h / W_h$.

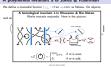
Complexifying the action: $\mathbb{R}^2 \to \mathbb{C}^2, \, H_+ \to H_+^C$, $H_- \to H_+^C$. Then: $\pi_1(\mathbb{R}_{+}^{\mathbb{C}}) \cong \mathcal{R}r_{k_1} = \langle \delta, \delta, | \delta, \delta, \delta = \delta, \delta, \delta \rangle$

Half-way in between trivial \subset ?? $\subset u_r$ - part II



Aside. This drops out of a good of Schur-Weyl duality.

A polynomial invariant à la Jones & Kauffman



his involves and Top and the

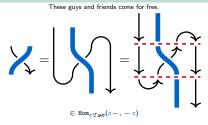
Thanks for your attention!

These guys and friends come for free.

$$= \bigcup_{\substack{\leftarrow \text{Hom}_{c,Tan}(c-, -c)}} \bigoplus_{\substack{\leftarrow \text{Hom}_{c,Ta$$

■ Back

I see them as diagrams – no topological interpretation intended at the moment.



◀ Back

Satake \sim 1956 ("V-manifold"), Thurston \sim 1978, Haefliger \sim 1990 ("orbihedron"), etc. A triple $0rb = (X_{0rb}, \cup_i U_i, G_i)$ of a Hausdorff space X_{0rb} , a covering $\cup_i U_i$ of it (closed under finite intersections) and a collection of finite groups G_i is called an orbifold (of dimension m) if for each U_i there exists a open subset $V_i \subset \mathbb{R}^m$ carrying an action of G_i , and some compatibility conditions.

Fact. A two-dimensional ("smooth") orbifold is locally modeled on:

- ightharpoonup Reflector corners ightharpoonup reflection action of the dihedral group.
- ightharpoonup Mirror points ightharpoonup reflection action of $\mathbb{Z}/_{2\mathbb{Z}}$.



Satake \sim 1956 ("V-manifold"), Thurston \sim 1978, Haefliger \sim 1990 ("or Not super important. Only one thing to stress: ,, a cove Topologically an orbifold is sometimes the same as its underlying space. grou So all notions concerning orbifolds have to take this into account. pen subset $V_i \subset \mathbb{R}^m$ carrying an action of G_i , and some compatibility conditions.

Fact. A two-dimensional ("smooth") orbifold is locally modeled on:

- \triangleright Reflector corners \leftrightsquigarrow reflection action of the dihedral group.
- ightharpoonup Mirror points ightharpoonup reflection action of $\mathbb{Z}/_{2\mathbb{Z}}$.



Satake ~1956 ("V-manifold"), Thurston ~1978, Haefliger ~1990
("or Not super important. Only one thing to stress: ,, a cove Topologically an orbifold is sometimes the same as its underlying space. grou So all notions concerning orbifolds have to take this into account. pen

Quote by Thurston about the name orbifold:

"This terminology should not be blamed on me. It was obtained by a democratic process in my course of 1976-77. An orbifold is something with many folds; unfortunately, the word 'manifold' already has a different definition. I tried 'foldamani', which was quickly displaced by the suggestion of 'manifolded'. After two months of patiently saying 'no, not a manifold, a manifoldead,' we held a vote, and 'orbifold' won."

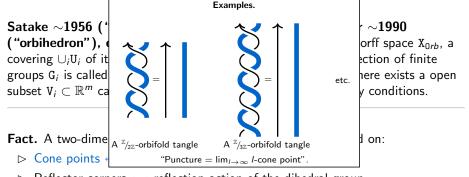
◆ Back

Satake \sim 1956 ("V-manifold"), Thurston \sim 1978, Haefliger \sim 1990 ("orbihedron"), etc. A triple $0rb = (X_{0rb}, \cup_i U_i, G_i)$ of a Hausdorff space X_{0rb} , a covering $\cup_i U_i$ of it (closed under finite intersections) and a collection of finite groups G_i is called an orbifold (of dimension m) if for each U_i there exists a open subset $V_i \subset \mathbb{R}^m$ carrying an action of G_i , and some compatibility conditions.

Fact. A two-dimensional ("smooth") orbifold is locally modeled on:

- ightharpoonup Reflector corners ightharpoonup reflection action of the dihedral group.
- ightharpoonup Mirror points ightharpoonup reflection action of $\mathbb{Z}/_{2\mathbb{Z}}$.





- ightharpoonup Reflector corners ightharpoonup reflection action of the dihedral group.
- \triangleright Mirror points $\leftrightarrow \rightarrow$ reflection action of $\mathbb{Z}/_{2\mathbb{Z}}$.

◆ Back

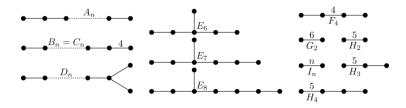


Figure: The Coxeter graphs of finite type.

Example. The type \boldsymbol{A} family is given by the symmetric groups using the simple transpositions as generators.

(Picture from https://en.wikipedia.org/wiki/Coxeter_group.)



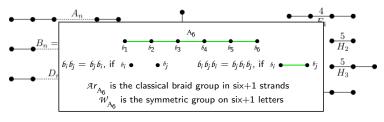
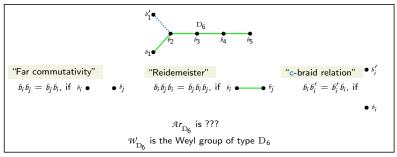


Figure: The Coxeter graphs of finite type.

Example. The type \boldsymbol{A} family is given by the symmetric groups using the simple transpositions as generators.

(Picture from https://en.wikipedia.org/wiki/Coxeter_group.)

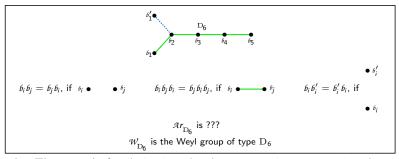




Example. The type A family is given by the symmetric groups using the simple transpositions as generators.

(Picture from https://en.wikipedia.org/wiki/Coxeter_group.)

◆ Back



Example. The type A family is given by the symmetric groups using the simple transpositions at want to answer $\ref{eq:simple}$ in this case, and partially in general.

(Picture from https://en.wikipedia.org/wiki/Coxeter_group.)



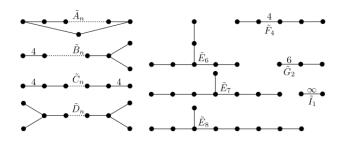


Figure: The Coxeter graphs of affine type.

Example. The type \widetilde{A}_n corresponds to the affine Weyl group for \mathfrak{sl}_n .

(Picture from https://en.wikipedia.org/wiki/Coxeter_group.)



	A_2	
•		•
α_1		α_2

positive root	$\alpha_1 = (1, -1, 0)$	$\alpha_2 = (0, 1, -1)$	$\alpha_1 + \alpha_2 = (1, 0, -1)$
reflection action	$x_1 \leftrightarrow x_2$	$x_2 \leftrightarrow x_3$	$x_1 \leftrightarrow x_3$
⊥-hyperplane	$\{(x,x,0)\}$	$\{(0,y,y)\}$	$\{(z,0,z)\}$

Hyperplane equations: $\{(x,y,z)\in (\mathbb{R}^2)^3\mid x=y \text{ or } y=z \text{ or } x=z\}$ This is gf-notation.

$$\underbrace{ \overset{A_2}{\alpha_1} \overset{A_2}{\alpha_2} }$$

positive root	$\alpha_1 = (1, -1, 0)$	$\alpha_2 = (0, 1, -1)$	$\alpha_1 + \alpha_2 = (1, 0, -1)$
reflection action	$x_1 \leftrightarrow x_2$	$x_2 \leftrightarrow x_3$	$x_1 \leftrightarrow x_3$
⊥-hyperplane	$\{(x,x,0)\}$	$\{(0,y,y)\}$	$\{(z,0,z)\}$

Hyperplane equations: $\{(x,y,z)\in (\mathbb{R}^2)^3\mid x=y \text{ or } y=z \text{ or } x=z\}$

Observe that this matches the diagonal of the configuration space picture.

$$\underbrace{\begin{smallmatrix} A_2 \\ \alpha_1 & \alpha_2 \end{smallmatrix}}_{A_2}$$

positive root	$\alpha_1 = (1, -1, 0)$	$\alpha_2 = (0, 1, -1)$	$\alpha_1 + \alpha_2 = (1, 0, -1)$
reflection action	$x_1 \leftrightarrow x_2$	$x_2 \leftrightarrow x_3$	$x_1 \leftrightarrow x_3$
⊥-hyperplane	$\{(x,x,0)\}$	$\{(0,y,y)\}$	$\{(z,0,z)\}$

Hyperplane equations: $\{(x, y, z) \in (\mathbb{R}^2)^3 \mid x = y \text{ or } y = z \text{ or } x = z\}$



positive root	$\alpha_1' = (1, 1, 0)$	$\alpha_1 = (1, -1, 0)$	more "type A-like"
reflection action	$x_1', x_1 \leftrightarrow -x_1', -x_1$	$x_1 \leftrightarrow x_2$	more "type A-like"
⊥-hyperplane	$\{(x, -x, 0, 0)\}$	$\{(x,x,0,0)\}$	more "type A-like"

Hyperplane equations: $\{(x, y, z, w) \in \mathbb{C}^4 \mid x = \pm y \text{ etc.}\}$

$$\begin{smallmatrix} A_2 \\ \bullet \\ \alpha_1 & \alpha_2 \end{smallmatrix}$$

positive root	$\alpha_1 = (1, -1, 0)$	$\alpha_2 = (0, 1, -1)$	$\alpha_1 + \alpha_2 = (1, 0, -1)$
reflection action	$x_1 \leftrightarrow x_2$	$x_2 \leftrightarrow x_3$	$x_1 \leftrightarrow x_3$
⊥-hyperplane	$\{(x,x,0)\}$	$\{(0,y,y)\}$	$\{(z,0,z)\}$

Hyperplane equations: $\{(x, y, z) \in (\mathbb{R}^2)^3 \mid x = y \text{ or } y = z \text{ or } x = z\}$

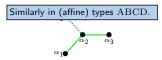
Observe that this matches the diameter of the configuration space picture up to a 2-fold covering $(x, y, z, w) \mapsto (x^2, y^2, z^2, w^2)$.

Hyperplane equations: $\{(x, y, z, w) \in \mathbb{C}^4 \mid x = \pm y \text{ etc.}\}$

$$\begin{smallmatrix} A_2 \\ \bullet \\ \alpha_1 & \alpha_2 \end{smallmatrix}$$

positive root	$ \alpha_1 = (1, -1, 0)$	$\alpha_2 = (0, 1, -1)$	$\alpha_1 + \alpha_2 = (1, 0, -1)$
reflection action	$x_1 \leftrightarrow x_2$	$x_2 \leftrightarrow x_3$	$x_1 \leftrightarrow x_3$
⊥-hyperplane	$\{(x,x,0)\}$	$\{(0,y,y)\}$	$\{(z,0,z)\}$

Hyperplane equations: $\{(x, y, z) \in (\mathbb{R}^2)^3 \mid x = y \text{ or } y = z \text{ or } x = z\}$



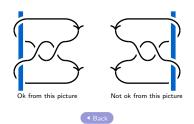
positive root	$\alpha_1'=(1,1,0)$	$\alpha_1 = (1, -1, 0)$	more "type A-like"
reflection action	$x_1', x_1 \leftrightarrow -x_1', -x_1$	$x_1 \leftrightarrow x_2$	more "type A-like"
hyperplane	$\{(x, -x, 0, 0)\}$	$\{(x, x, 0, 0)\}$	more "type A-like"

Hyperplane equations: $\{(x, y, z, w) \in \mathbb{C}^4 \mid x = \pm y \text{ etc.}\}$

 $c \mathcal{U}_v$ is not a Hopf algebra, but rather a right coideal (subalgebra) of \mathcal{U}_v :

$$\Delta(\mathtt{B}) = \mathtt{B} \otimes \underbrace{\mathtt{K}^{-1}}_{\not\in\mathtt{c}\, \mathcal{U}_{\mathtt{v}}} + 1 \otimes \mathtt{B} \in \mathtt{c}\, \mathcal{U}_{\mathtt{v}} \otimes \, \mathcal{U}_{\mathtt{v}},$$

which gives $\Re ep(c\mathcal{U}_v)$ the structure of a right $\Re ep(\mathcal{U}_v)$ -category \Rightarrow right handedness of diagrams, e.g.:



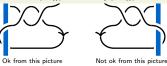
 $c\,\mathcal{U}_v$ is not a Hopf algebra, but rather a right coideal (subalgebra) of $\mathcal{U}_v\colon$

h

Example. The vector representations of \mathfrak{gl}_n , \mathfrak{so}_n and \mathfrak{sp}_n all agree, and indeed $\mathfrak{so}_n \hookrightarrow \mathfrak{gl}_n$ and $\mathfrak{sp}_n \hookrightarrow \mathfrak{gl}_n$.

But the quantum vector representations do not agree, i.e. $\mathcal{U}_{v}(\mathfrak{so}_{n}) \not\hookrightarrow \mathcal{U}_{v}(\mathfrak{gl}_{n})$ and $\mathcal{U}_{v}(\mathfrak{sp}_{n}) \not\hookrightarrow \mathcal{U}_{v}(\mathfrak{gl}_{n})$.

This is bad. Idea: Invent new quantizations such that $\mathcal{U}'_{\mathbf{v}}(\mathfrak{so}_n) \hookrightarrow \mathcal{U}_{\mathbf{v}}(\mathfrak{gl}_n)$ and $\mathcal{U}'_{\mathbf{v}}(\mathfrak{sp}_n) \hookrightarrow \mathcal{U}_{\mathbf{v}}(\mathfrak{gl}_n)$.



 $c\,\mathcal{U}_v$ is not a Hopf algebra, but rather a right coideal (subalgebra) of \mathcal{U}_v :

h

Example. The vector representations of \mathfrak{gl}_n , \mathfrak{so}_n and \mathfrak{sp}_n all agree, and indeed $\mathfrak{so}_n \hookrightarrow \mathfrak{gl}_n$ and $\mathfrak{sp}_n \hookrightarrow \mathfrak{gl}_n$.

But the quantum vector representations do not agree, i.e. $\mathcal{U}_{v}(\mathfrak{so}_{n}) \not\hookrightarrow \mathcal{U}_{v}(\mathfrak{gl}_{n})$ and $\mathcal{U}_{v}(\mathfrak{sp}_{n}) \not\hookrightarrow \mathcal{U}_{v}(\mathfrak{gl}_{n})$.

This is bad. Idea: Invent new quantizations such that $\mathcal{U}'_{v}(\mathfrak{so}_{n}) \hookrightarrow \mathcal{U}_{v}(\mathfrak{gl}_{n})$ and $\mathcal{U}'_{v}(\mathfrak{sp}_{n}) \hookrightarrow \mathcal{U}_{v}(\mathfrak{gl}_{n})$.



 $c \mathcal{U}_v$ is not a Hopf algebra, but rather a right coideal (subalgebra) of \mathcal{U}_v :

$$\Delta(\mathtt{B}) = \mathtt{B} \otimes \underbrace{\mathtt{K}^{-1}}_{\not\in\mathtt{c}\, \mathcal{U}_{\mathtt{v}}} + 1 \otimes \mathtt{B} \in \mathtt{c}\, \mathcal{U}_{\mathtt{v}} \otimes \mathcal{U}_{\mathtt{v}},$$

which gives This happens really often. In our case we have basically right

$$\mathfrak{gl}_1 \hookrightarrow \mathfrak{sl}_2, ig(tig) \mapsto egin{pmatrix} 0 & t \ t & 0 \end{pmatrix}$$

which does not quantize properly...

Observation. This happens repeatedly.



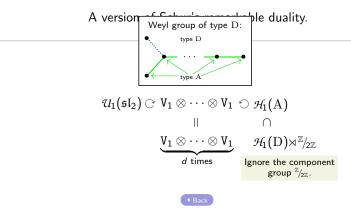
Not ok from this picture

Plain old
$$\mathfrak{sl}_2$$
: Acts by matrices. The symmetric group: Acts by permutation.
$$\mathcal{U}_1\big(\mathfrak{sl}_2\big) \circlearrowleft \underbrace{\mathbb{V}_1 \otimes \cdots \otimes \mathbb{V}_1}_{\textit{d times}} \circlearrowleft \mathcal{H}_1\big(A\big)$$

Schur \sim **1901.** The natural actions of $\mathcal{U}_1(\mathfrak{sl}_2)$ and $\mathcal{H}_1(A)$

on $V_1^{\otimes d} = (\mathbb{C}^2)^{\otimes d}$ commute and generate each other's centralizer.

◀ Back



$$\mathcal{U}_1(\mathfrak{sl}_2) \bigcirc V_1 \otimes \cdots \otimes V_1 \circlearrowleft \mathcal{H}_1(A)$$
 $\cup \qquad \qquad \qquad \cap$
?? $\bigcirc \underbrace{V_1 \otimes \cdots \otimes V_1}_{d \text{ times}} \circlearrowleft \mathcal{H}_1(D) \rtimes^{\mathbb{Z}}_{/2\mathbb{Z}}$

◆ Back

Regev \sim **1983.** The actions of $\mathcal{U}_1(\mathfrak{gl}_1)$ and $\mathcal{H}_1(D) \rtimes \mathbb{Z}/_{2\mathbb{Z}}$ on $V_1^{\otimes d}$ commute and generate each other's centralizer.

$$\mathcal{U}_{\mathtt{v}}(\mathfrak{sl}_2) \ominus \, \mathtt{V}_{\mathtt{v}} \otimes \cdots \otimes \mathtt{V}_{\mathtt{v}} \, \odot \, \mathcal{H}_{\mathtt{v}}(\mathrm{A})$$

Jimbo $\sim\!\!$ **1985.** The natural actions of $\mathcal{U}_v(\mathfrak{sl}_2)$ and $\mathcal{H}_v(A)$

on $V_{\mathtt{v}}^{\otimes d} = (\mathbb{C}(\mathtt{v})^2)^{\otimes d}$ commute and generate each other's centralizer.



$$\begin{array}{c} \mathcal{U}_v(\mathfrak{sl}_2) \bigcirc \ \mathbb{V}_v \otimes \cdots \otimes \mathbb{V}_v \ \bigcirc \ \mathcal{H}_v(A) \\ \\ \underbrace{\mathbb{V}_v \otimes \cdots \otimes \mathbb{V}_v}_{d \ \text{times}} \end{array}$$

$$\begin{array}{c} \mathcal{U}_v\big(\mathfrak{sl}_2\big) \bigcirc \ \mathbb{V}_v \otimes \cdots \otimes \mathbb{V}_v \ \bigcirc \ \mathcal{H}_v\big(A\big) \\ & \qquad \qquad || \qquad \qquad \cap \\ & \qquad \underbrace{\mathbb{V}_v \otimes \cdots \otimes \mathbb{V}_v}_{\textit{d times}} \ \bigcirc \ \mathcal{H}_v\big(D\big) \rtimes^{\mathbb{Z}}\!/_{\!\!2\mathbb{Z}} \\ & \qquad \qquad \mathbb{Q}_{\text{uantizes nicely.}} \end{array}$$

◆ Back

$$\begin{array}{c|c} \mathcal{U}_v(\mathfrak{sl}_2) \bigcirc V_v \otimes \cdots \otimes V_v \circlearrowleft \mathcal{H}_v(A) \\ \hline \text{Does not embed.} & \qquad \qquad || \qquad \qquad \cap \\ \mathcal{U}_v(\mathfrak{gl}_1) \bigcirc \underbrace{V_v \otimes \cdots \otimes V_v}_{\textit{d times}} \circlearrowleft \mathcal{H}_v(D) \rtimes^{\mathbb{Z}}\!/_{\!\!2\mathbb{Z}} \end{array}$$

$$\begin{array}{c|c} \mathcal{U}_v(\mathfrak{sl}_2) \circlearrowleft V_v \otimes \cdots \otimes V_v & \circlearrowleft \mathcal{H}_v(A) \\ & & & & & & & & \\ \mathcal{U}_v(\mathfrak{gl}_1) & & & V_v \otimes \cdots \otimes V_v & \circlearrowleft \mathcal{H}_v(D) \rtimes^{\mathbb{Z}} /_{2\mathbb{Z}} \\ \hline \text{No commuting action.} & d \text{ times} \\ & & & & & & \\ \end{array}$$

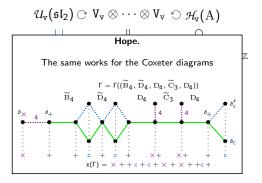
$$\begin{array}{c|c} \mathcal{U}_v\big(\mathfrak{sl}_2\big) \circlearrowleft \ V_v \otimes \cdots \otimes V_v \circlearrowleft \mathcal{H}_v\big(A\big) \\ \text{Is a} \\ \text{subalgebra.} & \quad \qquad \\ c \, \mathcal{U}_v\big(\mathfrak{gl}_1\big) \qquad \underbrace{V_v \otimes \cdots \otimes V_v}_{\textit{d times}} \circlearrowleft \mathcal{H}_v\big(D\big) \rtimes^\mathbb{Z}/\!\!_{\!\!2\mathbb{Z}} \end{array}$$

$$\begin{array}{c|c} \mathcal{U}_v(\mathfrak{sl}_2) \circlearrowleft V_v \otimes \cdots \otimes V_v & \circlearrowleft \mathcal{H}_v(A) \\ & \cup & & \cap \\ & \subset \mathcal{U}_v(\mathfrak{gl}_1) \circlearrowleft \underbrace{V_v \otimes \cdots \otimes V_v}_{d \text{ times}} & \circlearrowleft \mathcal{H}_v(D) \rtimes^\mathbb{Z}/_{\!\!2\mathbb{Z}} \\ & & \text{Act by} \\ & & \text{restriction.} \end{array}$$

◆ Back

 $\textbf{Ehrig-Stroppel, Bao-Wang} \ \sim \textbf{2013}. \ \ \text{The actions of } \ \mathtt{c} \ \mathcal{U}_{\mathtt{v}}(\mathfrak{gl}_1) \ \text{and} \ \ \mathcal{H}_{\mathtt{v}}(\mathrm{D}) \rtimes^{\mathbb{Z}} /_{\!\! 2\mathbb{Z}}$

on $V_{v}^{\otimes d}$ commute and generate each other's centralizer.



But, again, only in the special case of type ${\rm ABCD}$ this is known.

Message to take away. Coideal naturally appear in Schur-Weyl-like games.

And these pull the strings from the background for tangle and link invariants.